

# BATTLE HUMANOID

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## ABSTRACT

This imaginative framework is made for tasks which include high hazard for people to enter, particularly for some criminal case and may demonstrate extremely advantageous for military zone for spying purposes. This framework makes utilizes automated vehicle which encourages not exclusively to enter a region including high hazard yet in addition it is outfitted with laser firearm to shoot down the adversaries when required. The framework additionally incorporates remote camera transmitter which is equipped for gushing the video caught by the robot remotely to the remote DVR which can be associated with typical TV for review.

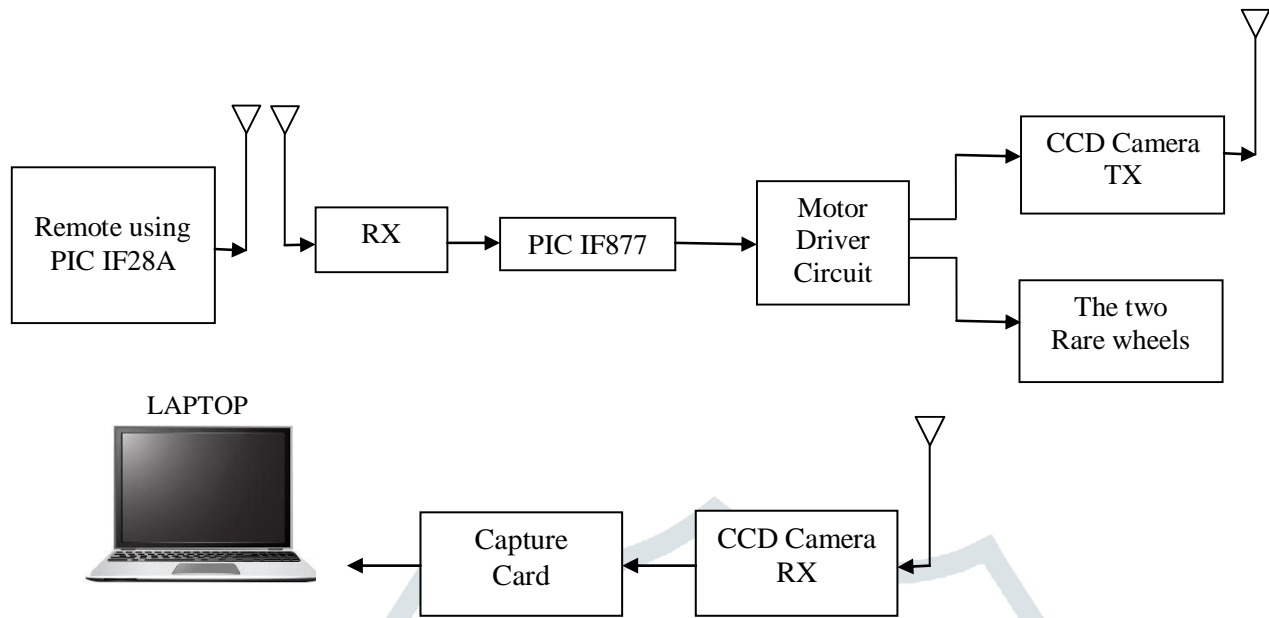
The entire framework is controlled by means of signal in a remote spot and subsequently by development of the hand towards forward, left and right activity robot development can be controlled. The transmitter framework sends directions to the getting circuit mounted on the automated vehicle through RF Transmitter set in the remote end. The accepting circuit includes ARDUINO and a RF recipient which gets directions sent remotely to control the development of the mechanical module and to control the shooting activity of the laser weapon.

## INTRODUCTION

The advancement in innovation is constantly developing the world over on the road to success, of which one factor is Robotics. Apply autonomy is an amalgam of PC, electrical and mechanical designing, to be exact a mix of programming, interfacing, engines and incorporated chips. The historical background of the term mechanical autonomy originates from the word robot, and the term robot discovers its foundations from the Czech word 'Robota' which means constrained work or bondage. A humanoid is a machine which Performs capacities practically equivalent to human, however under human direction for example according to direction from his proprietor. There are three laws of apply autonomy additionally named as Asimov's Laws. Those three laws can be expressed as pursues:

1. A robot is restricted from injuring human being as well as through inaction, all human being to falling into dangerous situations.
2. A robot is relied upon to obey and pursue every single direction given by person yet under a condition which won't struggle the main law.
3. A robot needs to extend himself for example it ought to be sharp in self defending, regarding the First and the Second law Robots are bifurcated.

