

FPGA Implementation of Pipelined 16-bit RISC Processor with Floating Point Unit

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Abstract: This paper describes implementation of 16-bit RISC processor with Floating Point mode design using Verilog Hardware Description Language (HDL). The architecture proposed is Harvard architecture having separate instruction and data memory. The important feature of proposed processor is pipelining, Floating Point Mode. Pipelining is used for improving the performance; such that the design is optimized for every clock cycle. one instruction is executed per clock. The instruction set finalized consists of 16 instructions, which is very compact, simple and easy to learn, which another key feature of the design is. The processor has ALU, Instruction Memory, Data Memory, Program Counter, Eight 16bit general purpose registers, Floating Point Adder/Subtractor, 4-bit flag register and priority based three vectored interrupts. The processor code is synthesized for Xilinx Spartan 3A Starter Board FPGA.

Index Terms – RISC, HDL, FPGA, Verilog, Xilinx, Spartan, Harvard, ALU.

I. INTRODUCTION

Due to betterment of field programmable gate array, have reached a point where architecture of processor can be modified by programming [1]. The main difference between the reconfigurable processor and ordinary microprocessors is the potential to make significant changes to the data path itself besides the control flow. On the other hand, the main distinction with application specific integrated circuits (ASIC's) is the feasibility to redesign the hardware during runtime by loading a new circuit on the reconfigurable fabric [2]. To minimize the amount of area required, complexity of instruction set, instruction cycle and cost during the implementation of the design Reduced Instruction Set Computer design technique is used. The usage of RISC processor is increasing extensively in all fields with expeditious development of the silicon technology and fall in the price of the integrated circuit. Memory is accessed by the load and store operations. Other operations are performed on register to register basis, so that this feature makes the instruction set design more clear as it allows execution of instructions at one instruction per cycle rate. Multiple instructions are executed simultaneously with the help of pipelining implementation technique. Clock power is important component of overall dynamic power consumption, which should be minimized in design in order to reduce the power consumption. One of the methods which are used to reduce the clock power is clock-gating (ANDing) which dynamically terminates the clock signals in unused modules of the total hardware. Universal Asynchronous Receiver Transmitter (UART) which is a type of serial communication mostly used for short distance communication, low speed, low-cost data exchange between the computer and other peripherals. It has advantages of high reliability, less transmission line and long transmission distance, and hence extensively used as a mode of communication between the computer and the peripherals.

II. BACKGROUND

In outlining a chip, there are a few parameters that must be considered. Some of these parameters include: speed review, throughput, number of bits that the microchip manages at once, number of instructions the chip can execute, and different contemplations that contributes for the execution of the chip. Too, factors that incorporate multifaceted nature, possibility for usage, configuration structure, and capacity to be actualized in the accessible apparatuses were likewise considered. So as to deliver and to know the contemplations for these parameters, the accompanying investigations also, chip designs were looked into and examined.

1) Pipelined vs Non-pipelined: Normally pipeline implemented processors are faster than Non-pipelined processors. In Non-Pipelined processors one instruction is executed per clock cycle but in pipeline implemented processor every part of it is kept busy. Many instructions are executed per clock cycle in pipelining technique by dividing a single instruction into many number of instructions.

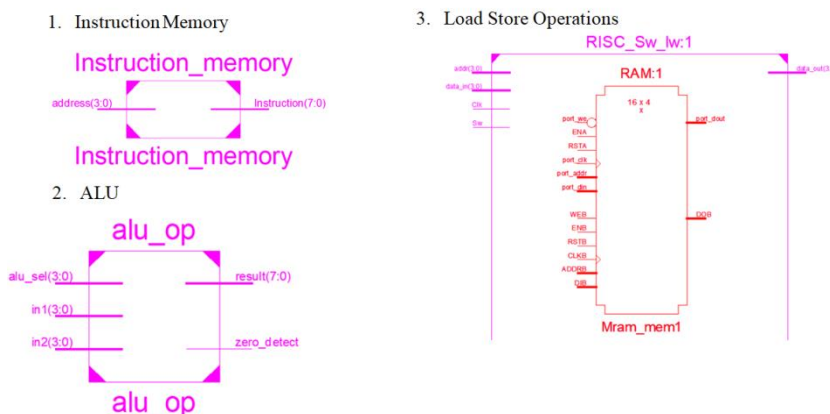
Pipelining increases the CPU throughput but increases the latency due to overhead of the pipelining process itself. Hardware or software implementation of pipeline technique is possible. Pipeline is a series of stages where some work is done at each stage and work is not completed until it has passed through all the stages.

