

An Efficient Multicast Protocol for Network Capacity Enhancement in Mobile Ad-Hoc Network

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Abstract : Node movement highlight of Mobile ad hoc network (MANET) intently takes after with that of mobile ad hoc network (MANET) however its rapid versatility and flighty development attributes are the key contrasting element from that of MANET. The likeness nature proposes that the predominant steering protocol of MANET is especially appropriate to MANET. In any case, on a similar line, the divergence qualities result in incessant loss of connectivity. This requires up gradation of the current directing protocols to adapt itself into MANET situation. In this paper, proposed on demand multicast steering protocol (ODMRP). The exhibitions are assessed by fluctuating portability, number of sources and node speed while packet delivery fraction, start to finish delay and standardized steering load are utilized as execution measurements. The simulations have demonstrated that OMMRP performs similarly superior to DSR and AODV in various versatility models as far as start to finish delay as execution metric.

IndexTerms - MANET, Multihop, Protocol, Packet, Mobile, ODMRP.

I. INTRODUCTION

Node movement requires up gradation of the current steering protocols to adapt itself into MANET situation. The key parameter that should be bolstered into these protocols is a sensible versatility model which contains criterion connected to speed, road intersections, traffic light impact and so forth. In this paper, we look at exhibitions of receptive directing protocols named Dynamic Source Steering (DSR), Ad hoc On Demand Separation Vector (AODV) and Ad hoc On Demand Multipath Separation Vector (AOMDV) in MANET utilizing diverse Versatility Models gave in MANET MobiSim structure. The exhibitions are assessed by differing versatility, number of sources and node speed while packet delivery fraction, start to finish delay and standardized steering load are utilized as execution measurements. The simulations have demonstrated that AOMDV performs nearly superior to DSR and AODV in various portability models regarding start to finish delay as execution metric. MANET, which is the wireless ad hoc communication between vehicles, has as of late risen as one of the interesting issues in investigations of wireless network innovation. Specifically, MANET is utilized in smart transportation frameworks or ITS. The ITS applications have turned out to be progressively compelling in the ebb and flow driving method of road drivers. One of the conspicuous functions of ITS is to produce different kinds of accommodating traffic information to drivers. The drivers can basically get the encompassing traffic condition, road condition, security information, business advertisement, and so on. In addition, MANET can help in rush hour gridlock the board. Tiaprasert et al. [1] and Comert [2] proposed a system to appraise the line length by utilizing MANET for traffic light control. In created nations, MANET can gather information. For instance, the vehicle information and communication framework (VICS) [3] has been propelled in Japan and especially used to convey traffic information to road vehicles. For the standard of VICS, all traffic information from road sensors is sent to a VICS focal server and spread to vehicles on the road framework. As per the VICS, an incorporated information collection plan has an incredible advantage on traffic information preparing. Notwithstanding, there are a couple of disadvantages. Initially, the procedures of both information assembling and scattering between a focal server and road sensors have long delays. Second, the achievement of the continuous applications isn't smooth a direct result of both absence of the focal server and quick versatility of vehicles. Accordingly, information dissemination techniques become one of the difficult issues of MANET, which must be investigated for certain upgrades and enhancements and improvements.

II. RESEARCH GAPS

A Various localization strategies have been proposed for processing the position of mobile nodes. A fascinating part of MANETs is that most localization methods can be connected effectively to these networks. Delineates various localization methods that can be utilized by vehicles to evaluate their positions, to be specific Guide Coordinating, Dead Reckoning, Cell Localization, Picture/Video Preparing, Localization Administrations, Sensors, DSRC, GSM, Radars and Relative Appropriated Ad Hoc Localization.

Routing protocol are fundamental pieces of MANETs. These protocols give an interface and communication between wireless gadgets. The examination holes depend on directing protocol. The primary objective for directing protocol is to give ideal ways between network nodes by means of least overhead. Many steering protocols have been produced for MANETs environment, which can be ordered from multiple points of view, as per various perspectives, for example, protocols attributes, procedures utilized, directing information, nature of administrations, network structures, directing calculations, etc. Some examination papers characterized MANETs steering protocols into five classes: topology-based, position-based, geocast-based, broadcast, and group based directing protocols, this classification depends on the steering protocols qualities and methods utilized. Topology-based steering protocol as a rule a traditional MANET directing protocol, it uses connection's information which put away in the directing table as a premise to advance packets from source node to destination, it commonly ordered into three classifications : Proactive (occasional), Responsive (on-demand) and Hybrid

