

# Köthe- Toeplitz Duals of Generalized Difference Sequence Spaces

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**Abstract:** In this paper we introduce the difference sequence spaces  $c_0(\Delta_v)$ ,  $c(\Delta_v)$ ,  $l_\infty(\Delta_v)$ , and  $bv(\Delta_v)$ . The properties of difference sequence spaces i.e. AK-Property, BK-Space, normality, Schauder basis and Köthe - Toeplitz duals are also the part of our studies. We extended the work done by Kizmaz on the difference sequence spaces  $c_0(\Delta)$ ,  $c(\Delta)$  and  $l_\infty(\Delta)$  and V. K. Bhardwaj and Sandeep Gupta on Cesaro summable difference sequence spaces  $C_1(\Delta)$ .

**Keywords-** Difference Sequence Spaces, BK-space, Schauder basis,  $\alpha$ -,  $\beta$  - and  $\gamma$  - duals and Köthe duals. - Toeplitz

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## Definitions

Let  $\omega$  denote the linear space of all complex sequence spaces over  $\mathbb{C}$  (the field of complex numbers). A vector subspace of  $\omega$  is called a sequence subspace.  $l_\infty$ ,  $c$ ,  $c_0$  denote the space of all bounded, convergent and null sequence spaces  $x = (x_k)$  with complex terms respectively. By  $cs$  we denote the space of all convergent series and  $bv$  denotes the space of all sequences of bounded variation.

Throughout this paper, unless otherwise specified we denote  $\sum_k$  for  $\sum_{k=1}^{\infty}$  and  $\lim_n$  for  $\lim_{n \rightarrow \infty}$ .

A complete metric linear space is called a Fréchet space. Let  $X$  be a linear subspace of  $\omega$  st.  $X$  is a Fréchet space with continuous coordinate projections. Then we say that  $X$  is FK-space. If the metric of a FK-space is given by a complete norm, then we say that  $X$  is BK-space.

We say that an FK-space  $X$  has AK or has the AK-property, if  $(e_k)$  the sequence of unit vectors, is a Schauder basis for  $X$ .

A sequence space  $X$  is called

- (i) normal if  $y = (y_k) \in X$  whenever  $|y_k| < |x_k|$ ,  $k \geq 1$  for some  $x = (x_k) \in X$
- (ii) monotone if it contains the canonical preimages of its step spaces.
- (iii) a sequence algebra if  $xy = (x_k y_k) \in X$  whenever  $x = (x_k), y = (y_k) \in X$ .
- (iv) symmetric if  $(x_k) \in X \Rightarrow (x_{\pi(k)}) \in X$  where  $\pi$  is permutation on  $\mathbb{N}$ .

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The idea of dual sequence spaces was introduced by Köthe and Toeplitz whose main result concerned  $\alpha$  – duals, the  $\alpha$  – dual of  $X \subset \omega$  being defined as-

$$X^\alpha = \left\{ a = (a_k) \in \omega : \sum_k |a_k x_k| < \infty \text{ for all } x = (x_k) \in X \right\}$$

They also introduced another kind of duals namely the  $\beta$  – dual by Chilling-worth[12],

$$X^\beta = \left\{ a = (a_k) \in \omega : \sum_k a_k x_k \text{ converges for all } x = (x_k) \in X \right\}$$

A still more general notion of dual was introduced by Garling in Kamthan and Gupta[7] as

$$X^\gamma = \left\{ a = (a_k) \in \omega : \sup_k \left| \sum_{i=1}^k a_i x_i \right| < \infty \text{ for all } x = (x_k) \in X \right\}$$

A more general notation of dual was introduced by Chandra and Tripathy[16],

$$X^\eta = \{ a = (a_k) \in \omega : (a_k x_k) \in I_r \text{ for all } x = (x_k) \in X \}$$

Obviously,  $\phi \subset X^\alpha \subset X^\beta \subset X^\gamma$ , where  $\phi$  is the well-known sequence spaces of finitely non-zero scalar sequences. Also if  $X \subset Y$  then  $Y^t = X^t$  for  $t = \alpha, \beta, \gamma$ . For any sequence space  $X$ , we denote  $(X^\delta)^t$  by  $X^{\delta t}$  where  $\delta, t = \alpha, \beta$  or  $\gamma$ . It is clear that  $X \subset X^{tt}$  where  $t = \alpha, \beta$  or  $\gamma$ .

