# Model for Optimal Reserve Inventory Between Three Machines in Series with Reference to Repair Time Distribution

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**Abstract:** Consider an inventory system in which three machines are operating in series. The mathematical expressions for optimal reserve inventories between the first two machines as well as that between last two machines are derived based on the repair items of the first machine. The truncation point is also a random variable which follows any one of the probability distributions. Numerical values are obtained for optimal reserve inventory for varying holding costs, shortage costs and inter-arrival times between breakdowns and also graphically exhibited.

Key words: Repair time, truncation point, SCBZ property, Leibnitz rule and optimal reserve inventory.

## 1. Introduction

In inventory control theory, determining the optimal reserve inventory between two machines is an important model and these models have been studied by many researchers. The two machines problem may be conceptualized as follows.

A system in which there are two machines  $M_1$  and  $M_2$  in series and the output of machine  $M_1$  is the input to the machine  $M_2$ . Whenever the machine  $M_1$  goes in the breakdown state, it affects the productive level of Machine  $M_2$  in order to avoid the idle time of machine  $M_2$ , a reserve inventory is to be maintained between the machines. Hence, there are two costs namely holding cost and idle time cost involved in this process and therefore to balance out the two costs an optimal reserve inventory needs to be derived.

This type of model is basically introduced by Hanssmann (1962) and these types of models have been discussed by many researchers under the assumption that the repair time of machine  $M_1$  is a random variable.

Sachithanantham et al., (2006) have studied a model with the assumption that the probability function of the repair time undergoes a parametric change after the truncation point. The very basic concept of parametric change known as the Setting the Clock Back to Zero (SCBZ) property has been first discussed by RajaRao and Talwalker (1990). The model for optimal reserve inventory between two machines under the assumption that the repair time of machine M<sub>1</sub> satisfies the SCBZ property with the truncation point is being a random variable has been derived by Sachithanantham et al., (2007). The same type of model has been discussed by Srinivasan et al., (2007a) with the assumption that the inter arrival times between successive break downs of machine M<sub>1</sub> is a random variable, which satisfies SCBZ property. The same model with a modification of the probability function of truncation point has been discussed by Ramathilagam et al., (2014). The same model has been extended by Sachithanantham and Jagathesan (2017) and they authors have obtained the optimal reserve inventory under the assumption that the repair time of machine  $M_1$  is a random variable which satisfies the SCBZ property. It is also assumed that the truncation of repair time distribution is itself a random variable which follows mixed exponential distribution. Rajagopal and Sathiyamoorthi (2003) have studied the model in which there are three machines in series and derived the optimal reserve inventories between "M1 and M2" and that between " $M_2$  and  $M_3$ " under the assumption that the repair time of machine  $M_1$  is a random variables. Venkatesan et al., (2016) have discussed same model with the assumption that the consumption rates of the reserve inventories by the machines M<sub>2</sub> and M<sub>3</sub> are random variable. The improvement over this model is being studied in this paper, in which the repair time of M<sub>1</sub> is a random variable and its

probability function undergoes a parametric change after the truncation point. It is also assumed that the truncation point itself is a random variable which follows uniform distribution.

## 2. Assumptions

There are three machines  $M_1, M_2$  and  $M_3$  in series.

- (i) The output of  $M_1$  is the input for  $M_2$  and the output of  $M_2$  is the input for  $M_3$
- (ii)  $M_1$  is in down state where as  $M_2$  and  $M_3$  are in upstate.
- (iii) The idle time cost of  $M_3$  is very costly
- (iv) The repair time of Machine  $M_1$  is a random variable and its distribution satisfies the SCBZ property.