Therefore the objective of the research is:-

To implement the design and developments of routing protocols for MANETs

Table 1: Comparison between different routing protocols of MANET

Protocol Proposed	Compared with protocol	Comparison parameters	Advantages	Disadvantages
VVR	GPSR, AODV	Delivery ratio, delay, normalized routing overhead	Solves the problem of routing holes problem	Success of packet delivery through edges is not guaranteed
STAR	GyTAR, GLS, VVR	Aggregate TCP throughput	Intersection based routing protocol used for urban areas	Less suitable for straight road
GLS	GyTAR, STAR	Average delivery delay, CDF of delivery ratio	Useful on straight road communication	Not useful on intersection of roads
GyTAR	GSR, LAR	Delivery ratio vs. (a)packet sending rate and (b) Nodes number	Limits the control message overhead, uses concept of prediction	Requires the additional information of network
GPCR	GyTAR	Delivery ratio and throughput	Don't require any global and external information i.e. maps	While choosing next hop, a coordinator node is preferred rather than non-coordinator even if is not closet to destination
GSR	GyTAR, LAR	Routing Overhead vs no. Of nodes	Combines position based routing with topological knowledge	Requires additional geographic information
VADD	D-VADD, MD-VADD, H-VADD, GPSR, Epidemic	Data sending rate for 150 nodes and 210 nodes	Support delay tolerate application in sparsely connected MANET	Uses predicable vehicle mobility which limited to traffic pattern and road layout
RSLs	HLS, GLS	Success rate vs velocity, success rate vs no. of vehicles	Is successful in terms of small and large scenarios in terms of success query rate	Not suitable for high speeds
RLFF	GPSR	Packet delivery ratio, delay and overhead	Suitable for both intersection and straight mode	Requires support from the traffic lights

III. PROPOSED PROTOCOL

In wireless networking, On-Demand Multicast Directing Protocol is a protocol for steering multicast and unicast traffic all through Ad hoc wireless work networks. ODMRP makes courses on demand, instead of proactively making courses as OLSR does. This experiences a course acquisition delay, in spite of the fact that it lessens network traffic when all is said in done. To help lessen the issue of this delay, a few implementations send the main information packet along with the course disclosure packet. Since certain connections might be awry, the way starting with one node then onto the next isn't really equivalent to the turnaround way of these nodes. .

IV. RESULT

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Command Window
4. time: 259 ms, SRC: 5, DST: A, PROTO: ODMRP, type=DATA, seq=1, len=616, last=5
5. time: 291 ms, SRC: 4, DST: A, PROTO: ODMRP, type=DATA, seq=2, len=616, last=4
6. time: 322 ms, SRC: 5, DST: A, PROTO: ODMRP, type=DATA, seq=1, len=616, last=5
7. time: 340 ms, SRC: 10, DST: A, PROTO: ODMRP, type=DATA, seq=3, len=616, last=10
8. time: 349 ms, SRC: 1, DST: A, PROTO: ODMRP, type=DATA, seq=1, len=616, last=1
9. time: 355 ms, SRC: 5, DST: A, PROTO: ODMRP, type=DATA, seq=1, len=616, last=5
10. time: 391 ms, SRC: 4, DST: A, PROTO: ODMRP, type=DATA, seq=3, len=616, last=4
11. time: 422 ms, SRC: 9, DST: A, PROTO: ODMRP, type=DATA, seq=2, len=616, last=9
12. time: 440 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=10, hops=9, ttl=32
13. time: 441 ms, SRC: 10, DST: A, PROTO: ODMRP, type=DATA, seq=4, len=616, last=10
14. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=1, hops=1, ttl=31
15. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=2, hops=1, ttl=31
16. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=3, hops=1, ttl=31
17. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=4, hops=1, ttl=31
18. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=5, hops=1, ttl=31
19. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=6, hops=1, ttl=31
20. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=7, hops=1, ttl=31
21. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=8, hops=1, ttl=31
22. time: 442 ms, SRC: 10, DST: 0, PROTO: ODMRP, type=JOIN REQ, seq=1, prev=9, hops=1, ttl=31
23. time: 449 ms, SRC: 1, DST: A, PROTO: ODMRP, type=DATA, seq=3, len=616, last=1
24. time: 459 ms, SRC: 5, DST: A, PROTO: ODMRP, type=DATA, seq=3, len=616, last=5
    