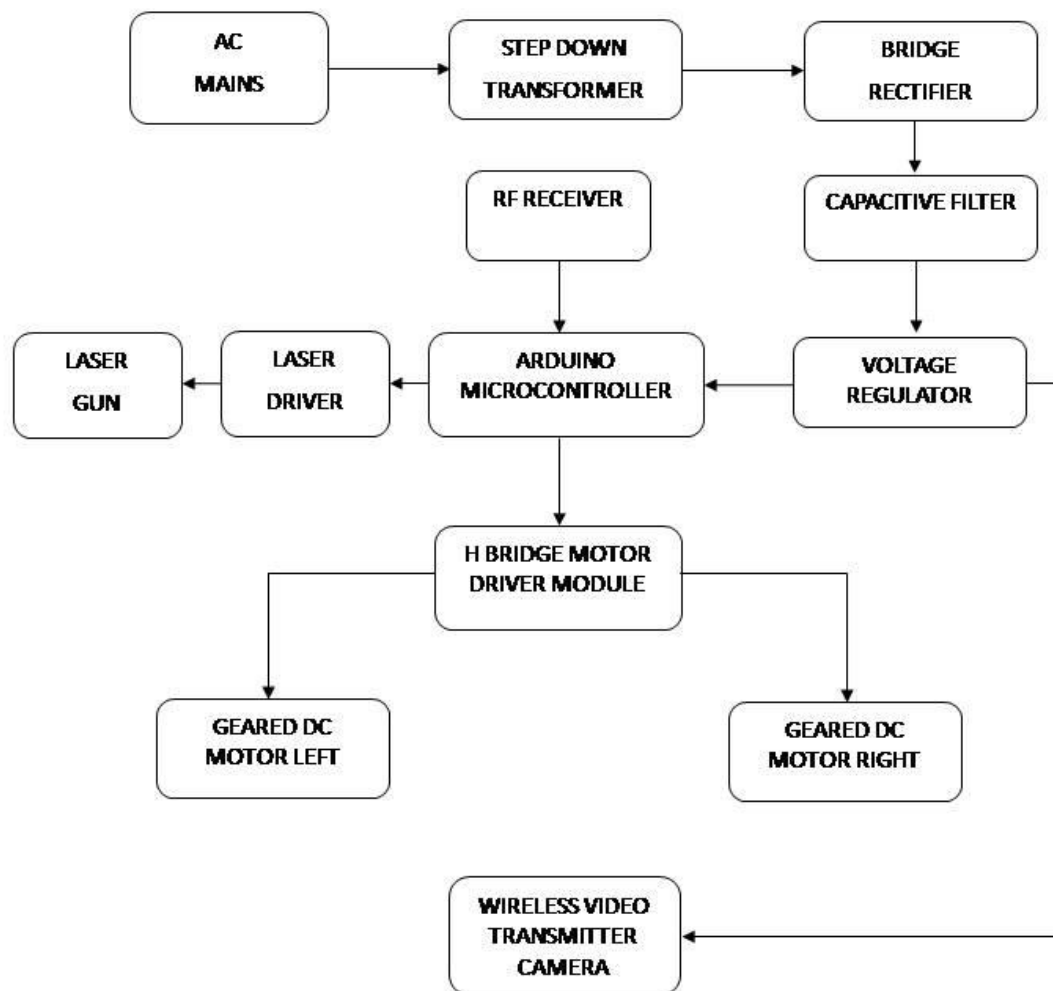
## EXISTING SYSTEM



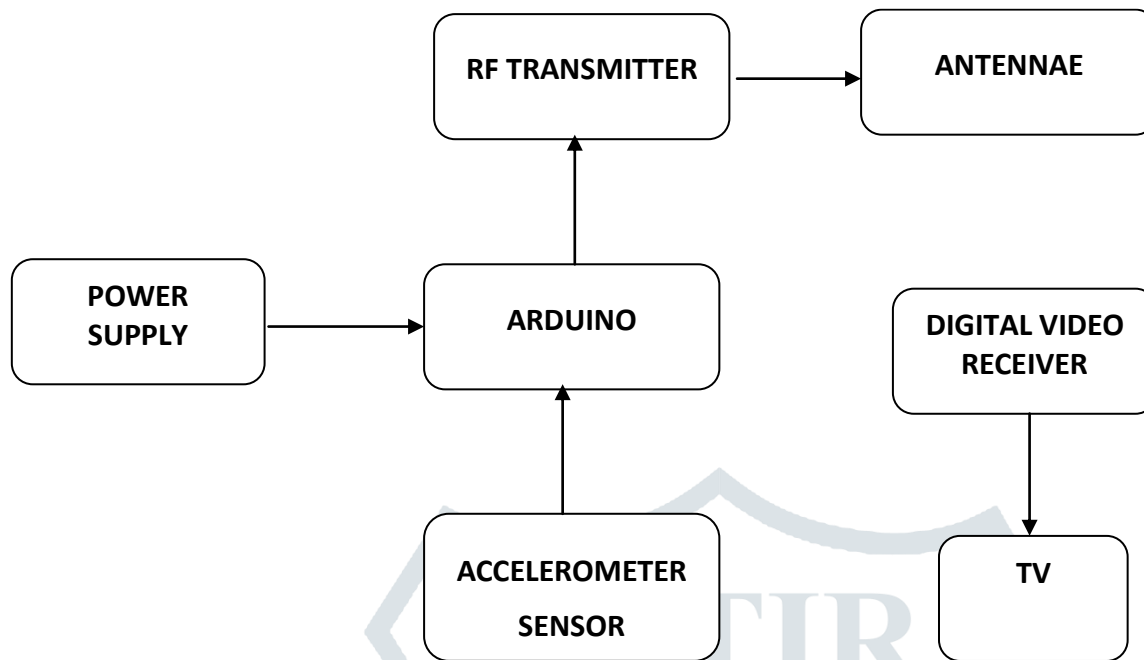
By and by, it is generally an electro-mechanical machine which is guided by PC or workstation, portable or electronic programming, and is in this way ready to do assignments all alone. Remote controlled robots use RF circuits which have downsides of constrained working reach, recurrence range and restricted control. Spy robot can catch sound and video data from the environment and can be sending to a remote station through RF signal. The control of robot includes three unmistakable stages: discernment, preparing and activity. For the most part, the preceptors are sensors mounted on the robot, preparing is finished by the on-board microcontroller or processor, and the undertaking is performed utilizing engines or with some different actuators. At the point when the client controls by remote controller, the government operative robot will move to wanted goal and spy pictures around the robot in this task. This robot isn't exactly colossal one and intended to be simple transportation.