## 3. Notations

- $r_1, r_2$  : Consumption rates of  $M_2$  and  $M_3$  respectively.
- $h_1,h_2 \quad : \ Inventory \ holding \ costs \ per \ unit \ of \ S_1 \ and \ S_2 \ respectively$
- $d_1, d_2 \quad : \ Down \ time \ cost \ of \ M_2 \ and \ M_3 \ respectively$
- $S_1, S_2 \quad : \ Reserve \ inventory \ between \ M_1 \ and \ M_2, \ M_2 \ and \ M_3 \ respectively.$
- $\mu_1, \mu_2$ : Average inter arrival time between breakdowns of  $M_1$  and  $M_2$  respectively
- t : Repair time of  $M_1$

## 4. Model 1

In this model,  $M_1$  is in the downstate and both  $M_2$  and  $M_3$  are in the upstate. The expected total cost of this model is given by

$$E(C) = h_1 S_1 + h_2 S_2 + \frac{d_1}{\mu_1} \int_{\frac{S_1}{r_1}}^{\infty} \left( t - \frac{s_1}{r_1} \right) g(t) dt + \frac{d_2}{\mu_2} \int_{\frac{S_1}{r_1} + \frac{S_2}{r_2}}^{\infty} \left( t - \frac{s_1}{r_1} - \frac{s_2}{r_2} \right) g(t) dt \quad (1)$$

where the first two terms are the inventory holding costs, the third term is the idle time cost of  $M_2$  after the failure of  $M_1$  and before it is repaired and the fourth term is the idle time cost of  $M_3$  after the failure of  $M_1$  and before it is repaired.

Equation (1) is partially differentiating with respect to  $S_1$  and  $S_2$  and equating them to zero, we obtain.

$$h_1 + \frac{d_1}{\mu_1 r_1} \left[ 1 - G\left(\frac{S_1}{r_1}\right) \right] - \frac{d_2}{\mu_1 r_1} \left[ 1 - G\left(\frac{S_1}{r_1} + \frac{S_2}{r_1}\right) \right] = 0$$
(2)

and

$$h_2 - \frac{d_1}{\mu_1 r_1} \left[ 1 - G\left(\frac{S_1}{r_1} + \frac{S_2}{r_2}\right) \right] = 0$$
(3)

Solving the equations (2) and (3), the optimal values of  $S_1$  and  $S_2$  can be obtained. This model has been discussed by Rajagopal and Sathiyamoorthi (2003).

### 5. Results

In this model, a novel concept, the so called SCBZ properly is applied to the probability function of the repair time of Machine  $M_1$ . In doing so, the probability function of the repair time of machine  $M_1$  is assumed to follow exponential distribution and which takes a parametric change (SCBZ) after the truncation point. It is also assumed that the truncation point itself a random variable, which follows uniform distribution.

Thus the pdf of the repair time is

$$g(t,\theta) = \theta e^{-\theta t}, \text{ if } t \le x_o$$
  

$$g(t,\theta) = \theta^* e^{-\theta^* t} e^{x_o(\theta^* - \theta)}, \text{ if } t > x_o$$

It can be shown that  $\int_{0}^{\infty} g(t)dt = 1$ . where  $x_0$  is a random variable denoting that truncation point, which follows uniform distribution (a, b). Hence the p d f of repair time can be stated as

Hence the p.d.f of repair time can be stated as

$$f(t) = g(t,\theta)P(t \le x_0) + g(t,\theta^*)P(t > x_0)$$
(4)

$$P(t \le x_o) = P(x_o \le t) = \int_t^b \frac{1}{b-a} dx_o$$
  
=  $\frac{1}{b-a} \int_t^b dx_o$   
=  $\frac{1}{b-a} [b-t]$  (5)

$$P(t > x_o) = P(x_o < t) = \int_a^t \frac{1}{b - a} dx_o$$
(6)

Substituting equations (5) and (6) in the equation (4), we get

$$f(t) = \theta^{-\theta t} \left(\frac{1}{b-a}\right) (b-t) + \theta^* e^{-\theta^* t} e^{x_o(\theta^* - \theta)} \left(\int_t^b \frac{1}{b-a} dx_o\right)$$
(7)  
The expected cost is given by

$$E(C) = h_1 S_1 + h_2 S_2 + \frac{d_1}{\mu_1} \int_{\frac{S_1}{r_1}}^{\infty} \left( t - \frac{S_1}{r_1} \right) f(t) dt + \frac{d_2}{\mu_2} \int_{\frac{S_1}{r_1} + \frac{S_2}{r_2}}^{\infty} \left( t - \frac{S_1}{r_1} - \frac{S_2}{r_2} \right) f(t) dt \quad (\mathbf{8})$$

