

# SOME NEW SEPARATION AXIOMS IN TOPOLOGICAL SPACES

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## Abstract:

A subset  $A$  of a space  $(X, \tau)$  is said to be  $sb\hat{g}$  closed if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $b\hat{g}$ -open in  $X$ . The complement of  $sb\hat{g}$  closed set is called  $sb\hat{g}$ -open set. A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $sb\hat{g}$ -continuous if  $f^{-1}(v)$  is  $sb\hat{g}$  closed in  $(X, \tau)$  for every closed set  $V$  in  $(Y, \sigma)$ . A function  $f: (X, \tau) \rightarrow (Y, \sigma)$  is said to be  $sb\hat{g}$ -irresolute if  $f^{-1}(V)$  is  $Sb\hat{g}$  closed in  $(X, \tau)$ . In this paper we introduce three new topological spaces namely  $sb\hat{g}$ - $T_0$ ,  $sb\hat{g}$ - $T_1$  and  $sb\hat{g}$ - $T_2$  spaces via  $sb\hat{g}$ -open sets. Also we characterize their properties.

## Keywords:

$sb\hat{g}$  closed set,  $sb\hat{g}$ -open set,  $sb\hat{g}$ - $T_0$  spaces,  $sb\hat{g}$ - $T_1$  spaces,  $sb\hat{g}$ - $T_2$  spaces,  $sb\hat{g}$ -kernel.

## 1.Inroduction:

Caldas and Jafari[7] introduced and studied  $b$ - $T_0$ ,  $b$ - $T_1$  and  $b$ - $T_2$  via  $b$ -open sets. K.Bala Deepa Arasi and S.Navaneetha Krishnan[2] introduced the concept of  $sb\hat{g}$ -closed set in Topological spaces. And they introduced and studied  $sb\hat{g}$ -continuous functions[3], contra  $sb\hat{g}$ -continuous functions [4],  $sb\hat{g}$ -quotientmap[5],  $sb\hat{g}$ -connected spaces and  $sb\hat{g}$ -compact spaces[6].

In this paper we introduce three new spaces namely,  $sb\hat{g}$ - $T_0$ ,  $sb\hat{g}$ - $T_1$  and  $sb\hat{g}$ - $T_2$  spaces via  $sb\hat{g}$ -open set. We investigate relation between these spaces with other existing spaces. Also we study some properties of these spaces.

## 2.Preliminaries:

Throughout this paper  $(X, \tau)$  &  $(Y, \sigma)$  respectively and on which no separation axioms are assumed unless otherwise explicitly stated. Let  $A$  be a subset of the space  $X$ . The interior and closure of a set  $A$  in  $X$  are denoted by  $int(A)$  and

$cl(A)$ . The complement of  $A$  is denoted by  $(X-A)$  or  $A^c$ .

**Definition 2.1:** A subset  $A$  of a topological space  $(X, \tau)$  is said to be an  $sb\hat{g}$ -closed set if  $scl(A) \subseteq U$  whenever  $A \subseteq U$  and  $U$  is  $b\hat{g}$ -open in  $X$ . The family of all  $sb\hat{g}$ -closed sets of  $X$  is denoted by  $sb\hat{g}$ - $C(X)$ . The complement of  $sb\hat{g}$ -closed set is called  $sb\hat{g}$ -open set. The family of all  $sb\hat{g}$ -open sets of  $X$  is denoted by  $sb\hat{g}$ - $O(X)$ .

**Definition 2.2:[7]** A topological space  $(X, \tau)$  is said to be

i)  $b$ - $T_0$  if for each pair of distinct points in  $X$ , there is a  $b$ -open set containing one of the points but not the other.

ii)  $b$ - $T_1$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist  $b$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively such that  $y \notin U$  and  $x \notin V$ .

iii)  $b$ - $T_2$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist disjoint  $b$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively.

**Definition 2.3:[8]** A topological space  $(X, \tau)$  is said to be

i)  $\alpha$ - $T_0$  if for each pair of distinct points in  $X$ , there exists an  $\alpha$ -open set containing one of the points but not the other.

ii)  $\alpha$ - $T_1$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist  $\alpha$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively such that  $y \notin U$  and  $x \notin V$ .

iii)  $\alpha$ - $T_2$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist disjoint  $\alpha$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively.

