

MITIGATION OF HARMONICS AND POWER QUALITY ENHANCEMENT FOR GRID CONNECTED WIND TURBINE WITH SEIG USING SOFT COMPUTING TECHNIQUE

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Abstract: Wind energy is integrated with the grid to meet the energy demand. Non Linear loads and SEIG consume reactive power and produce harmonics in the system. Due to harmonics many problems occurs as the power factor reduces, the devices may not work properly. Voltage fluctuations can also take place in case of harmonics. So there is need to reduce the harmonics and to inject the reactive power into the system. So STATCOM is connected in the system. STATCOM is a family of FACTS devices. STATCOM generate reactive power and reduce the harmonics.

Modelling of STATCOM and Wind Generator is done on MATLAB platform. In Control scheme of STATCOM fuzzy controller is used. The harmonics are reduced and voltage regulation is improved in the MATLAB Simulink Model.

IndexTerms: Wind Energy Conversion System, Fuzzy Controller, STATCOM.

I. INTRODUCTION

The energy demand is rising day by day as the population is increasing at a very rapid rate. So to meet the energy need we have to generate more electricity. In conventional method to produce electricity the fossil fuels are used that pollute the environment and has a very negative impact. So to have a sustainable growth we need to generate more electricity by the use of renewable energy. The renewable energy that includes wind energy, solar energy, tidal energy etc. These types of energy is clean and produce no pollution and do not harm the environment. The power generated by the wind must be integrated to the grid. In the recent years there has been extensive growth in the use of wind energy. Various power quality issues are also associated with the integration of wind turbines. To solve the problem of poor power quality STATCOM is used. STATCOM injects the reactive power into the system and hence harmonics are reduced by the injection of reactive power. The flow of the reactive power is controlled by the control of the bus voltage, the magnitude of the bus voltage decides the direction of reactive power flow. The induction generator is used in the wind turbine. Induction generator has various advantages that includes cost effectiveness and robustness. But the reactive power is required by the induction machine. In this thesis STATCOM based control scheme is introduced that is based on the fuzzy system. In a conventional STATCOM PI controller is used in the voltage regulator. But in this thesis the fuzzy system is used. Generally fuzzy system is used where the mathematical model cannot be formed. If there is experience based system then we use the fuzzy system.

II. BASIC PRINCIPLE OF STATCOM

The current I is given by the formula

$$I = \frac{V - E}{X}$$

The reactive power is given by

$$Q = \frac{I - \frac{E}{V}}{X} - V^2$$

So the basic principle of operation of STATCOM is controlling the magnitude of E. If the value of E is greater than V this will result in a leading current that is the STATCOM is operating as over excited machine, STATCOM is seen as capacitor by the system. If the value of E is lesser than V this will result in a lagging current that is STATCOM is operating as under excited machine, the STATCOM is seen as inductor by the system.

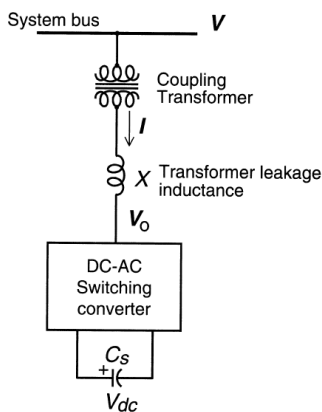


Figure 1.1 Reactive power generation by a voltage source switching converter

The basic principle of operation of voltage source switching converter is same as that of rotating synchronous compensator. If we change the amplitude of output voltage the reactive power will also be changed. If the value of output voltage is greater than the system bus voltage then the current will flow from the converter to the system bus, the converter generates the reactive power. Conversely if the value of output voltage is lower than the voltage of the system bus voltage then the current will flow from system bus to converter, the converter absorbs reactive power.

III. CONTROL SCHEME OF STATCOM

There are two components of source currents

- i. In phase component
- ii. Quadrature component

The component which is responsible for active power is in phase component which is represented by $(i^*_{sad}, i^*_{sbd}, i^*_{scq})$

The component which is responsible for AC voltage control is quadrature component which is represented by $(i^*_{saq}, i^*_{sbq}, i^*_{scq})$

The amplitude of reference voltage is compared with the AC voltage. The error produced is then processed in PID controller. Then a current controller which is based on PWM is used to control STATCOM currents.

$$v_m = \sqrt{\frac{2}{3}(v_a^2 + v_b^2 + v_c^2)}$$

The unit vector u_a, u_b, u_c are calculated as

$$u_a = \frac{v_a}{v_m}$$

$$u_b = \frac{v_b}{v_m}$$

$$u_c = \frac{v_c}{v_m}$$

The unit vector in quadrature with v_a, v_b, v_c may be derived by taking a quadrature transformation of in phase unit vector.