It can be shortly rewritten as

$$E(C) = h_1 S_1 + h_2 S_2 + T_1 T_2$$
(9)

Here,

$$T_{1} = \frac{d_{1}}{\mu_{1}} \int_{\frac{s_{1}}{r_{1}}}^{\infty} \left(t - \frac{s_{1}}{r_{1}}\right) \left\{ \theta e^{-\theta t} \left(\frac{1}{b-a}\right) (b-t) + \theta^{*} e^{-\theta^{*} t} e^{x_{0}(\theta^{*}-\theta)} \left( \int_{a}^{t} \left(\frac{1}{b-a}\right) dx_{0} \right) \right\} dt$$

$$T_{2} = \frac{d_{2}}{\mu_{2}} \int_{\frac{s_{1}}{r_{1}}+\frac{s_{2}}{r_{2}}}^{\infty} \left(t - \frac{s_{1}}{r_{1}} - \frac{s_{2}}{r_{2}}\right) \left\{ \theta e^{-\theta t} \left(\frac{1}{b-a}\right) (b-t) + \theta^{*} e^{-\theta^{*} t} e^{x_{0}(\theta^{*}-\theta)} \left( \int_{a}^{t} \left(\frac{1}{b-a}\right) dx_{0} \right) \right\} dt$$

To obtain the optimal values of  $S_1$  and  $S_2$ , differentiate the equation (9) with respect to  $S_1$  and  $S_2$ .

$$\frac{\partial E(C)}{\partial S_1} = 0 \Longrightarrow h_1 + \frac{\partial T_1}{\partial S_1} + \frac{\partial T_2}{\partial S_1}$$
(10)

$$T_{1} = \frac{d_{1}}{\mu_{1}} \int_{\frac{S_{1}}{r_{1}}}^{\infty} \left( t - \frac{S_{1}}{r_{1}} \right) \left\{ \theta e^{-\theta t} \left( \frac{1}{b-a} \right) (b-t) + \theta^{*} e^{-\theta^{*} t} e^{x_{0}(\theta^{*}-\theta)} \left( \int_{a}^{t} \left( \frac{1}{b-a} \right) dx_{0} \right) \right\} dt$$

Using Leibnitz rule of differentiation of an integral, we get

$$\frac{\partial T_1}{\partial S_1} = \frac{d_1}{\mu_1} \int_{\frac{S_1}{r_1}}^{\infty} \left( -\frac{1}{r_1} \right) \left\{ \theta e^{-\theta t} \left( \frac{1}{b-a} \right) (b-t) + \theta^* e^{-\theta^* t} e^{x_0 (\theta^* - \theta)} \left( \int_a^t \left( \frac{1}{b-a} \right) dx_0 \right) \right\} dt$$