**Definition 2.4:[9]** A topological space  $(X, \tau)$  is said to be

i)  $gb$ - $T_0$  if for each pair of distinct points in  $X$ , there is a  $gb$ -open set containing one of the points but not the other.

ii)  $gb$ - $T_1$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist  $gb$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively such that  $y \notin U$  and  $x \notin V$ .

iii)  $gb$ - $T_2$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist disjoint  $gb$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively.

**Definition 2.5:** A topological space  $(X, \tau)$  is said to be

i)  $g^*b$ - $T_0$  if for each pair of distinct points in  $X$ , there is a  $g^*b$ -open set containing one of the points but not the other.

ii)  $g^*b$ - $T_1$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist  $g^*b$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively such that  $y \notin U$  and  $x \notin V$ .

iii)  $g^*b$ - $T_2$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist disjoint  $g^*b$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively.

**Definition 2.6:** A topological space  $(X, \tau)$  is said to be

i)  $b\hat{g}$ - $T_0$  if for each pair of distinct points in  $X$ , there is a  $b\hat{g}$ -open set containing one of the points but not the other.

ii)  $b\hat{g}$ - $T_1$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist  $b\hat{g}$ -open sets  $U$  and  $V$  containing  $x$  and  $y$  respectively such that  $y \notin U$  and  $x \notin V$ .

iii)  $b\hat{g}$ - $T_2$  if for each pair of distinct points  $x$  and  $y$  of  $X$ , there exist disjoint  $b\hat{g}$ -open

sets  $U$  and  $V$  containing  $x$  and  $y$  respectively.

**Proposition 2.7:[2]** Every  $\alpha$ -closed set is  $sb\hat{g}$ -closed set

**Proposition 2.8:[2]**

- i) Every  $sb\hat{g}$ -closed set is  $b$ -closed set.
- ii) Every  $sb\hat{g}$ -closed set is  $gb$ -closed set.
- iii) Every  $sb\hat{g}$ -closed set is  $g^*b$ -closed set.
- iv) Every  $sb\hat{g}$ -closed set is  $b\hat{g}$ -closed set.

**Proposition 2.9:** Let  $A$  and  $B$  be subsets of a topological space  $(X, \tau)$ . Then

1.  $sb\hat{g}\text{-cl}(\phi) = \phi$  and  $sb\hat{g}\text{-cl}(X) = X$ .
2. If  $A \subseteq B$ , then  $sb\hat{g}\text{-cl}(A) \subseteq sb\hat{g}\text{-cl}(B)$ .
3.  $sb\hat{g}\text{-cl}(A \cap B) \subseteq sb\hat{g}\text{-cl}(A) \cap sb\hat{g}\text{-cl}(B)$ .
4.  $sb\hat{g}\text{-cl}(A \cup B) \supseteq sb\hat{g}\text{-cl}(A) \cup sb\hat{g}\text{-cl}(B)$ .
5.  $A$  is an  $sb\hat{g}$ -closed set in  $(X, \tau)$  if and only if  $A = sb\hat{g}\text{-cl}(A)$ .
6.  $sb\hat{g}\text{-cl}(sb\hat{g}\text{-cl}(A)) = sb\hat{g}\text{-cl}(A)$ .

**Proposition 2.10:**

Let  $(X, \tau)$  be a topological space. Then  $x \in sb\hat{g}\text{-cl}(A)$  if and only if  $U \cap A \neq \phi$  for every  $sb\hat{g}$ -open set  $U$  containing  $x$ .

**3.  $sb\hat{g}$ - $T_i$  SPACES,  $i = 0, 1, 2$ .**

**Definition 3.1:** A topological space  $(X, \tau)$  is said to be  $sb\hat{g}$ - $T_0$  if for each pair of distinct point  $x, y$  in  $X$ , there exists an  $sb\hat{g}$ -open set  $U$  of  $X$  such that either  $x \in U$  and  $y \notin U$  or  $x \notin U$  and  $y \in U$ .

**Example 3.2:** Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a\}\}$ . Here,  $sb\hat{g}\text{-O}(X) = \{X, \phi, \{a\}, \{a, b\}, \{a, c\}\}$ . Clearly,  $X$  is an  $sb\hat{g}$ - $T_0$  space.

**Definition 3.3:** A topological space  $(X, \tau)$  is said to be  $sb\hat{g}$ - $T_1$  if for each pair of distinct points  $x, y$  in  $X$ , there exist two  $sb\hat{g}$ -open sets  $U$  and  $V$  such that  $x \in U$  but  $y \notin U$  and  $x \notin V$  but  $y \in V$ .