$$w_a = -\frac{u_b}{\sqrt{3}} + \frac{u_c}{\sqrt{3}}$$

$$w_b = \frac{\sqrt{3}}{2}u_a + \frac{u_b}{2\sqrt{3}} - \frac{u_c}{2\sqrt{3}}$$

$$w_c = -\frac{\sqrt{3}}{2}u_a + \frac{u_b}{2\sqrt{3}} - \frac{u_c}{2\sqrt{3}}$$

the voltage error V_{CR} at the n^{th} sampling instant $V_{er}(n) = V_{ref}(n) - V_m(n)$ The output of PID controller at the n^{th} instant is expressed as $I^*_{smq}(n) = I^*_{smq}(n-1) + K_p(V_{cr}(n) - V_{cr}(n-1)) + K_i V_{cr}(n)$ Where K_p and K_i are proportional and integral constant

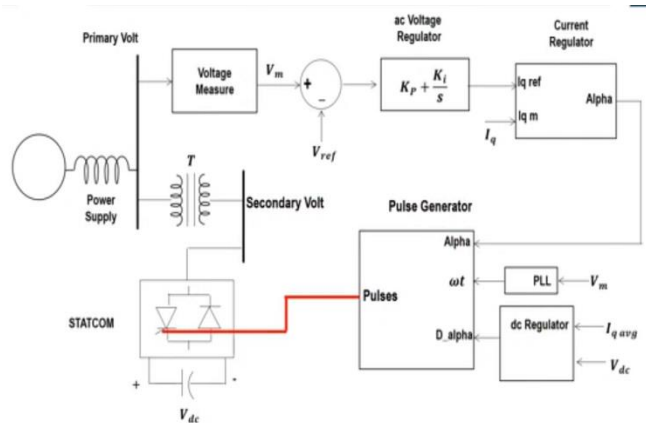


Figure 1.2 Control Scheme of STATCOM

From the power supply the voltage is measured and this voltage is compared with V_{ref} and an error signal is produced, this error signal is passed through ac voltage regulator where PI controller is used. After that the control signal is produced and it is passed through Current Regulator and this signal is compared with I_{ref} and after that alpha signal is produced and which is passed through Pulse Generator. And after that the pulses are given to the STATCOM.

IV. OPERATIONAL SCHEME IN GRID SYSTEM

This is the operational scheme in Grid System. Generator is connected to the non-linear load through grid. In the grid wind generator is integrated at the PCC. The STATCOM is connected to the grid which injects reactive power to the system.

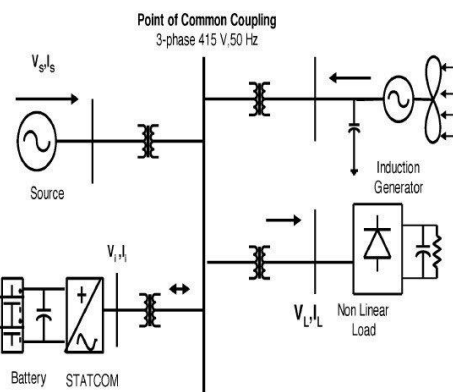


Figure 1.3 Operational Scheme in Grid System

V. MATLAB SIMULINK MODEL OF THE SYSTEM

The figure shows MATLAB Simulink model of the system. The STATCOM can supply as well as absorb the reactive power in accordance with the voltage of the grid. In the conventional control scheme of STATCOM PI controller is used in voltage regulator block. In this research work fuzzy control scheme is used to further enhance the power quality.