For a sequence space  $X$ , if  $X = X^{\alpha\alpha}$  then  $X$  is called a Köthe space or a perfect space. The notion of difference sequence spaces was introduced by Kizmaz in 1981 as follows:

$$X(\Delta) = \{ x = (x_k) \in \omega : (\Delta x_k) \in X \}$$

for  $X = l_\infty, c, c_0$ ; where  $\Delta x_k = x_k - x_{k+1}$ , for all  $k \in \mathbb{N}$ .

## Introduction

The difference sequence spaces have been studied by Cooke[10], Maddox[2], Colak[4], Orhan[5] and Bektas[12]. Soon after the introduction of the notion of difference sequence space, Orhan[6], [7] in 1983, applied the same technique of taking differences to the Cesaro spaces  $ces_p$ ,  $1 \leq p \leq \infty$  and  $ces_\infty$  of Shiue[4] to introduce the Cesaro difference sequence spaces  $C_p$ ,  $1 \leq p \leq \infty$  and  $C_\infty$ . Malkowsky[1] studied the matrix transformations in difference sequence spaces. Since the initiation of the study of difference sequence spaces by kizmaz[3], a large number of literature has grown. The work of this paper is an extension of the work done by Kizmaz [3] on the difference sequence spaces  $c_0(\Delta), c(\Delta)$ , and  $l_\infty(\Delta)$  and V. K. Bhardwaj and Sandeep Gupta[13] on Cesaro summable difference sequence spaces  $c_1(\Delta)$ . Let  $v = (v_k) = (1, 1, 1, \dots)$  be any fixed sequence of non-zero complex numbers. Now we define

$$X(\Delta_v) = \{ x = (x_k) \in \omega : (\Delta_v x_k) \in X \}$$

for  $X = l_\infty, c, c_0, C_1, bv$ ; where  $\Delta_v x_k = v_k x_k - v_{k+1} x_{k+1}$ , for all  $k \in \mathbb{N}$ .  
i.e.

$$l_\infty(\Delta_v) = \{ x = (x_k) \in \omega : (\Delta_v x_k) \in l_\infty \};$$

$$c(\Delta_v) = \{ x = (x_k) \in \omega : (\Delta_v x_k) \in c \};$$

$$c_0(\Delta_v) = \{ x = (x_k) \in \omega : (\Delta_v x_k) \in c_0 \};$$

$$C_1(\Delta_v) = \{x = (x_k) \in \omega : (\Delta_v x_k) \in C_1\};$$

$$bv(\Delta_v) = \{x = (x_k) \in \omega : (\Delta_v x_k) \in bv\}.$$

The overall picture regarding inclusion among the already existing spaces  $l_\infty$ ,  $c$ ,  $c_0$ ,  $C_1$  and the newly introduced space  $l_\infty(\Delta_v)$ ,  $c(\Delta_v)$ ,  $c_0(\Delta_v)$ ,  $C_1(\Delta_v)$  and  $bv(\Delta_v)$  as shown below-

$$\begin{array}{ccccccc} & & & C_1 & \subset & C_1(\Delta_v) & \\ & & & \cup & & \cup & \\ l_1 & \subset & bv(\text{or } c_0) & \subset & c & \subset & l_\infty \\ \cap & & \cap & \cap & & \cap & \\ l_1(\Delta_v) & \subset & bv(\Delta_v)(\text{or } c_0(\Delta_v)) & \subset & c(\Delta_v) & \subset & l_\infty(\Delta_v) \\ & & & & & \cap & \\ & & & & & C_1(\Delta_v) & \end{array}$$

In section 3, different inclusion relations that are strict are discussed. Also different topological properties of  $C_1(\Delta_v)$  are also discussed. Section 4, is devoted to study of Köthe-Toeplitz and  $\gamma$  duals of these spaces.

## The Inclusion Relations

**Theorem 3.1**  $l_\infty \subset C_1(\Delta_v)$ , the inclusion being strict.

**Proof** Let  $x = (x_k) \in l_\infty$ . Then there exists  $M > 0$  such that  $|x_k - x_{k+1}| < M$  for all  $k \geq 1$ , and so  $\frac{1}{k} \sum_{i=1}^k \Delta v_i x_i \rightarrow 0$  as  $k \rightarrow \infty$ . For strict inclusion, observe that  $(k) \in C_1(\Delta_v)$  but  $k \notin l_\infty$ .