**Example 3.4:** Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ .  $sb\hat{g}\text{O}(X) = \{X, \phi, \{a\}, \{b\}, \{a, b\}, \{a, c\}, \{b, c\}\}$ . Clearly,  $X$  is an  $sb\hat{g}$ - $T_1$  space.

**Definition 3.5:** A topological space  $(X, \tau)$  is said to be  $sb\hat{g}$ - $T_2$  (or  $sb\hat{g}$ -Hausdorff) if for each distinct points  $x, y$  in  $X$ , there exist two disjoint  $sb\hat{g}$ -open sets  $U$  and  $V$  of  $X$  containing  $x$  and  $y$  respectively.

**Example 3.6:** Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{b\}, \{c\}, \{b, c\}\}$ . Here  $sb\hat{g}$ -

$O(X) = \{X, \phi, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$ .

Clearly,  $X$  is an  $sb\hat{g}-T_2$  space.

**Proposition 3.7:** For a topological space  $(X, \tau)$ , the following properties hold:

- i) Every  $\alpha-T_i$  space is  $sb\hat{g}-T_i$  space,  $i = 0, 1, 2$ .
- ii) Every  $sb\hat{g}-T_i$  space is  $b-T_i$  space,  $i = 0, 1, 2$ .
- iii) Every  $sb\hat{g}-T_i$  space is  $gb-T_i$  space,  $i = 0, 1, 2$ .
- iv) Every  $sb\hat{g}-T_i$  space is  $g^*b-T_i$  space  $i = 0, 1, 2$ .
- v) Every  $sb\hat{g}-T_i$  space is  $b\hat{g}-T_i$  space,  $i = 0, 1, 2$ .

**Proof:** The proofs follow from Proposition 2.7, 2.8(i), 2.8(ii), 2.8(iii) and 2.8(iv).

The following examples show that the converse of the above propositions need not be true.

**Example 3.8:**

(i) Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$ . Here  $\alpha-O(X) = \{X, \phi, \{a\}, \{b\}, \{a, b\}\}$  and  $sb\hat{g}-O(X) = \{X, \phi, \{a\}, \{b\}, \{a, b\}, \{a, c\}, \{b, c\}\}$ . Clearly  $(X, \tau)$  is  $sb\hat{g}-T_1$  and  $sb\hat{g}-T_2$  space but not  $\alpha-T_1$  and  $\alpha-T_2$  space.

(ii) Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a\}, \{b, c\}\}$ . Here  $b-O(X) = \{X, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$  and  $sb\hat{g}-O(X) = \{X, \phi, \{a, b\}, \{c\}\}$ . Clearly  $(X, \tau)$  is  $b-T_1$  space but not  $sb\hat{g}-T_i$  space,  $i=0, 1, 2$ .

(iii) Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a, b\}, \{c\}\}$ . Here  $gb-O(X) = \{X, \phi, \{a\}, \{b\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$  and  $sb\hat{g}-O(X) = \{X, \phi, \{a, b\}, \{c\}\}$ . Clearly  $(X, \tau)$  is  $gb-T_1$  space but not  $sb\hat{g}-T_i$  space,  $i=0, 1, 2$ .

(iv) Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a, c\}\}$ . Here  $g^*b-O(X) = \{X, \phi, \{a\}, \{c\}, \{a, b\}, \{a, c\}, \{b, c\}\}$  and  $sb\hat{g}-O(X) = \{X, \phi, \{a, c\}\}$ . Clearly  $(X, \tau)$  is  $g^*b-T_1$  space but not  $sb\hat{g}-T_i$  space,  $i=0, 1, 2$ .

v) Let  $X = \{a, b, c, d\}$  with a topology  $\tau = \{X, \phi, \{a\}, \{b, c, d\}\}$ . Here  $b\hat{g} O(X) = \{X, \phi, \{a\}, \{b\}, \{c\}, \{d\}, \{a, b\}, \{a, c\}, \{a, d\}, \{b, c\}, \{b, d\}, \{c, d\}, \{a, b, c\}, \{a, b, d\}, \{a, c, d\}, \{b, c, d\}\}$  and  $sb\hat{g} -O(X) = \{X, \phi, \{a\}, \{b, c, d\}\}$ . Clearly  $(X, \tau)$  is  $b\hat{g}-T_1$  space but not  $sb\hat{g}-T_i$  space,  $i=0, 1, 2$ .