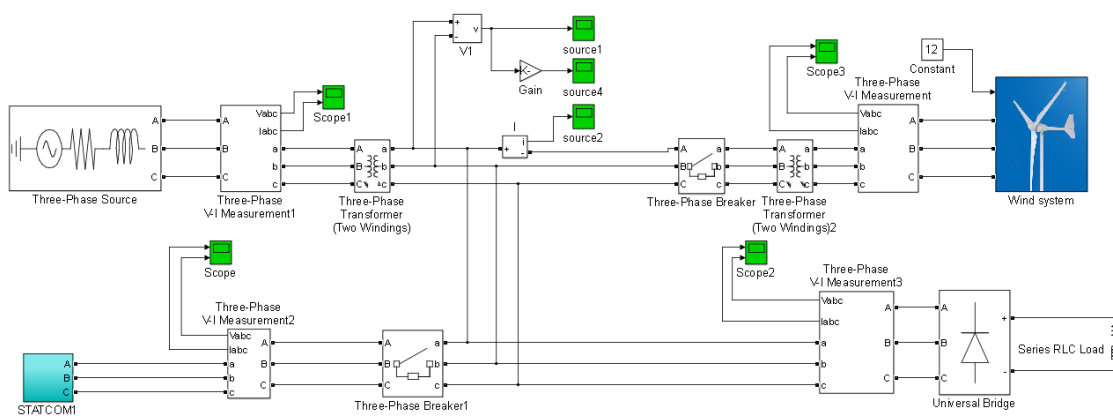


Figure 1.4 MATLAB Simulink Model of the system

Fuzzy Rule base

This is the fuzzy rule base that is used in this thesis

Δe					
e	NB	NS	Z	PS	PB
NB	NB	NB	NS	NS	Z
NS	NB	NS	NS	Z	PS
Z	NS	NS	Z	PS	PS
PS	NS	Z	PS	PS	PB
PB	Z	PS	PS	PB	PB

VI. SIMULATION RESULTS WITHOUT STATCOM

Voltage and current waveform at PCC

As the non-linear load and induction generator is connected so it will absorb reactive power. The nonlinear load injects harmonics in the system. From the waveform we can see the distorted waveform, this is basically due to the harmonics injected in the system. From the waveform the voltage output is coming as 0.78 pu which results in poor voltage regulation. The voltage regulation is calculated as 21.31%.

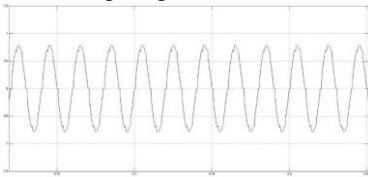


Figure 1.7 Voltage waveform at PCC

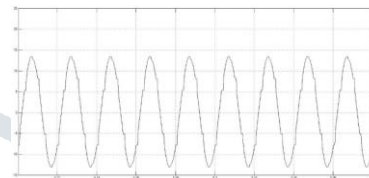


Figure 1.8 Current Waveform at PCC

FFT analysis of waveform at PCC

FFT analysis of voltage and current waveform is done in FFT window. The total harmonic distortion in voltage waveform is calculated as 6.18%. The THD in current waveform is calculated as 6.14%

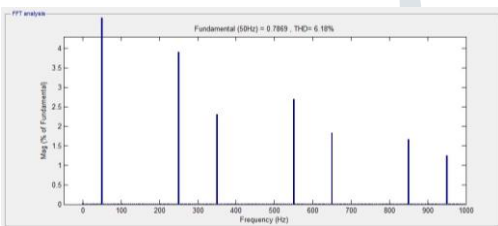


Figure 1.9 FFT analysis of voltage waveform at PCC

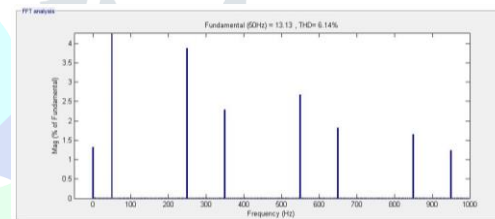


Figure 1.10 FFT analysis of current waveform at PCC

VII. SIMULATION RESULTS WITH CONVENTIONAL CONTROLLER IN STATCOM

Voltage Waveform at PCC

The STATCOM is connected at the PCC. The STATCOM injects the reactive power into the system and improves the voltage profile of the system. The following waveform shows the impact of STATCOM when it is connected. It reduces the harmonics in the system and makes the waveform smooth. The voltage regulation is also improved. The voltage regulation is calculated as -2.3%. Thus power quality of the system is improved.

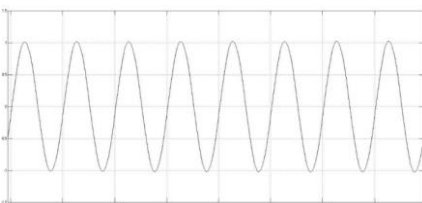


Figure 1.11 Voltage Waveform at PCC

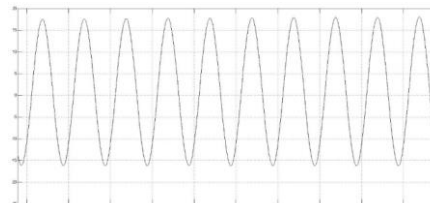


Figure 1.12 Current Waveform at PCC

STATCOM injecting current

The following waveform shows how STATCOM is injecting current into the system.