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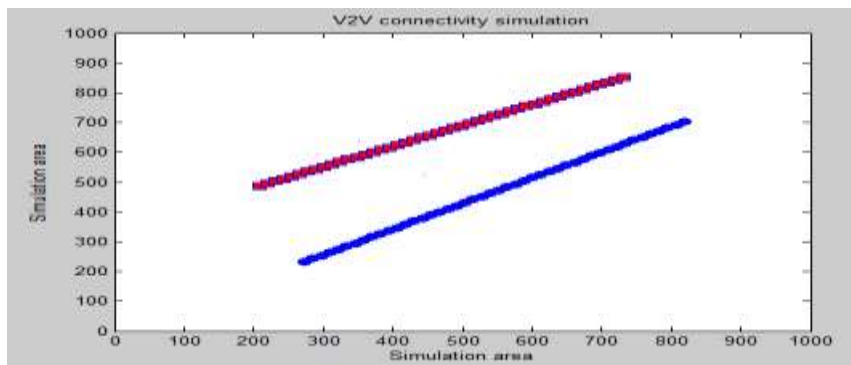


Figure 1: Simulation of NV2N

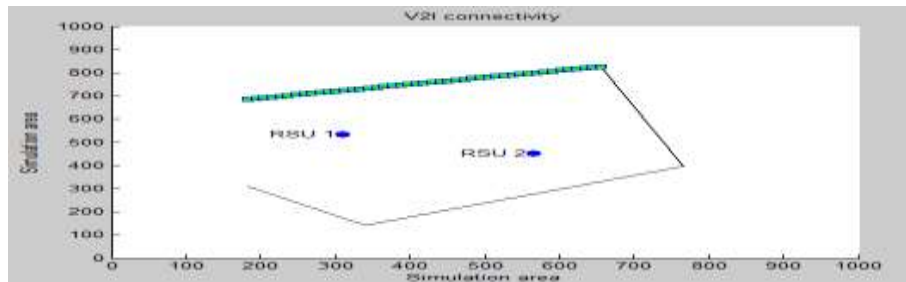
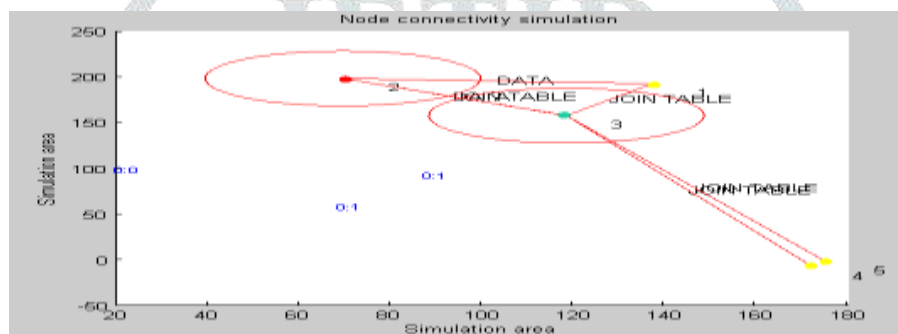
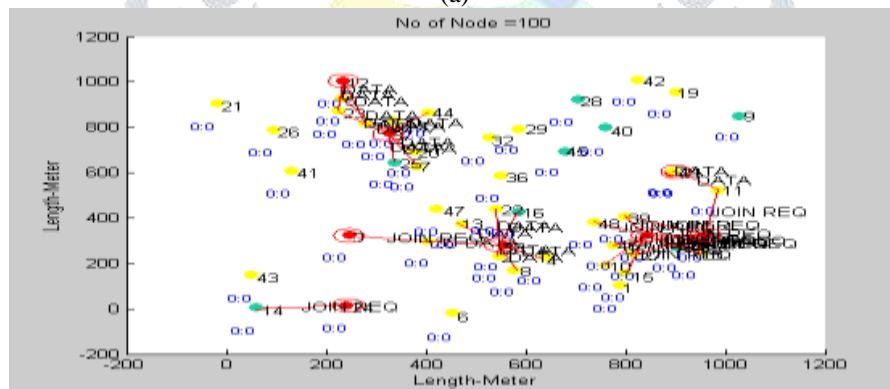


Figure 2: Node-to-roadside communication



(a)



(b)

Figure 3: (a) & (b) Simulation of MANET using ODMRP

Table I shows different parameters which included in simulation duration.

Table-1: Simulation parameters

Software	MATLAB 8.3.0.532 (R2014a)
System Environment	Windows 10
Time	100 ms to 1000 ms
Destination	1-100
Source	1-100
Protocol	ODMRP
Length	1200-1200

Table 2: Performance Parameter (Node=10)

Sr No.	Parameter	Value
1	Protocol	ODMRP
2	Packet Sent	30
3	Packet Received	183
4	Packets relayed	12
5	Total bytes sent	6488
6	Total bytes received	43560
7	Forwarding efficiency	1.20
8	Aggregated traffic	3
9	Packet delivery ratio	2.2
10	Single node Time	801ms
11	Total Simulation Time	4.51 Sec

Table-3 Comparison of Proposed work with previous work

PARAMETER	PREVIOUS WORK	PROPOSED WORK
Routing protocols	AODV, MAODV	ODMRP
Number of nodes:	Upto 100	Upto 100
Simulation Time:	10.1secs	8.39 Secs
Simulator:	NS3	MATLAB 2014
Mobility Model:	Random way point	Random way point
Area:	1000m*1000m	1200m*1200m
Packet Size	512 bytes	512 bytes

Table 3 shows Comparison of Proposed work with previous work in terms of different parameters like throughput, packet delivery ratio and end to end delay.