**Proposition 3.9:**

A topological space  $(X, \tau)$  is  $sb\hat{g}-T_0$  if and only if for each pair of distinct points  $x, y$  of  $X$ ,  $sb\hat{g}-cl(\{x\}) \neq sb\hat{g}-cl(\{y\})$ .

**Proof:** Let  $(X, \tau)$  be an  $sb\hat{g}-T_0$  space and  $x, y$  be any two distinct points of  $X$ . There exists an  $sb\hat{g}$ -open set  $U$  containing  $x$  or  $y$ , say  $x$  but not  $y$ . Then  $X \setminus U$  is an  $sb\hat{g}$ -closed set which does not contain  $x$  but contains  $y$ . Since  $sb\hat{g}-cl(\{y\})$  is the smallest  $sb\hat{g}$ -closed set containing  $y$ ,  $sb\hat{g}-cl(\{y\}) \subseteq X \setminus U$ . Therefore,  $x \notin sb\hat{g}-cl(\{y\})$ . Consequently,  $sb\hat{g}-cl(\{x\}) \neq sb\hat{g}-cl(\{y\})$ . Conversely, suppose that  $x, y \in X$ ,  $x \neq y$  and  $sb\hat{g}-cl(\{x\}) \neq sb\hat{g}-cl(\{y\})$ . Let  $z \in X$  such that  $z \in sb\hat{g}-cl(\{x\})$  but  $z \notin sb\hat{g}-cl(\{y\})$ . We claim that  $x \notin sb\hat{g}-cl(\{y\})$ . Suppose  $x \in sb\hat{g}-cl(\{y\})$ . Then by proposition 2.9(2) and (6),  $sb\hat{g}-cl(\{x\}) \neq sb\hat{g}-cl(sb\hat{g}-cl(\{y\})) = sb\hat{g}-cl(\{y\})$ . Therefore,  $z \in sb\hat{g}-cl(\{y\})$  which is a contradiction. Thus,  $x \notin sb\hat{g}-cl(\{y\})$ . Now,  $X \setminus sb\hat{g}-cl(\{y\})$  is an  $sb\hat{g}$ -open set in  $X$  such that  $x \in X \setminus sb\hat{g}-cl(\{y\})$  and  $y \notin X \setminus sb\hat{g}-cl(\{y\})$ . Hence,  $(X, \tau)$  is an  $sb\hat{g}-T_0$  space.

**Proposition 3.10:** A topological space  $(X, \tau)$  is  $sb\hat{g}-T_1$  if and only if the singletons are  $sb\hat{g}$ -closed sets.

**Proof:** Let  $(X, \tau)$  be an  $sb\hat{g}-T_1$  space and  $x$  be any point of  $X$ . Suppose  $y \in X \setminus \{x\}$ . Then  $x \neq y$ . So, there exists an  $sb\hat{g}$ -open set  $U$  such that  $y \in U$  but  $x \notin U$ . Consequently,  $y \in U \cap X \setminus \{x\}$ , that is  $X \setminus \{x\} = \bigcup \{U : y \in U \cap X \setminus \{x\}\}$  which is  $sb\hat{g}$ -open. So, singletons in  $(X, \tau)$  are  $sb\hat{g}$ -closed sets. Conversely, suppose  $\{p\}$  is  $sb\hat{g}$ -closed for every  $p \in X$ . Let  $x, y \in X$  with  $x \neq y$ . Since  $x \neq y$ ,  $y \in X \setminus \{x\}$ . So,  $X \setminus \{x\}$  is an  $sb\hat{g}$ -open set contains  $y$  but not  $x$ . Similarly,  $X \setminus \{y\}$  is an  $sb\hat{g}$ -open set contains  $x$  but not  $y$ . Hence,  $X$  is an  $sb\hat{g}-T_1$  space.

**Proposition 3.11:** Let  $(X, \tau)$  be a topological space. Then the following statements are equivalent:

- 1)  $X$  is an  $sb\hat{g}-T_2$  space.
- 2) Let  $x \in X$ . For each  $y \neq x$ , there exists an  $sb\hat{g}$ -open set  $U$  containing  $x$  such that  $y \notin sb\hat{g}-cl(U)$ .
- 3) For each  $x \in X$ ,  $\bigcap \{sb\hat{g}-cl(U) : U \in sb\hat{g}-O(X) \text{ and } x \in U\} = \{x\}$ .

