# Inverse Aboodh Transform of some standard functions and properties with Applications in ODE 

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#### Abstract

In this paper we study the definition of inverse Aboodh transform. We also study the inverse Aboodh transform of some standard functions .Further, we establish and prove some important properties related to inverse Aboodh transform. In addition, we establish application of inverse Aboodh transform to find particular solution of first and second order linear ordinary differential equations.


Keywords-Inverse Aboodh transform, Linearity, Change of scale, Effect of multiplication.

## 1. Introduction

Aboodh Transform was introduced by Khalid Suliman Aboodh in 2013 from classical Fourier integral. Aboodh transform is defined for function of exponential order by

$$
A\{f(t)\}=\frac{1}{v} \int_{0}^{\infty} f(t) e^{-v t} d t, \quad t \geq 0, k_{1} \leq v \leq k_{2}
$$

where $f(t)$ is a function from the set of the form $A=\left\{f(t): \ni M, k_{1}, k_{2}>0,|f(t)|<M e^{-v t}\right\}$.[1]
One of the most importance of transforms is solving ordinary differential equations, partial differenatial equations, linear volterra integro-differential equations etc. Aboodh transform is useful in solving ordinary differential equations, partial differenatial equations equations [2] which gives rise to make use of inverse Aboodh transform. Aboodh transform is also useful for solving solving fourth order parabolic PDE with variable coefficients [3]. The higher versions of Aboodh Transform such as double aboodh transform, triple aboodh transform are already established [8,9]. In addition to it several theorems and properties related to them are also verified. Moreover applications of these higher versions of aboodh transforms to solve integral, partial and fractional differential equations are also discussed[2,4,7,8,9,10].

In this article we introduce An Inverse Aboodh Transform in a different and more simpler way. We also prove some important properties for Inverse Aboodh Transform using some basic properties of Aboodh transform. We also illustrate use of Inverse Aboodh Transform in solving first and second order linear differential equations.

## 2. PRELIMINARIES

In this section, we study the definition of inverse aboodh transform.
Definition If $F(t)$ is piecewise continuous and of exponential order for $t \geq 0$ such that $A\{F(t)\}=f(v)$ then $F(t)$ is called inverse Aboodh transform of $f(v)$ and we write

$$
A^{-1}\{f(v)\}=F(t)
$$

## 3. INVERSE ABOODH TRANSFORM OF SOME STANDARD FUNCTIONS

In this section, we present the inverse Aboodh transform of some standard functions.
a) $A^{-1}\left\{\frac{1}{v^{2}}\right\}=1$,
b) $A^{-1}\left\{\frac{1}{v^{3}}\right\}=t$,

In general, we can define

$$
A^{-1}\left\{\frac{1}{v^{n+2}}\right\}=\frac{t^{n}}{n!}, n=0,1,2, \ldots
$$

Explanation:-
As we know, [1] $A\left\{\frac{t^{n}}{n!}\right\}=\frac{1}{n!} A\left\{t^{n}\right\}$

$$
=\frac{1}{n!} \frac{n!}{v^{n+2}}
$$

$$
=\frac{1}{v^{n+2}}
$$

Thus, $A^{-1}\left\{\frac{1}{v^{n+2}}\right\}=\frac{t^{n}}{n!}, n=0,1,2, \ldots$
Alternatively, we can also prove it in following manner

$$
\begin{aligned}
{[1] A\left\{\frac{t^{n}}{n!}\right\} } & =\frac{1}{v} \int_{0}^{\infty} \frac{t^{n}}{n!} e^{-v t} d t \\
& =\frac{1}{n!}\left\{\frac{1}{v} \int_{0}^{\infty} t^{n} e^{-v t} d t\right\} \\
& =\frac{1}{n!} A\left\{t^{n}\right\}=\frac{1}{v^{n+2}} .
\end{aligned}
$$

Thus, $A^{-1}\left\{\frac{1}{v^{n+2}}\right\}=\frac{t^{n}}{n!}, n=0,1,2, \ldots$
c) $A^{-1}\left\{\frac{1}{v(v-a)}\right\}=A^{-1}\left\{\frac{1}{v^{2}-a v}\right\}=e^{a t}$
d) $A^{-1}\left\{\frac{1}{v\left(v^{2}+a^{2}\right)}\right\}=\frac{1}{a}$ sinat