**Theorem 3.2**  $C_1 \subset C_1(\Delta_v)$ , the inclusion being strict.

**Proof** For  $x = (x_k) \in C_1$ , we have  $\lim_k \frac{1}{k} x_k = 0$ , and so  $\frac{1}{k} \sum_{i=1}^k \Delta v_i x_i \rightarrow 0$  as  $k \rightarrow \infty$ . Inclusion is strict in view of the example in theorem 3.1.

**Theorem 3.3**  $bv \subset bv(\Delta_v)$ , the inclusion being strict.

**Proof** Let  $x = (x_k) \in bv$ . Then  $(\Delta v_k x_k) \in l_1 \subset bv$ . For strict inclusion, consider the sequence  $x = (x_0, x_1, x_2, \dots)$  where

$$x_k = \begin{cases} 0, & \text{for } k = 0 \\ k(-1) - (k-1)\frac{1}{2} - (k-2)\frac{1}{2^2} \dots - \frac{1}{2^{k-1}}, & \text{for } k \geq 1. \end{cases}$$

Similarly,  $c_0 \subset c_0(\Delta_v)$ ,  $c \subset c(\Delta_v)$ ,  $l_\infty \subset l_\infty(\Delta_v)$  these inclusions are also strict.

**Theorem 3.4**  $c(\Delta_v) \subset C_1(\Delta_v)$ , the inclusion being strict.

**Proof** Inclusion is obvious since  $c \subset C_1$ . To see that the inclusion is strict, consider the sequence  $x = (x_k) = (1, 2, 1, 2, 1, 2, \dots)$ .

**Theorem 3.5**  $l_1(\Delta_v) \subset bv(\Delta_v) \subset c(\Delta_v)$ , the inclusion being strict.

**Proof** The result follows from the fact that  $l_1 \subset bv \subset c$ . For strict inclusion  $l_1(\Delta_v) \subset bv(\Delta_v)$ , observe

that  $(k) \in bv(\Delta_v)$  but  $(k) \in l_1(\Delta_v)$ . Inclusion  $bv(\Delta_v) \subset c(\Delta_v)$  is strict as  $(y_k) = \left(0, -1, -1 + \frac{1}{2}, -1 + \frac{1}{2} - \frac{1}{3}, \dots\right) \in c(\Delta_v)$  but does not belong to  $bv(\Delta_v)$ .

**Theorem 3.6**  $C_1(\Delta_v)$  and  $bv(\Delta_v)$  are BK-space with the norm  $\|x\|_{\Delta_v} = |x_1| +$

$\sup_k \frac{1}{k} \left| \sum_{i=1}^k \Delta v_i x_i \right|$ ,  $x = (x_k) \in C_1(\Delta_v)$  and  $\|x\|_{\Delta_v} = |x_1| + |x_2| + \sum_k |\Delta v_k x_k - \Delta v_{k+1} x_{k+1}|$ ,  $x = (x_k) \in bv(\Delta_v)$ , respectively.

**Proof** Since  $C_1(\Delta_v)$  and  $bv(\Delta_v)$  are Banach spaces with continuous coordinates, that is,  $\|x^s - x\|_{\Delta_v} \rightarrow 0$  implies  $|x_k^s - x_k| \rightarrow 0$ , for each  $k \in \mathbb{N}$ , as  $s \rightarrow \infty$ , they are also BK-spaces.

**Theorem 3.7**  $bv(\Delta_v)$  does not have the AK-property.

**Proof** Let  $x = (x_k) = (1, 2, 3, \dots) \in bv(\Delta_v)$ . Consider the  $n^{\text{th}}$  section of the sequence  $(x_k)$  as  $x^{[n]} = (1, 2, 3, \dots, n, 0, 0, 0, \dots)$ .