**Proof:**

(1)  $\Rightarrow$  (2): Since  $X$  is an  $sb\hat{g}-T_2$  space, for each  $y \neq x$ , there exist two disjoint  $sb\hat{g}$ -



open sets  $U$  and  $V$  such that  $x \in U$  and  $y \in V$ . If  $F = X \setminus V$ , then  $F$  is an  $sb\hat{g}$ -closed set such that  $U \subseteq F$ . By proposition 2.9(2),  $sb\hat{g}\text{-cl}(U) \subseteq sb\hat{g}\text{-cl}(F) = F$ . Since  $y \notin F$   $y \notin sb\hat{g}\text{-cl}(U)$ .

(2)  $\Rightarrow$  (3): Suppose for any  $x \in X$  and for each  $y \neq x$ , there exists an  $sb\hat{g}$ -open set  $U$  such that  $x \in U$  and  $y \notin sb\hat{g}\text{-cl}(U)$ . Therefore,  $y \notin \bigcap \{sb\hat{g}\text{-cl}(U) : U \in sb\hat{g}\text{-O}(X) \text{ and } x \in U\}$ . Hence,  $\bigcap \{sb\hat{g}\text{-cl}(U) : U \in sb\hat{g}\text{-O}(X) \text{ and } x \in U\} = \{x\}$ .

(3)  $\Rightarrow$  (1): Let  $x, y \in X$  and  $x \neq y$ . Then  $y \notin \{x\} = \bigcap \{sb\hat{g}\text{-cl}(U) : U \in sb\hat{g}\text{-O}(X) \text{ and } x \in U\}$ . This implies that, there exists an  $sb\hat{g}$ -open set  $U$  containing  $x$  such that  $y \notin sb\hat{g}\text{-cl}(U)$ . Let  $V = X \setminus sb\hat{g}\text{-cl}(U)$ . Then  $V$  is  $sb\hat{g}$ -open and  $y \in V$ . Now,  $U \cap V = U \cap (X \setminus sb\hat{g}\text{-cl}(U)) \subseteq U \cap (X \setminus U) = \emptyset$ . Therefore,  $X$  is an  $sb\hat{g}\text{-T}_2$  space.

**Proposition 3.12:** Every  $sb\hat{g}\text{-T}_1$  space is  $sb\hat{g}\text{-T}_0$  space.

**Proof:** The proof follows from definition 3.1 and 3.3.

The following example shows that the converse of the above proposition need not be true.

**Example:**

Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \emptyset, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}$ . Here  $sb\hat{g}\text{-O}(X) = \{X, \emptyset, \{a\}, \{b\}, \{a, b\}, \{a, c\}\}$ . Clearly,  $(X, \tau)$  is an  $sb\hat{g}\text{-T}_0$  space but not  $sb\hat{g}\text{-T}_1$  space.

**Proposition 3.13:** Every  $sb\hat{g}\text{-T}_2$  space is  $sb\hat{g}\text{-T}_1$  space.

**Proof :** The proof follows from definition 3.3 and 3.5.

**Definition 3.14:** A subset  $A$  of a topological space  $X$  is called  $sb\hat{g}$ -difference set (briefly  $sb\hat{g}\text{-D}$  set) if there are  $U, V \in sb\hat{g}\text{-O}(X)$  such that  $U \neq X$  and  $A = U \setminus V$ . It is true that every  $sb\hat{g}$ -open set different from  $X$  is an  $sb\hat{g}\text{-D}$  set if  $A = U$  and  $V = \emptyset$ . So, we can observe the following.

**Remark 3.15:** Every proper  $sb\hat{g}$ -open set is an  $sb\hat{g}\text{-D}$  set.

The following example shows that the converse of the above remark need not be true

**Example 3.16:** Let  $X = \{a, b, c, d\}$  with a topology  $\tau = \{X, \emptyset, \{a\}, \{a, c\}, \{a, b, d\}\}$ . Here

$sb\hat{g}\text{-O}(X) = \{X, \emptyset, \{a\}, \{a, b\}, \{a, c\}, \{a, d\}, \{a, b, c\}, \{a, b, d\}, \{a, c, d\}\}$ . Consider,  $U = \{a, b, d\} \neq X$  and  $V = \{a, b, c\}$  are  $sb\hat{g}$ -open sets in  $X$ . Then, we have  $A = U \setminus V = \{d\}$  is an  $sb\hat{g}\text{-D}$  set but not  $sb\hat{g}$ -open set.