# PROPOSED SYSTEM

## RECEIVER SECTION

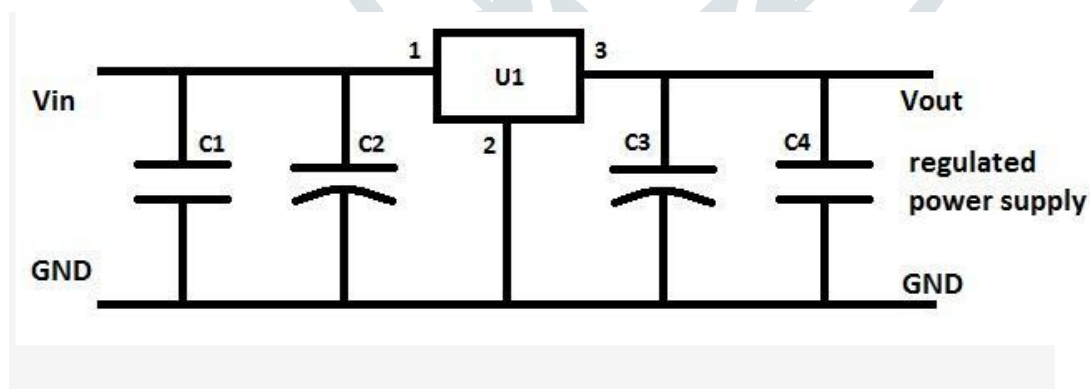


## TRANSMITTER SECTION



### I. VOLTAGE REGULATOR

The controlled power supply is progressively basic for some electronic gadgets due to the semiconductor material inbuilt in them will have a fixed pace of current just as voltage. Quite possibly the gadget may get crushed if there is any progressions from the genuine rate. The info AC power supply will get changed over into steady DC current by this circuit. With the assistance of a voltage controller DC, the unregulated yield will be relegated to a consistent voltage. The circuit is developed of direct voltage controller 7805 what's more with capacitors and resistors alongside connect rectifier made up of diodes. From sending a constant voltage supply the yield arrives at continuous to the gadget, the diodes moreover with capacitors handle raised proficient sign transport.



### II.MECHANICAL SENSOR

The ADXL335 utilizes a solitary structure for detecting the X, Y, and Z tomahawks. Therefore, the three tomahawks sense headings are exceptionally symmetrical and have minimal cross-pivot sensitivity. Mechanical misalignment of the sensor kick the bucket to the bundle is the main wellspring of cross-hub sensitivity. Mechanical misalignment can, obviously, be adjusted out at the framework level.