Then

$$\begin{aligned} \|x - x^{[n]}\|_{b\vartheta} &= \|(0, 0, 0, \dots, n+1, n+2, \dots)\|_{b\vartheta} \\ &= |0| + |0| + \dots + |n+1| + |n+2| + \dots \end{aligned}$$

which does not tend to 0 as  $n \rightarrow \infty$

**Theorem 3.8**  $bv(\Delta_v)$  is not monotone.

**Proof** Take  $(x_k) = (1, 1, 1, \dots) \in bv(\Delta_v)$  and  $y = y_k$  as

$$y_k = \begin{cases} x_k, & \text{if } k \text{ is odd} \\ 0, & \text{if } k \text{ is even} \end{cases}$$

i.e.,  $(y_k) = (1, 0, 1, 0, 1, 0, \dots)$ . Then  $(\Delta_v y_k) = (1, -1, 1, -1, \dots)$  and so  $(y_k) \notin bv(\Delta_v)$ .

**Theorem 3.9**  $bv(\Delta_v)$  is neither symmetric nor a sequence algebra.

**Proof** Let  $(x_k) = (1, 2, 3, 4, \dots) \in bv(\Delta_v)$  and  $(y_k) = (2, 1, 4, 3, 6, \dots)$  e a rearrangement of the terms of the sequence  $(x_k)$ . Here  $(\Delta_v y_k) = (1, -3, 1, -3, \dots) \in bv$  and so  $(y_k) \in bv(\Delta_v)$ . This shows that  $bv(\Delta_v)$  is not a symmetric space.

**Lemma 3.10** Let  $X$  be sequence space. Then we have

(i)  $X$  is perfect  $\Rightarrow X$  is normal  $\Rightarrow X$  is monotone.

(ii)  $X$  is normal  $\Rightarrow X^\alpha = X^\gamma$

(iii)  $X$  is monotone  $\Rightarrow X^\alpha = X^\beta$

**corollary 3.11**  $bv(\Delta_v)$  is not normal.

**Theorem 3.12**  $C_1(\Delta_v)$  is not separable.

**Proof** Let  $A$  be the of all sequence  $x_a, x_b, x_c, \dots$  where

$$x_a = (k+a)_k = (1+a, 2+a, \dots), \quad x_b = (k+b)_k = (1+b, 2+b, \dots), \dots$$

with  $|a-b| > \frac{1}{2}$ ;  $a, b \in \mathbb{R}$ . Clearly,  $A \subset C_1(\Delta_v)$  and  $A$  is uncountable. Let  $D$  be any dense set in  $C_1(\Delta_v)$ .

Define a map  $f: A \rightarrow D$  as follows:

Let  $x_a \in A \subset C_1(\Delta_v)$ . As  $D$  is dense in  $C_1(\Delta_v)$ , so there exists some  $z_{x_a} \in D$  such that  $\|x_a - z_{x_a}\|_{\Delta_v} < \frac{1}{4}$ .

We set  $f(x_a) = z_{x_a}$ .

For  $x_a, x_b \in A$ , we have

$$\begin{aligned}
\|x_a - x_b\|_{\Delta_v} &= |(x_a - x_b)_1| + \sup_k \frac{1}{k} \left| \sum_{i=1}^k \Delta(v_a x_a - v_b x_b)_i \right| \\
&= |(1+a) - (1+b)| + \sup_k \frac{1}{k} \left| \sum_{i=1}^k \Delta(v_a x_a - v_b x_b)_i \right| \\
&\geq |a - b| \\
&> \frac{1}{2}
\end{aligned}$$

Now

$$\begin{aligned}
\|x_a - x_b\|_{\Delta_v} &\leq \|x_a - z_{x_a}\|_{\Delta_v} + \|z_{x_a} - x_b\|_{\Delta_v} \\
\|z_{x_a} - x_b\|_{\Delta_v} &\geq \|x_a - x_b\|_{\Delta_v} - \|x_a - z_{x_a}\|_{\Delta_v} \\
&> \frac{1}{2} - \frac{1}{4} = \frac{1}{4}
\end{aligned}$$

and already we have  $\|x_b - z_{x_b}\| < \frac{1}{4}$ , therefore  $z_{x_a} \neq z_{x_b}$ . Hence  $f$  is one-one. As  $f(A) \subset D$ . So  $D$  is uncountable. Thus,  $C_1(\Delta_v)$  has no countable dense set.