**Definition 3.17:** A topological space  $(X, \tau)$  is said to be  $sb\hat{g}$ -symmetric if for  $x, y$  in  $X$ ,  $x \in sb\hat{g}\text{-cl}(\{y\})$  implies  $y \in sb\hat{g}\text{-cl}(\{x\})$  (or  $x \notin sb\hat{g}\text{-cl}(\{y\})$  implies  $y \notin sb\hat{g}\text{-cl}(\{x\})$ ).

**Example 3.18:** Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \emptyset, \{a\}, \{b\}, \{a, b\}\}$ . Here  $sb\hat{g}\text{-O}(X) = \{X, \emptyset, \{a\}, \{b\}, \{c\}, \{a, c\}, \{b, c\}\}$ . Here for any pair of distinct points  $x, y$  in  $X$ ,  $x \notin sb\hat{g}\text{-cl}(\{y\})$  implies  $y \notin sb\hat{g}\text{-cl}(\{x\})$  So,  $X$  is an  $sb\hat{g}$ -symmetric space.

**Proposition 3.19:** Let  $(X, \tau)$  be a topological space. Then  $(X, \tau)$  is an  $sb\hat{g}$ -symmetric space if and only if  $\{x\}$  is  $sb\hat{g}$ -closed for each  $x \in X$ .

**Proof:** Assume that  $\{x\}$  is  $sb\hat{g}$ -open in  $X$ . Then there exists  $sb\hat{g}$ -open set  $U$  such that  $\{x\} \subseteq U$ , but  $sb\hat{g}\text{-cl}(\{x\}) \not\subseteq U$ . Then  $sb\hat{g}\text{-cl}(\{x\}) \cap (X \setminus U) \neq \emptyset$ . Now, we take  $y \in sb\hat{g}\text{-cl}(\{x\}) \cap (X \setminus U)$ , then by hypothesis  $x \in sb\hat{g}\text{-cl}(\{y\})$  and also  $sb\hat{g}\text{-cl}(\{y\}) \subseteq (X \setminus U)$ . Therefore,  $x \notin U$ , which is a contradiction. Hence,  $\{x\}$  is  $sb\hat{g}$ -closed for each  $x \in X$ . Conversely, suppose singleton sets are  $sb\hat{g}$ -closed in  $X$ . We claim that  $X$  is an  $sb\hat{g}$ -symmetric space. Assume that  $x \in sb\hat{g}\text{-cl}(\{y\})$  but  $y \notin sb\hat{g}\text{-cl}(\{x\})$ . Then  $\{y\} \subseteq X \setminus sb\hat{g}\text{-cl}(\{x\})$ . So,  $sb\hat{g}\text{-cl}(\{y\}) \subseteq X \setminus sb\hat{g}\text{-cl}(\{x\})$ . Thus,  $x \in X \setminus sb\hat{g}\text{-cl}(\{x\})$ . Therefore,  $x \notin sb\hat{g}\text{-cl}(\{x\})$  which is a contradiction. Hence,  $y \in sb\hat{g}\text{-cl}(\{x\})$ .

**Corollary 3.20:** If a topological space  $(X, \tau)$  is an  $sb\hat{g}\text{-T}_1$  space, then it is  $sb\hat{g}$ -symmetric.

**Proof:** Since  $X$  is an  $sb\hat{g}\text{-T}_1$  space and by proposition 3.10, singleton sets are  $sb\hat{g}$ -closed. Therefore by Proposition 3.19,  $(X, \tau)$  is an  $sb\hat{g}$ -symmetric space.

**Corollary 3.21:** If a topological space  $(X, \tau)$  is  $sb\hat{g}$ -symmetric and  $sb\hat{g}\text{-T}_0$  space, then  $(X, \tau)$  is  $sb\hat{g}\text{-T}_1$  space.