### III. ARDUINO

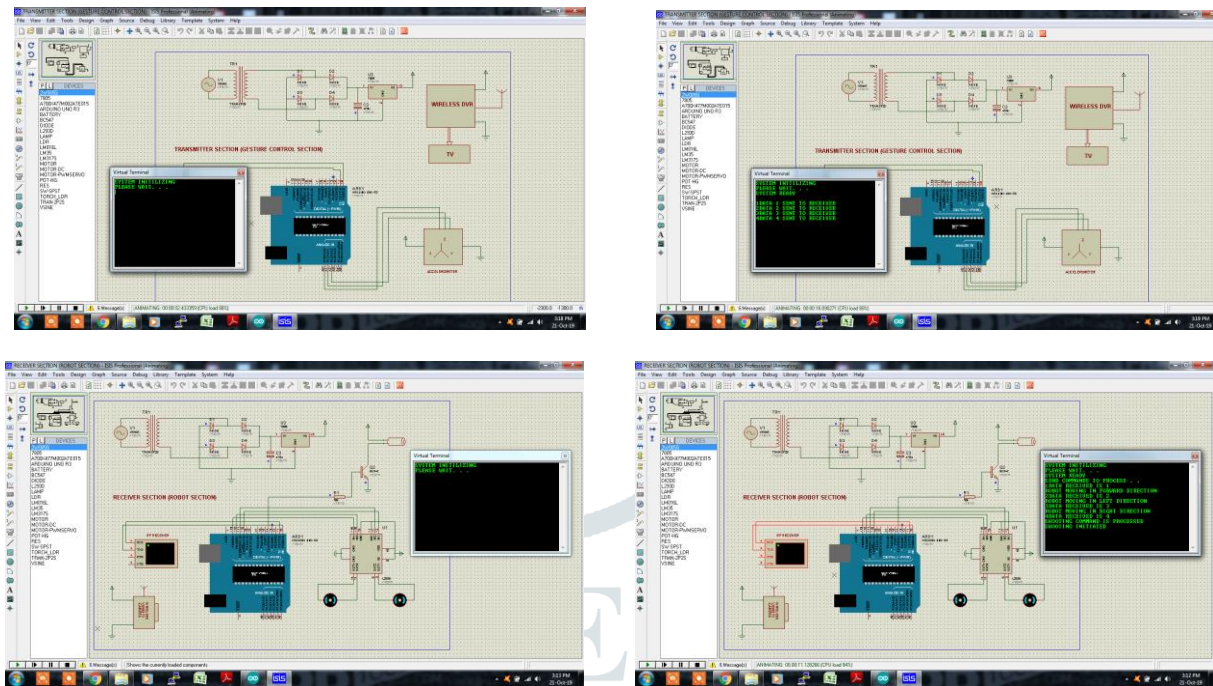
Arduino is an open-source venture that made microcontroller-based packs for building computerized gadgets and intuitive articles that can detect and control physical gadgets. The task depends on microcontroller board plans, delivered by a few sellers, utilizing different microcontrollers. These frameworks give sets of computerized and simple info/yield (I/O) sticks that can interface to different development sheets (named shields) and different circuits. The sheets highlight sequential correspondence interfaces, including Universal Serial Bus (USB) on certain models, for stacking programs from PCs. For programming the microcontrollers, the Arduino venture gives a coordinated improvement condition (IDE) in view of a programming language named Processing, which additionally underpins the dialects C and C++. Arduino Uno is a microcontroller board dependent on the ATmega328P. It has 14 advanced info/yield pins (of which 6 can be utilized as PWM yields), 6 simple information sources, a 16 MHz quartz gem, a USB association, a power jack, an ICSP header and a reset catch. It contains everything expected to help the microcontroller; just interface it to a PC with a USB link or power it with an AC-to-DC connector. Arduino Uno has various offices for speaking with a PC, another Arduino board, or different microcontrollers.

### IV. RF TRANSMITTER AND RECEIVER

A RF transmitter module (HT12E) is equipped for transmitting a radio wave and balancing that wave to convey information. A RF recipient module (HT12D) gets the adjusted RF signal and demodulates it. This remote correspondence is done through Radio Frequency (RF) correspondence. A RF transmitter module is a little PCB sub-get together fit for transmitting a radio wave and regulating that wave to convey information. Transmitter modules are typically actualized close by a smaller scale controller which will give information to the module which can be transmitted. RF transmitters are typically dependent upon administrative prerequisites which direct the greatest permissible transmitter power yield, music, and band edge necessities. A RF collector module gets the regulated RF signal, and demodulates it. There are two kinds of RF collector modules: too heterodyne beneficiaries and super-regenerative recipients. Super-regenerative modules are typically ease and low power structures utilizing a progression of enhancers to concentrate adjusted information from a bearer wave.

Super-regenerative modules are commonly loose as their recurrence of activity changes significantly with temperature and power supply voltage. Excessively heterodyne collectors have a presentation advantage over super-regenerative, they offer expanded precision and dependability over an enormous voltage and temperature.

## RESULT



## FUTURE WORKS

The future work of the Battle humanoid can be of Hardware execution with equipment segments which incorporates two areas specifically Transmitter and the collector section. The transmitter segment works with the assistance of motion direction and will make the beneficiary to react as needs be to it. And furthermore the client can see nature where humanoid moves and furthermore give the positive commands. The collector segment comprises of equipment parts and furthermore this segment will react to the transmitter directions like moving in specific ways and furthermore shooting order is executed here.

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