# SOLUTION OF $(3 \times 3)$ LINEAR SYSTEM OF CONGRUENCES BY USING GAUSS ELIMINATION AND GAUSS JORDAN METHODS 

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#### Abstract

The purpose of this paper is to find the solution of $3 \times 3$ linear congruence system by using numerical methods. In Gauss elimination and Gauss Jordan methods the system converted into matrix form. The techniques employed to solve linear system of equations using matrices can be adapted nicely to solve higher order linear system (Congruences).


Keywords: Congrurnces, $3 \times 3$ linear system, Gauss Elimination Method and Gauss Jordan Method.

## I. INTRODUCTION

Numerical methods play a vital role to fit an approximate value of a system of linear equations. In number theory, the solutions are always an integer. Gauss Elimination and Jordan methods are two direct methods to find the accurate solution of system of linear equations. Gauss Jacobi and Seidel methods are not suitable to solve the congruences system, since these two are iterative methods. Here considering $3 \times 3$ linear system (Congruences) instead of linear equations.

## Definition: Congruence

If $m$ is a positive integer, we say the integers $a$ and $b$ are congruent modulo $m$, and write $a \equiv b(\bmod m)$, if they have the same remainder on division by $m$.
Definition: $\mathbf{3} \times \mathbf{3}$ linear system of congruences
A $3 \times 3$ linear system is a system of linear congruences is of the form
$a_{1} x+b_{1} y+c_{1} z=d_{1}(\bmod m)$
$a_{2} x+b_{2} y+c_{2} z=d_{2}(\bmod m)$
$a_{3} x+b_{3} y+c_{3} z=d_{3}(\bmod m)$

## II. METHODOLOGY

## Gauss Elimination Method:

Gauss elimination is an algorithm for solving systems of linear equations $A X=B$,
$a_{1} x+b_{1} y+c_{1} z=d_{1}$
$a_{2} x+b_{2} y+c_{2} z=d_{2}$
$a_{3} x+b_{3} y+c_{3} z=d_{3}$
In which, the augmented matrix $[A, B]$ is transformed into an upper triangular matrix. Then the solution is obtained by using back substitution method.

## Gauss Jordan Method:

In this method, the augmented matrix $[A, B]$ is transformed into diagonal matrix or unit matrix. Then the solution is obtained directly from the resultant matrix.

## III. EXAMPLE

Solve $2 x-3 y+z \equiv 12(\bmod 13), x+2 y-z \equiv 6(\bmod 13)$ and $3 x-y+2 z \equiv 2(\bmod 13)$ by Gauss elimination method and Gauss Jordan method.
Solution:

## Gauss Elimination Method:

$$
\begin{array}{rlrl}
(A, B) & \equiv\left(\begin{array}{cccc}
2 & -3 & 1 & 12(\bmod 13) \\
1 & 2 & -1 & 6(\bmod 13) \\
3 & -1 & 2 & 2(\bmod 13)
\end{array}\right) & \\
& \equiv\left(\begin{array}{cccc}
2 & -3 & 1 & 12(\bmod 13) \\
0 & 7 & -3 & 0(\bmod 13) \\
0 & 7 & 1 & 7(\bmod 13)
\end{array}\right) & & \left(\because R_{2} \rightarrow 2 R_{2}-R_{1} \text { and } R_{3} \rightarrow 2 R_{3}-3 R_{1}\right) \\
& \equiv\left(\begin{array}{cccc}
2 & -3 & 1 & 12(\bmod 13) \\
0 & 7 & -3 & 0(\bmod 13) \\
0 & 0 & 4 & 7(\bmod 13)
\end{array}\right) & & \left(\because R_{3} \rightarrow R_{3}-R_{2}\right)
\end{array}
$$

By back Substitution method,
From $R_{3}, 4 z \equiv 7(\bmod 13)$,i.e., $z \equiv 5(\bmod 13)$
From $R_{2}, 7 y-3 z \equiv 0(\bmod 13)$,i.e., $y \equiv 4(\bmod 13)($ by $(1))$
From $R_{1}, 2 x-3 y+z \equiv 12(\bmod 13)$, i.e., $x \equiv 3(\bmod 13)($ by $(1) \&(2))$
Therefore the solution is
$x \equiv 3(\bmod 13)$
$y \equiv 4(\bmod 13)$
$z \equiv 5(\bmod 13)$
Gauss Jordan Method:

Then from $R_{1}, 14 x \equiv 3(\bmod 13)$,i.e., $x \equiv 3(\bmod 13)$
From $R_{2}, 4 y \equiv 3(\bmod 13)$, i.e., $y \equiv 4(\bmod 13)$
From $R_{3}, 4 z \equiv 7(\bmod 13)$, i.e., $z \equiv 5(\bmod 13)$
Hence the solution is
$x \equiv 3(\bmod 13)$
$y \equiv 4(\bmod 13)$
$z \equiv 5(\bmod 13)$

## Result:

$x \equiv 3(\bmod 13)$
$y \equiv 4(\bmod 13)$
$z \equiv 5(\bmod 13)$

## IV. CONCLUSION

Therefore the solution of $3 \times 3$ linear system on congruences is unique by using Gauss elimination and gauss Jordan methods.

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