**Proof:** Let  $x \neq y$  and  $(X, \tau)$  be an  $sb\hat{g}\text{-T}_0$  space. We may assume that  $x \in U \square X \setminus \{y\}$  for some  $U \in sb\hat{g}\text{-O}(X)$ . Then  $x \notin sb\hat{g}\text{-cl}(\{y\})$ . Since  $X$  is an  $sb\hat{g}$ -symmetric space,  $y \notin sb\hat{g}\text{-cl}(\{x\})$ . Then there exists an  $sb\hat{g}\text{-cl}(\{y\})$ . Since  $X$  is an  $sb\hat{g}$ -symmetric space,

$y \notin \text{sb}\hat{g}\text{-cl}(\{x\})$ . Then there exists an  $\text{sb}\hat{g}$ -open set  $V$  such that  $y \in V \cap X \setminus \{x\}$ . Hence,  $(X, \tau)$  is an  $\text{sb}\hat{g}$ -T1 space.

**Definition 3.22:** Let  $(X, \tau)$  be a topological space and  $A \subseteq X$ . Then the  $\text{sb}\hat{g}$ -kernel of  $A$  is denoted by  $\text{sb}\hat{g}\text{-ker}(A)$  and is defined to be  $\text{sb}\hat{g}\text{-ker}(A) = \bigcap \{U \in \text{sb}\hat{g}\text{-O}(X) : A \subseteq U\}$ .

**Example 3.23:** Let  $X = \{a, b, c\}$  with a topology  $\tau = \{X, \phi, \{a\}, \{a, b\}, \{a, c\}\}$ . Here  $\text{sb}\hat{g}\text{-O}(X) = \{X, \phi, \{a\}, \{a, b\}, \{a, c\}\}$ .  $\text{sb}\hat{g}\text{-ker}(\{a\}) = \{a\}$ ;  $\text{sb}\hat{g}\text{-ker}(\{b\}) = \{a, b\}$ ;  $\text{sb}\hat{g}\text{-ker}(\{c\}) = \{a, c\}$ ;  $\text{sb}\hat{g}\text{-ker}(\{a, b\}) = \{a, b\}$ ;  $\text{sb}\hat{g}\text{-ker}(\{a, c\}) = \{a, c\}$ ;  $\text{sb}\hat{g}\text{-ker}(\{b, c\}) = X$ .

**Proposition 3.24:** Let  $(X, \tau)$  be a topological space and  $x \in X$ . Then  $y \in \text{sb}\hat{g}\text{-ker}(\{x\})$  if and only if  $x \in \text{sb}\hat{g}\text{-cl}(\{y\})$ .

**Proof :** Suppose that  $y \notin \text{sb}\hat{g}\text{-ker}(\{x\})$ . Then there exists an  $\text{sb}\hat{g}$ -open set  $V$  containing  $x$  such that  $y \notin V$ . By proposition 2.10,  $x \notin \text{sb}\hat{g}\text{-cl}(\{y\})$ . Conversely, assume that  $x \notin \text{sb}\hat{g}\text{-cl}(\{y\})$ . Then there exists an  $\text{sb}\hat{g}$ -open set  $U$  containing  $x$  such that  $y \notin U$ . By the definition of  $\text{sb}\hat{g}$ -kernel,  $y \notin \text{sb}\hat{g}\text{-ker}(\{x\})$ .

**Proposition 3.25:** Let  $(X, \tau)$  be a topological space and  $A$  be a subset of  $(X, \tau)$ . Then  $\text{sb}\hat{g}\text{-ker}(A) = \{x \in X : \text{sb}\hat{g}\text{-cl}(\{x\}) \cap A \neq \phi\}$ .

**Proof:** Let  $x \in \text{sb}\hat{g}\text{-ker}(A)$ . Suppose  $x \notin \{x \in X : \text{sb}\hat{g}\text{-cl}(\{x\}) \cap A \neq \phi\}$ . Then  $\text{sb}\hat{g}\text{-cl}(\{x\}) \cap A = \phi$ . So,  $X \setminus \text{sb}\hat{g}\text{-cl}(\{x\})$  is an  $\text{sb}\hat{g}$ -open set containing  $A$  and  $x \notin X \setminus \text{sb}\hat{g}\text{-cl}(\{x\})$ . Therefore by definition 3.22  $x \notin \text{sb}\hat{g}\text{-ker}(A)$ . It contradicts  $x \in \text{sb}\hat{g}\text{-ker}(A)$ . Conversely, if  $\text{sb}\hat{g}\text{-cl}(\{x\}) \cap A \neq \phi$ . We claim that,  $x \in \text{sb}\hat{g}\text{-ker}(A)$ . Suppose that  $x \notin \text{sb}\hat{g}\text{-ker}(A)$ . Then there exists an  $\text{sb}\hat{g}$ -open set  $V$  containing  $A$  such that  $x \notin V$ . Now, let  $y \in \text{sb}\hat{g}\text{-cl}(\{x\}) \cap A$ . Then  $y \in \text{sb}\hat{g}\text{-cl}(\{x\})$  and  $y \in A$ . By proposition 2.10,  $y \in \text{sb}\hat{g}\text{-cl}(\{x\})$  implies  $V \cap \{x\} \neq \phi$  for every open set  $V$  containing  $y$ . Hence,  $x \in V$ . By this contradiction,  $x \in \text{sb}\hat{g}\text{-ker}(A)$ .