Packet Delivery Ratio (Throughput)= Data Rcvd / Data Sent

Control Overhead= Ctrl Bytes Sent / Data Bytes Rcvd

Forwarding Efficiency= Data + Ctrl Packets Sent / Data Packets Rcvd

Total Aggregated Traffic= Data + Ctrl Pkts Tx And Relayed / Ctrl + Data Pkts Rx

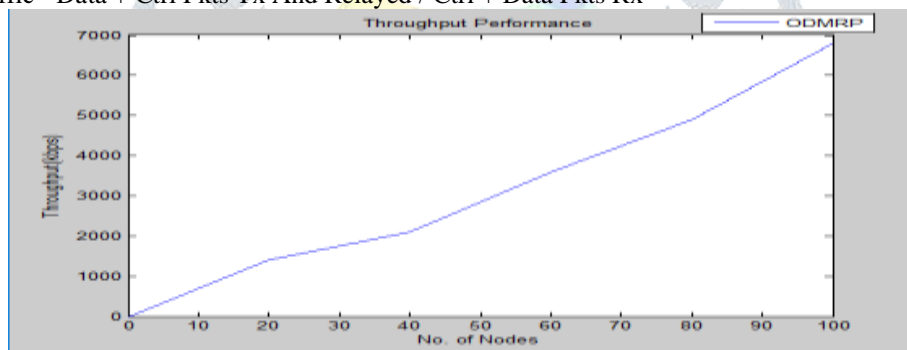


Figure 4: Throughput Performance

Figure 4 shows the performance of data rate or throughput. This is calculated by number of bits transmitted per second in ODMRP Protocol network.

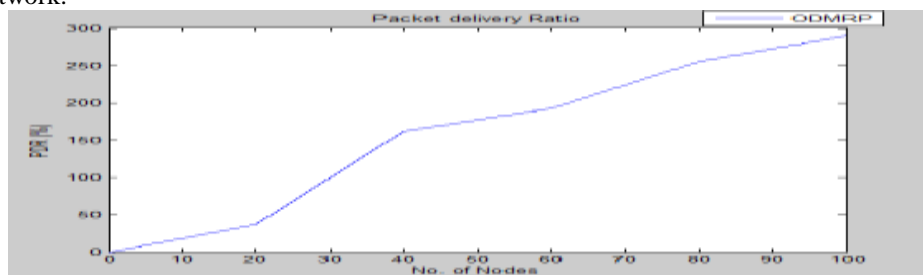


Figure 5: Packet Delivery Ratio

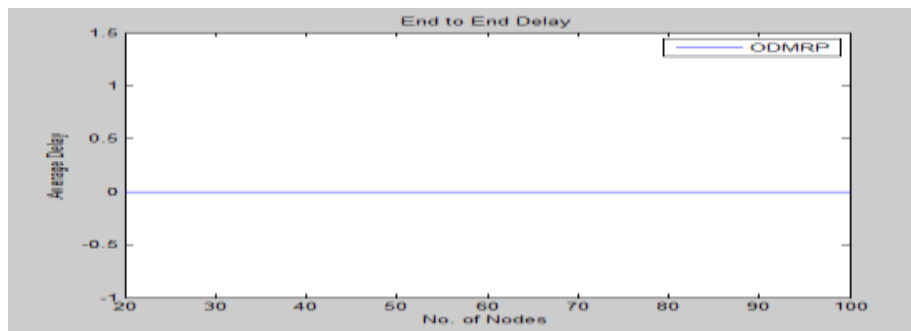


Figure 6: End to End Delay

V. CONCLUSION

An experiment of MANET simulation in a MATLAB has been done and the presentation parameters have been assessed, for example, End to End delay, and throughput. Execution of ODMRP is contrasted and MAODV and AODV Protocols regarding the exhibition parameters, for example, packet delivery ratio, Normal start to finish delay and directing overhead by utilizing MATLAB for various numbers of nodes (upto100). From the outcomes plainly at high versatility rate ODMRP performs better if there should be an occurrence of packet delivery ratio, Normal start to finish delay and directing overhead than AODV and MAODV. Thus ODMRP give preferable outcome in MATLAB environment over both AODV and MAODV.

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