Explanation:
Consider,

$$
\begin{aligned}
{[1] A\left\{\frac{1}{a} \sin a t\right\} } & =\frac{1}{a} A\{\sin a t\} \\
& =\frac{1}{a} \frac{a}{v\left(v^{2}+a^{2}\right)} \\
& =\frac{1}{v\left(v^{2}+a^{2}\right)} \\
\therefore A\left\{\frac{1}{a} \sin a t\right\} & =\frac{1}{v\left(v^{2}+a^{2}\right)} \\
\Rightarrow A^{-1}\left\{\frac{1}{v\left(v^{2}+a^{2}\right)}\right\} & =\frac{1}{a} \sin a t
\end{aligned}
$$

e) $A^{-1}\left\{\frac{1}{\left(v^{2}+a^{2}\right)}\right\}=$ cosat
f) $A^{-1}\left\{\frac{1}{v\left(v^{2}-a^{2}\right)}\right\}=\frac{1}{a} \sinh a t$

Explanation:
Consider,

$$
\text { [1] } \begin{aligned}
A\left\{\frac{1}{a} \sinh a t\right\} & =\frac{1}{a} A\{\sinh a t\} \\
& =\frac{1}{a} \frac{a}{v\left(v^{2}-a^{2}\right)} \\
& =\frac{1}{v\left(v^{2}-a^{2}\right)} \\
\therefore A\left\{\frac{1}{a} \sin a t\right\} & =\frac{1}{v\left(v^{2}-a^{2}\right)} \\
\Rightarrow A^{-1}\left\{\frac{1}{v\left(v^{2}-a^{2}\right)}\right\} & =\frac{1}{a} \sinh a t
\end{aligned}
$$

g) $A^{-1}\left\{\frac{1}{\left(v^{2}-a^{2}\right)}\right\}=$ coshat

Thus we can summarize this in tabular form as

| Function | Inverse Aboodh Transform |
| :---: | :---: |
| $\frac{1}{v^{2}}$ | 1 |
| $\frac{1}{v^{n+2}}$ | $\frac{t^{n}}{n!}, n=0,1,2, \ldots$ |
| $\frac{1}{v(v-a)}$ | $e^{a t}$ |
| $\frac{1}{v\left(v^{2}+a^{2}\right)}$ | $\frac{1}{a} \operatorname{sinat}$ |
| $\frac{1}{\left(v^{2}+a^{2}\right)}$ | $\cos a t$ |
| $\frac{1}{v\left(v^{2}-a^{2}\right)}$ | $\frac{1}{a} \operatorname{sinhat}$ |
| $\frac{1}{\left(v^{2}-a^{2}\right)}$ | $\operatorname{coshat}$ |

## 4. PROPERTIES OF INVERSE ABOODH TRANSFORM

In this section we discuss some properties of inverse Aboodh transform.

### 4.1 Linearity Property

If $f_{1}(v)$ and $f_{2}(v)$ are two functions such that $A^{-1}\left\{f_{1}(v)\right\}$ and $A^{-1}\left\{f_{2}(v)\right\}$ exists and $c_{1}, c_{2}$ are arbitrary constants then $A^{-1}\left\{c_{1} f_{1}(v)+c_{2} f_{2}(v)\right\}=c_{1} A^{-1}\left\{f_{1}(v)\right\}+c_{2} A^{-1}\left\{f_{2}(v)\right\}$

Proof: Suppose, $A^{-1}\left\{f_{1}(v)\right\}=F_{1}(t)$

$$
A^{-1}\left\{f_{2}(v)\right\}=F_{2}(t)
$$

Then, $A\left\{F_{1}(t)\right\}=f_{1}(v)$ and $A\left\{F_{2}(t)\right\}=f_{2}(v)$
For constants $c_{1}$ and $c_{2}$,
[1]By linearity property of Aboodh transform, we have

$$
A\left\{c_{1} F_{1}(t)+c_{2} F_{2}(t)\right\}=c_{1} A\left\{F_{1}(t)\right\}+c_{2} A\left\{F_{2}(t)\right\}
$$

$$
=c_{1} f_{1}(v)+c_{2} f_{2}(v)
$$

Thus, $A^{-1}\left\{c_{1} f_{1}(v)+c_{2} f_{2}(v)\right\}=c_{1} F_{1}(t)+c_{2} F_{2}(t)$