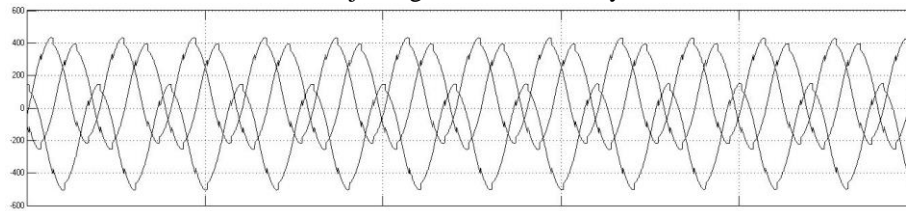


Figure 1.13 STATCOM injecting current

FFT analysis of the Voltage and Current Waveform at PCC

FFT analysis of the voltage waveform is done at PCC. The THD in voltage waveform is obtained as .81%. The THD in current waveform is obtained as .83%. So the harmonics are reduced by the application of the STATCOM.

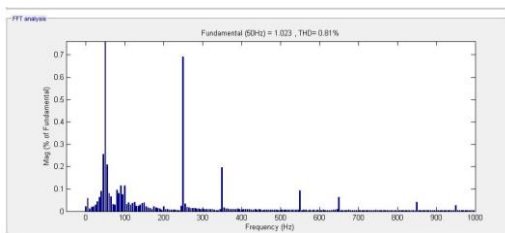


Figure 1.14 FFT analysis of the Voltage Waveform

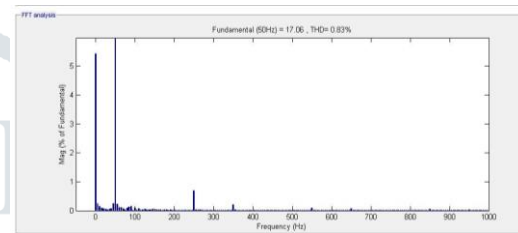


Figure 1.15 FFT analysis of the Current Waveform

VIII. RESULTS WITH FUZZY CONTROLLER WITH TRIANGULAR MF

Voltage Waveform at PCC

Now fuzzy control scheme is applied in STATCOM and different Membership functions are used. The following waveform shows the voltage waveform at PCC when triangular MF is used.

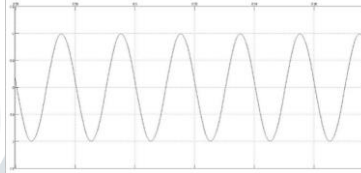


Figure 1.16 Voltage Waveform at PCC

8.6.2 FFT analysis of voltage and current waveform at PCC

FFT analysis of the voltage and current waveform is done. The THD in voltage waveform comes out to be .63% which is reduced when compared with the conventional scheme. The THD in current waveform is obtained as .64%. The voltage regulation is calculated as .57% which is further improved.

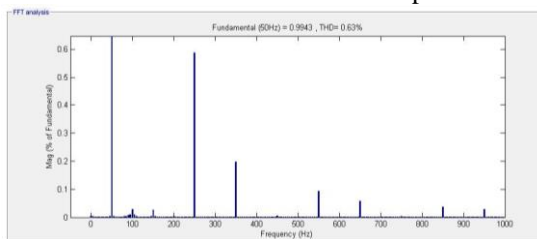


Figure 8. 1 FFT analysis of voltage waveform

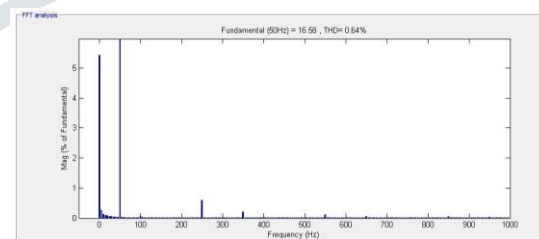


Figure FFT analysis of current waveform

IX. COMPARISON

	%THD in voltage waveform	%THD in current waveform	V _{pcc} (pu)	% Voltage Regulation
Without STATCOM	6.18%	6.14%	.7869	21.31%.
PI controller	.81%	.83%	1.023	-2.3%
Triangular MF	.63%	.64%	.9943	.57%

X. CONCLUSION

Without the use of STATCOM the total harmonic distortion is calculated as 6.18%. With the use of STATCOM with conventional control scheme the total harmonic distortion is calculated as .81%. From this we can say that the harmonics are reduced by the use of STATCOM. We get the smooth waveform which is nearly same as sinusoidal. With the use of fuzzy

controller in STATCOM control scheme the total harmonic distortion is calculated as .63%. From this analysis we can say that the performance is further improved by the use of fuzzy control scheme in STATCOM. The power quality of the system is improved.

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