**Proposition 3.2:** The following properties hold for the subsets  $A, B$  of a topological space  $(X, \tau)$ :

- 1)  $A \subseteq \text{sb}\hat{g}\text{-ker}(A)$ .
- 2)  $A \subseteq B$  implies  $\text{sb}\hat{g}\text{-ker}(A) \subseteq \text{sb}\hat{g}\text{-ker}(B)$ .
- 3) If  $A$  is  $\text{sb}\hat{g}$ -open in  $(X, \tau)$ , then  $A = \text{sb}\hat{g}\text{-ker}(A)$ .

4)  $\text{sb}\hat{g}\text{-ker}(\text{sb}\hat{g}\text{-ker}(A)) = \text{sb}\hat{g}\text{-ker}(A)$ .

**Proof:** 1) Suppose that  $A$  is any subset of  $X$ . If  $x \notin \text{sb}\hat{g}\text{-ker}(A)$ , then there exist  $U \in \text{sb}\hat{g}\text{-O}(X)$  such that  $A \subseteq U$  and  $x \notin U$ . Therefore,  $x \notin A$ . Hence  $A \subseteq \text{sb}\hat{g}\text{-ker}(A)$ .

2) Let  $A \subseteq B$ . Suppose  $\text{sb}\hat{g}\text{-ker}(A) \not\subseteq \text{sb}\hat{g}\text{-ker}(B)$ . Then  $x \in \text{sb}\hat{g}\text{-ker}(A)$  but  $x \notin \text{sb}\hat{g}\text{-ker}(B)$ . By the definition of  $\text{sb}\hat{g}$ -kernel, there exists an  $\text{sb}\hat{g}$ -open set  $U$  such that  $B \subseteq U$  and  $x \notin U$ . Since  $A \subseteq B \subseteq U$ ,  $x \notin \text{sb}\hat{g}\text{-ker}(A)$ . By this contradiction,  $\text{sb}\hat{g}\text{-ker}(A) \subseteq \text{sb}\hat{g}\text{-ker}(B)$ .

3) Obvious from the definition of  $\text{sb}\hat{g}\text{-ker}(A)$ .

4) From (1) and (2), we have,  $\text{sb}\hat{g}\text{-ker}(A) \subseteq \text{sb}\hat{g}\text{-ker}(\text{sb}\hat{g}\text{-ker}(A))$ . To prove the other implication, if  $x \notin \text{sb}\hat{g}\text{-ker}(A)$ , then there exists  $U \in \text{sb}\hat{g}\text{-O}(X)$  such that  $A \subseteq U$  and  $x \notin U$ . Therefore,  $\text{sb}\hat{g}\text{-ker}(A) \subseteq U$  and so  $x \notin \text{sb}\hat{g}\text{-ker}(\text{sb}\hat{g}\text{-ker}(A))$ . Hence,  $\text{sb}\hat{g}\text{-ker}(A) = \text{sb}\hat{g}\text{-ker}(\text{sb}\hat{g}\text{-ker}(A))$ .

**Proposition 3.27 :** If a singleton set  $\{x\}$  is an  $\text{sb}\hat{g}$ -D set of  $(X, \tau)$ , then  $\text{sb}\hat{g}\text{-ker}(\{x\}) \neq X$ .

**Proof:** since  $\{x\}$  is an  $\text{sb}\hat{g}$ -D set of  $(X, \tau)$ , there exist two  $\text{sb}\hat{g}$ -open subsets  $U, V$  such that  $\{x\} = U \setminus V$ . So that  $\{x\} \subseteq U$  and  $U \neq X$ . By proposition 3.26(2) and (3),  $\text{sb}\hat{g}\text{-ker}(\{x\}) \subseteq U \neq X$ . Hence  $\text{sb}\hat{g}\text{-ker}(\{x\}) \neq X$ .

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