$$
=c_{1} A^{-1}\left\{f_{1}(v)\right\}+c_{2} A^{-1}\left\{f_{2}(v)\right\}
$$

## Generalization:

The Linearity property can be generalized for $n$-functions $f_{i}(v), i=1,2, \ldots, n$ whose inverse Aboodh transform exists as follows

$$
A^{-1}\left\{\sum_{i=1}^{n} c_{i} f_{i}(v)\right\}=\sum_{i=1}^{n} c_{i} A^{-1}\left\{f_{i}(v)\right\}
$$

## Remark:

If we substitute $c_{2}=0$ in Linearity property,

$$
A^{-1}\left\{c_{1} f_{1}(v)+c_{2} f_{2}(v)\right\}=c_{1} A^{-1}\left\{f_{1}(v)\right\}+c_{2} A^{-1}\left\{f_{2}(v)\right\}
$$

We get,

$$
A^{-1}\left\{c_{1} f_{1}(v)\right\}=c_{1} A^{-1}\left\{f_{1}(v)\right\}
$$

Thus, we can conclude that "Any constant multiplier can be taken out while finding an inverse Aboodh transform".

### 4.2 Change of scale property

If $A^{-1}\{f(v)\}=F(t)$ then $A^{-1}\{f(a v)\}=\frac{1}{a^{2}} F\left(\frac{t}{a}\right)$
Proof: As $A^{-1}\{f(v)\}=F(t)$,

$$
\begin{aligned}
& \Rightarrow f(v)=A\{F(t)\} \\
& \therefore f(v)=\frac{1}{v} \int_{0}^{\infty} F(t) e^{-v t} d t
\end{aligned}
$$

Thus,
$f(a v)=\frac{1}{a v} \int_{0}^{\infty} F(t) e^{-a v t} d t$

$$
=\frac{1}{a v} \int_{0}^{\infty} F(t) e^{-(a t) v} d t
$$

Put, $a t=u \Rightarrow a d t=d u$

$$
\Rightarrow d t=\frac{d u}{a}
$$

$\therefore f(a v)=\frac{1}{a v} \int_{0}^{\infty} F(t) e^{-a v t} d t=\frac{1}{a v} \int_{0}^{\infty} e^{-u v} F\left(\frac{u}{a}\right) \frac{d u}{a}$

$$
=\frac{1}{a^{2}} \frac{1}{v} \int_{0}^{\infty} e^{-u v} F\left(\frac{u}{a}\right) d u
$$

Replacing $u$ by $t$, we have

$$
=\frac{1}{a^{2}} \frac{1}{v} \int_{0}^{\infty} e^{-v t} F\left(\frac{t}{a}\right) d t
$$

Thus, [1]

$$
f(a v)=\frac{1}{a^{2}} A\left\{F\left(\frac{t}{a}\right)\right\}
$$

Applying inverse Aboodh transform on both sides,

$$
\begin{aligned}
A^{-1}\{f(a v)\} & =A^{-1}\left\{\frac{1}{a^{2}} A\left\{F\left(\frac{t}{a}\right)\right\}\right\} \\
& =\frac{1}{a^{2}} A^{-1}\left[A\left\{F\left(\frac{t}{a}\right)\right\}\right] \\
A^{-1}\{f(a v)\} & =\frac{1}{a^{2}} F\left(\frac{t}{a}\right)
\end{aligned}
$$

### 4.3 Effect of multiplication by $\boldsymbol{e}^{-a v}$

If $A^{-1}\{f(v)\}=F(t)$ then, $A^{-1}\left\{e^{-a v} f(v)\right\}=\left\{\begin{array}{r}F(t-a), \quad t>a \\ 0, \quad t<a\end{array}\right.$
Proof: Consider, $A^{-1}\{f(v)\}=F(t)$

$$
\begin{aligned}
{[1] \Rightarrow f(v) } & =A\{F(t)\} \\
& =\frac{1}{v} \int_{0}^{\infty} e^{-v t} F(t) d t \\
\therefore f(v) & =\frac{1}{v} \int_{0}^{\infty} e^{-v t} F(t) d t \\
\Rightarrow & e^{-a v} f(v)=e^{-a v} \frac{1}{v} \int_{0}^{\infty} e^{-v t} F(t) d t \\
\Rightarrow & e^{-a v} f(v)=\frac{1}{v} \int_{0}^{\infty} e^{-(a+t) v} F(t) d t
\end{aligned}
$$