2) Architecture comparison- RISC vs CISC: RISC stands for Reduced Instruction Set Computer whereas Complex Instruction Set Computer is an abbreviation of CISC. CISC had large number of instructions wherein some instructions for special tasks where used infrequently. Compilers became more prevalent. RISC whereas is designed to perform smaller number of types of computer instruction so it is able to operate at a higher speed than CISC. RISC has less number of instructions may be 128 or less and hence few addressing modes. Memory access instructions were limited to LOAD and STORE. All operations were done within the registers of the CPU. The most important feature of RISC compared with that of CISC is Single cycle Instruction execution i.e done by overlapping fetch, decode and execute phases of two or three instructions known as pipelining. Clock

		Before Execution	After Execution																																
<p>Addition: The instruction given to perform addition operation is as shown in fig. The addition operation is performed and the result is stored in the register. From the fig we can see that the values in the register 2 and register 3 are added and the result is stored in the register 1.</p>	<pre>input clk; input [15:0] Instruction_address; output reg [15:0] Instruction; wire [15:0] Inst_Mem[0:65535]; assign Inst_Mem[0] = 16'h0990; // add \$1, \$2, \$3, \$1= \$2+\$3 assign Inst_Mem[1] = 16'h0000; assign Inst_Mem[2] = 16'h0000; assign Inst_Mem[3] = 16'h0000;</pre>	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>2</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>7</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	7	2	3	3	4	4	5	5	6	6	7	7	8
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<p>Subtraction: The instruction given to perform subtraction operation is as shown in fig. The subtraction operation is performed and the result is stored in the register. From the fig we can see that the values in the register 2 and register 3 are subtracted and the result is stored in the register 1.</p>	<pre>input clk; input [15:0] Instruction_address; output reg [15:0] Instruction; wire [15:0] Inst_Mem[0:65535]; assign Inst_Mem[0] = 16'h0991; // sub \$1, \$2, \$3</pre>	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>2</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>1</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	1	2	3	3	4	4	5	5	6	6	7	7	8
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<p>AND: The instruction given to perform and operation is as shown in fig. The AND operation is performed and the result is stored in the register. From the fig we can see that the values in the register 2 and register 3 are ANDed and the result is stored in the register 1.</p>	<pre>input clk; input [15:0] Instruction_address; output reg [15:0] Instruction; wire [15:0] Inst_Mem[0:65535]; assign Inst_Mem[0] = 16'h0992; // and \$1, \$2, \$3 assign Inst_Mem[1] = 16'h0000;</pre>	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>2</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>0</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	0	2	3	3	4	4	5	5	6	6	7	7	8
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<p>OR: The instruction given to perform OR operation is as shown in fig. The OR operation is performed and the result is stored in the register. From the fig we can see that the values in the register 2 and register 3 are ORed and the result is stored in the register 1.</p>	<pre>input clk; input [15:0] Instruction_address; output reg [15:0] Instruction; wire [15:0] Inst_Mem[0:65535]; assign Inst_Mem[0] = 16'h0993; // or \$1, \$2, \$3 assign Inst_Mem[1] = 16'h0000;</pre>	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>2</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>7</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	7	2	3	3	4	4	5	5	6	6	7	7	8
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<p>Load Word (LW): The contents stored in the data memory are transferred to the register. The offset and base address of the memory is required and then the particular locations of the memory are transferred into the register. The instruction for the load word is as shown in the fig.</p>	<pre>module Instruction_memory (clk, Instruction_address, Instruction); input clk; input [15:0] Instruction_address; output reg [15:0] Instruction; wire [15:0] Inst_Mem[0:65535]; assign Inst_Mem[0] = 16'h8180; // lw \$3,0(\$0) --> \$3 = memory[\$0 + 0]; assign Inst_Mem[1] = 16'h0000;</pre> <p>The values stored in the data memory can be read and stored in a register. The offset is added with the content of any one of the required register and that content of the memory is transferred to the register</p>	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>2</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>4</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	2	2	3	3	4	4	5	5	6	6	7	7	8	<table border="1"> <tr><td>0</td><td>1</td></tr> <tr><td>1</td><td>2</td></tr> <tr><td>2</td><td>3</td></tr> <tr><td>3</td><td>20</td></tr> <tr><td>4</td><td>5</td></tr> <tr><td>5</td><td>6</td></tr> <tr><td>6</td><td>7</td></tr> <tr><td>7</td><td>8</td></tr> </table>	0	1	1	2	2	3	3	20	4	5	5	6	6	7	7	8
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<p>Looping:Set if Less Than Integer (slti):</p> <p>It is used to record the result of a less than comparison with a constant. It compares the content of the register and immediate and records the Boolean result of the comparison in the destination register. If the contents of the register is less than the immediate the result is 1 (true) or else 0 (false). The instruction for the slti operation is as shown in the fig.</p>	<pre> module Instruction_memory (clk, Instruction_address input clk; input [15:0] Instruction_address; output reg [15:0] Instruction; wire [15:0] Inst_Mem[0:65535]; assign Inst_Mem[0] = 16'h2CE4; // slti \$1, \$3, 100 assign Inst_Mem[1] = 16'h0000; </pre>		
<p>Test Code: A code snippet, is taken which has both branching and looping instructions. The performance of the processor is evaluated using this piece of code shown below</p> <pre> Loop: lw \$3, 0(\$0) slti \$1, \$3, 100 beq \$1, \$0, Skip add \$4, \$4, \$3 addi \$3, \$3, 1 beq \$0, \$0, Loop Skip: </pre>	<pre> Inst_Mem[0] = 16'h0000; // when reset .. PC is s Inst_Mem[1] = 16'h8180; //lw \$3,0(\$0) --> \$3 = m Inst_Mem[2] = 16'h2CE4; //slti \$1,\$3,100(2Ce4) s Inst_Mem[3] = 16'hC46B; // beq,\$1,\$3, skip Inst_Mem[4] = 16'h0E40; // add \$4,\$4,\$3 Inst_Mem[5] = 16'hED81; // addi \$3,\$3,1 Inst_Mem[6] = 16'hc001; //beq \$0,\$0, loop Inst_Mem[7] = 16'h0000; Inst_Mem[8] = 16'h0000; </pre>		
<p>Floating Point Mode</p>			