**Corollary 3.13**  $C_1(\Delta_v)$  does not have a Schauder basis.

**Corollary 3.14**  $C_1(\Delta_v)$  does not have the AK-property.

**Theorem 3.15**  $C_1(\Delta_v)$  is not normal and hence neither perfect nor convergence free.

**Proof** Taking  $x = (x_k) = (k-1)$  and  $y = (y_k) = (-1)^k(k-1)$ , we see that  $x \in C_1(\Delta_v)$  but  $y \notin C_1(\Delta_v)$  although  $|y_k| \leq |x_k|, k \geq 1$  and so  $C_1(\Delta_v)$  is not normal. It is well known that every perfect space, and also every convergence free space, is normal and Consequently  $C_1(\Delta_v)$  is neither perfect nor convergence free.

**Theorem 3.16**  $C_1(\Delta_v)$  is neither monotone nor a sequence algebra.

**Proof** Take  $x = (x_k) = (k) \in C_1(\Delta_v)$ . Consider  $y = (y_k)$  where

$$y_k = \begin{cases} x_k, & \text{if } k \text{ is odd} \\ 0, & \text{if } k \text{ is even} \end{cases}$$

i.e,  $y = (1, 0, 3, 0, 5, \dots)$ . Then  $(\Delta_v y_k) = (1, -3, 3, -5, \dots)$  and  $(\Delta_v y_k) \notin C_1$ , i.e.  $y_k \notin C_1(\Delta_v)$  and hence  $C_1(\Delta_v)$  is not monotone. To see that  $C_1(\Delta_v)$  is not sequence algebra, take  $x = y = (k)$  and observe that  $x, y \in C_1(\Delta_v)$  but  $xy = (k^2) \notin C_1(\Delta_v)$ .

## Köthe - Toeplitz duals

**Theorem 4.1**

$$[C_1(\Delta_v)]^\alpha = \{a = (a_k) : \sum_k k |a_k| < \infty\} = D_1$$

**Proof** Let  $a = (a_k) \in D_1$ .

For any  $x = (x_k) \in C_1(\Delta_v)$ ,

we have

$$\frac{1}{k} \left( \sum_{i=1}^k \Delta v_i x_i \right) \in c$$

i.e.,

$$\frac{1}{k}(v_1x_1 - v_{k+1}x_{k+1}) \in c$$

and so there exists some  $M > 0$  such that  $|x_k| \leq M(k-1) + x_1$  for  $k \geq 1$  and hence  $\sup_k \frac{1}{k}|x_k| < \infty$ , which implies that

$$\sum_k |a_k x_k| = \sum_k (k|a_k|)(k^{-1}|x_k|) < \infty$$

Thus,  $a = (a_k) \in [C_1(\Delta_v)]^\alpha$ .

Conversely, let  $a = (a_k) \in [C_1(\Delta_v)]^\alpha$ .

Then  $\sum_k |a_k x_k| < \infty$  for all  $x = (x_k) \in [C_1(\Delta_v)]^\alpha$ . Taking  $x_k = k$  for all  $k \geq 1$ , we have  $x = (x_k) \in [C_1(\Delta_v)]^\alpha$  when  $\sum_k k |a_k| < \infty$ .

Similarly we can show that,

$$[l_\infty(\Delta_v)]^\alpha = \{a = (a_k): \sum_k k |a_k| < \infty\} = D_1$$

$$[c(\Delta_v)]^\alpha = \{a = (a_k): \sum_k k |a_k| < \infty\} = D_1$$

$$[c_0(\Delta_v)]^\alpha = \{a = (a_k): \sum_k k |a_k| < \infty\} = D_1$$

$$[bv(\Delta_v)]^\alpha = \{a = (a_k): \sum_k k |a_k| < \infty\} = D_1$$

i.e.,

$$[l_\infty(\Delta_v)]^\alpha = [c(\Delta_v)]^\alpha = [c_0(\Delta_v)]^\alpha = [bv(\Delta_v)]^\alpha = [C_1(\Delta_v)]^\alpha = D_1$$

So, we conclude that  $\alpha$  – duals of difference sequence spaces  $[l_\infty(\Delta_v)]$ ,  $[c(\Delta_v)]$ ,  $[c_0(\Delta_v)]$ ,  $[bv(\Delta_v)]$  and  $[C_1(\Delta_v)]$  coincide.

#### Theorem 4.2

$$[C_1(\Delta_v)]^{\alpha\alpha} = \{a = (a_k): \sup_k \frac{1}{k}|a_k| < \infty\} = D_2$$

The result follows in view of Theorem 4.1 and the fact ([10], Theorem 4.3) that  $[C_1(\Delta)]^{\alpha\alpha} = D_2$

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