Substitute, $t+a=u \Rightarrow d t=d u$
Thus,

$$
\begin{aligned}
e^{-a v} f(v) & =\frac{1}{v} \int_{a}^{\infty} e^{-u v} F(u-a) d u \\
& =\frac{1}{v} \int_{0}^{a} e^{-u v} 0 d u+\frac{1}{v} \int_{a}^{\infty} e^{-u v} F(u-a) d u
\end{aligned}
$$

Replace $u$ by $t$, gives

$$
\begin{aligned}
e^{-a v} f(v) & =\frac{1}{v} \int_{0}^{a} e^{-v t} 0 d t+\frac{1}{v} \int_{a}^{\infty} e^{-v t} F(t-a) d t \\
& =\frac{1}{v} \int_{0}^{\infty} G(t) e^{-v t} d t
\end{aligned}
$$

Where, $G(t)=\left\{\begin{array}{r}F(t-a), \quad t>a \\ 0, \quad t<a\end{array}\right.$
Thus, $\quad e^{-a v} f(v)=A\{G(t)\}$
$\Rightarrow A^{-1}\left\{e^{-a v} f(v)\right\}=G(t)=\left\{\begin{array}{rr}F(t-a), & t>a \\ 0, & t<a\end{array}\right.$

### 4.4 Effect of multiplication by $v$

If $A^{-1}\{f(v)\}=F(t)$ and $F(0)=0$ then $A^{-1}\{v f(v)\}=F^{\prime}(t)$.
In other words, the effect of multiplication by $v$ to $f(v)$ is equivalent to differentiation of $F(t)$ provided $F(0)=0$.

$$
\begin{aligned}
\text { Proof: Let, } A^{-1}\{f(v)\} & =F(t), F(0)=0 \\
\Rightarrow A\{F(t)\} & =f(v) .
\end{aligned}
$$

We know, [1] $A\left\{F^{\prime}(t)\right\}=v A\{F(t)\}-\frac{F(0)}{v}$

$$
=v A\{F(t)\}-0\{\because F(0)=0\}
$$

$$
\therefore A\left\{F^{\prime}(t)\right\}=v f(v)
$$

Hence,

$$
A^{-1}\{v f(v)\}=F^{\prime}(t)
$$

### 4.5 Effect of multiplication by $\boldsymbol{v}^{\boldsymbol{n}}$

The repeated multiplication by $v$ to $f(v)$ together with the assumption that $F(0)=F^{\prime}(0)=\cdots=F^{(n-1)}(0)=0$ leads to the result

$$
A^{-1}\left\{v^{n} f(v)\right\}=F^{(n)}(t)
$$

Proof: We know,

$$
\begin{aligned}
& \text { [1] } A\left\{F^{(n)}(t)\right\}=v^{n} A\{F(t)\}-\sum_{k=0}^{n-1} \frac{F^{(k)}(0)}{v^{2-n+k}} \\
& \Rightarrow A\left\{F^{(n)}(t)\right\}=v^{n} A\{F(t)\} \text { with assumption that } F(0)=F^{\prime}(0)=\cdots=F^{(n-1)}(0)=0 \\
&=v^{n} f(v) \\
& \text { Thus, }
\end{aligned}
$$

$A^{-1}\left\{v^{n} f(v)\right\}=F^{(n)}(t)$ provided $F(0)=F^{\prime}(0)=\cdots=F^{(n-1)}(0)=0$

## 5 Examples

1. $A^{-1}\left\{\frac{e^{-\pi v}}{v^{2}+9}\right\}$

Solution: Let, $f(v)=\frac{1}{v^{2}+9}$
Then,

$$
\begin{aligned}
A^{-1}\{f(v)\} & =A^{-1}\left\{\frac{1}{v^{2}+9}\right\} \\
& =\cos 3 t=F(t)
\end{aligned}
$$