FPGA Implementation: To test the complete code on the evaluation kit was not possible, hence the code was split into 3 functional modules for testing on FPGA i.e Instruction Memory, ALU and Store and Load operation. Since the evaluation FPGA has 8 LEDs, 8 DIP switches and 5 Switch's, the code was accordingly modified so that the output could be seen on FPGA.



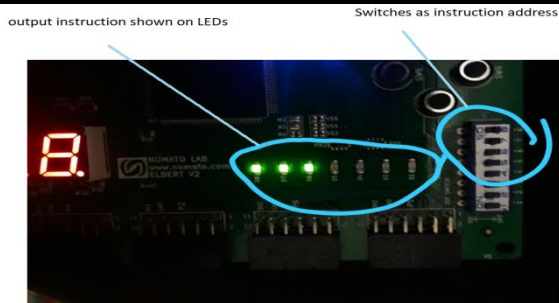


Fig2: Implementation snap shots of FPGA results

V. CONCLUSION AND FUTURE SCOPE

Hence we have designed a 8-bit RISC processor incorporated with pipelining technique for performance enhancement, simulated using modelsim and have implemented the same on Xilinx Spartan 3E starter board FPGA at speed of more than 60MHz. The complete instruction set were tested individually and at last a code snippet is tested which consisted of all type of instructions. Pipelining technique had yield better results with respect to the speed of the execution of the processor. The proposed processor has the uplift of lower power dissipation, occupies lesser area and achieves faster concurrent programming execution.

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