$\begin{aligned} \therefore A^{-1}\left\{e^{-\pi v} \frac{1}{v^{2}+9}\right\} & =A^{-1}\left\{e^{-\pi v} f(v)\right\} \\ & =G(t) \\ & =\left\{\begin{array}{rr}F(t-\pi), & t>\pi \\ 0, & t<\pi\end{array}\right.\end{aligned}$

$$
A^{-1}\left\{\frac{e^{-\pi v}}{v^{2}+9}\right\}=\left\{\begin{aligned}
\cos 3(t-\pi), & t>\pi \\
0, & t<\pi
\end{aligned}\right.
$$

2. $A^{-1}\left\{\frac{1}{(a v)^{n+2}}\right\}$

Solution: We know, $A^{-1}\left\{\frac{1}{v^{n+2}}\right\}=\frac{t^{n}}{n!}, n=0,1,2, \ldots$

$$
\text { Then, } \quad \begin{aligned}
A^{-1}\left\{\frac{1}{(a v)^{n+2}}\right\} & =\frac{1}{a^{2}} \frac{\left(\frac{t}{a}\right)^{n}}{n!} \\
& =\frac{1}{a^{n+2}} \frac{t^{n}}{n!}, n=0,1,2, \ldots
\end{aligned}
$$

3. $A^{-1}\left\{v^{k} \frac{1}{v^{n+2}}\right\}, k \leq n$

Solution: Consider,

$$
\begin{aligned}
f(v) & =\frac{1}{v^{n+2}} \\
A^{-1}\{f(v)\} & =\frac{t^{n}}{n!}, n=0,1,2, \ldots
\end{aligned}
$$

Clearly, $F(t)=\frac{t^{n}}{n!}$, has $F(0)=F^{\prime}(0)=\cdots=F^{(n-1)}(0)=0$
Hence, $A^{-1}\{v f(v)\}=F^{\prime}(t)$

$$
\begin{aligned}
& A^{-1}\left\{v^{2} f(v)\right\}=F^{\prime \prime}(t) \text { and so on } \\
& A^{-1}\left\{v^{k} f(v)\right\}=F^{k}(t)
\end{aligned}
$$

Therefore,

$$
A^{-1}\left\{v^{k} \frac{1}{v^{n+2}}\right\}=F^{k}(t), k \leq n
$$

## 6. Applications of Inverse Aboodh transform

Inverse Aboodh transform is useful in obtaining the particular solutions of first and second order linear ordinary differential equations.
6.1 Consider Initial value problem

$$
\frac{d^{2} y}{d t^{2}}+y=0, y(0)=1, y^{\prime}(0)=0
$$

To obtain the solution of this O.D.E.
Apply Aboodh transform on both sides, gives

$$
\begin{aligned}
& A\left\{y^{\prime \prime}(t)\right\}+A\{y(t)\}=0 \\
{[1] } & \Rightarrow v^{2} A\{y(t)\}-\frac{y^{\prime}(0)}{v}-y(0)+A\{y(t)\}=0 \\
& \Rightarrow\left(v^{2}+1\right) A\{y(t)\}-1=0 \\
& \Rightarrow A\{y(t)\}=\frac{1}{v^{2}+1}
\end{aligned}
$$

Applying inverse Aboodh transform on both sides, gives

$$
y(t)=A^{-1}\left\{\frac{1}{v^{2}+1}\right\}=\cos t
$$

Thus the solution to I.V.P. is $y(t)=$ cost .
6.2 Consider Initial value problem

$$
\frac{d^{2} y}{d t^{2}}-y=6, y(0)=1, y^{\prime}(0)=0
$$

To obtain the solution of this O.D.E.
Apply Aboodh transform on both sides, gives

$$
\begin{aligned}
& {[1] A\left\{y^{\prime \prime}(t)\right\}-A\{y(t)\}=6} \\
& \Rightarrow v^{2} A\{y(t)\}-\frac{y^{\prime}(0)}{v}-y(0)+A\{y(t)\}=6 \\
& \Rightarrow\left(v^{2}-1\right) A\{y(t)\}-1=6 \\
& \Rightarrow\left(v^{2}-1\right) A\{y(t)\}=7 \\
& \Rightarrow A\{y(t)\}=\frac{7}{v^{2}-1}
\end{aligned}
$$

Applying inverse Aboodh transform on both sides, gives

$$
y(t)=7 A^{-1}\left\{\frac{1}{v^{2}-1}\right\}=7 \cosh t
$$

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