$$\begin{split} &= -\frac{d_{1}}{\mu_{1}r_{1}(b-a)} \int_{\frac{s_{1}}{r_{1}}}^{\infty} \left\{ \theta e^{-\theta t} (b-t) + \theta^{*} e^{-\theta^{*} t} \left( \int_{a}^{t} e^{x_{0}(\theta^{*}-\theta)} dx_{0} \right) \right\} dt \\ &= \frac{d_{1}}{\mu_{1}r_{1}(b-a)} \left[ \left\{ \int_{\frac{s_{1}}{r_{1}}}^{\infty} \theta e^{-\theta t} (b-t) dt \right\} + \left\{ \int_{\frac{s_{1}}{r_{1}}}^{\infty} \theta^{*} e^{-\theta^{*} t} e^{\theta^{*} t} \left( \int_{a}^{t} e^{x_{0}(\theta^{*}-\theta)} dx_{0} \right) dt \right\} \right] \\ &= \frac{d_{1}}{\mu_{1}r_{1}(b-a)} \left[ \theta \left\{ \left( \int_{\frac{s_{1}}{r_{1}}}^{\infty} b e^{-\theta t} - t e^{-\theta t} \right) dt + I_{1} \right\} \right] \\ &= -\frac{d_{1}}{\mu_{1}r_{1}(b-a)} \left[ \theta \left\{ \int_{\frac{s_{1}}{r_{1}}}^{\infty} b e^{-\theta t} dt - \int_{\frac{s_{1}}{r_{1}}}^{\infty} t e^{-\theta t} dt \right\} + I_{1} \right] \\ &= -\frac{d_{1}}{\mu_{1}r_{1}(b-a)} \left[ \theta \left\{ \int_{\frac{s_{1}}{r_{1}}}^{\infty} b e^{-\theta t} dt - \int_{\frac{s_{1}}{r_{1}}}^{\infty} t e^{-\theta t} dt \right\} + I_{1} \right] \\ &= -\frac{d_{1}}{\mu_{1}r_{1}(b-a)} \left[ \left\{ b e^{-\frac{s_{1}}{r_{1}}} - \frac{s_{1}}{r_{1}} e^{-\frac{s_{1}}{r_{1}}} - \frac{\theta^{*}}{\theta} e^{-\frac{s_{1}}{r_{1}}} \theta + I_{1} \right] \\ &= \frac{d_{1}}{\mu_{1}r_{1}(b-a)} \left[ \left\{ b - \frac{s_{1}}{r_{1}} - \frac{s_{1}}{\theta} e^{-\frac{s_{1}}{r_{1}}} \theta + I_{1} \right\} \\ & \text{where} \\ &I_{1} = \int_{\frac{s_{1}}{r_{1}}}^{\infty} \theta^{*} e^{-\theta^{*} t} \left[ f_{1} e^{x_{0}(\theta^{*}-\theta)} dx_{0} \right] dt \\ &= \frac{\theta}{(\theta^{*}-\theta)} \left[ \int_{\frac{s_{1}}{r_{1}}}^{s_{0}} e^{-\theta^{*} t} \left[ e^{t(\theta^{*}-\theta)} dt - \int_{\frac{s_{1}}{r_{1}}}^{s_{0}} e^{-\theta^{*} t} e^{a(\theta^{*}-\theta)} dt \right] \\ &= \frac{\theta}{(\theta^{*}-\theta)} \left[ \int_{\frac{s_{1}}{r_{1}}}^{s_{0}} e^{-\theta^{*} t} dt - e^{a(\theta^{*}-\theta)} \int_{\frac{s_{1}}{r_{1}}}^{s_{0}} e^{-\theta^{*} t} dt \right] \\ &I_{1} = \frac{\theta}{(\theta^{*}-\theta)} \left[ e^{-\frac{s_{1}}{r_{1}}} - e^{a(\theta^{*}-\theta) \int_{\frac{s_{1}}{r_{1}}}^{s_{0}} e^{-\theta^{*} t} dt - e^{a(\theta^{*}-\theta)} \int_{\frac{s_{1}}{r_{1}}}^{s_{0}} e^{-\theta^{*} t} dt \right] \end{aligned}$$

$$(12)$$

Thus,

$$\frac{\partial T_1}{\partial S_1} = -\frac{d_1}{\mu_1 r_1 (b-a)} \left[ \left\{ b - \frac{s_1}{r_1} - \frac{1}{\theta} \right\} e^{-\frac{s_1}{r_1}\theta} + \frac{\theta^*}{(\theta^* - \theta)\theta} \left\{ e^{-\frac{s_1}{r_1}\theta} - e^{a(\theta^* - \theta) - \frac{s_1}{r_1}\theta^*} \right\} \right]$$
(13)

Similarly,  $\frac{\partial T_2}{\partial S_1}$  can be obtained as  $\frac{\partial T_2}{\partial S_1} = \frac{d_2}{\mu_2 r_1 (b-a)} \left[ \left\{ b - \left(\frac{S_1}{r_1} + \frac{S_2}{r_2}\right) - \frac{1}{\theta} \right\} e^{-\left(\frac{S_1}{r_1} + \frac{S_2}{r_2}\right)\theta} + \frac{\theta^*}{(\theta^* - \theta)\theta} \left\{ e^{-\left(\frac{S_1}{r_1} + \frac{S_2}{r_2}\right)\theta} - e^{a(\theta^* - \theta) - \left(\frac{S_1}{r_1} + \frac{S_2}{r_2}\right)\theta^*} \right\} \right]$ (14)

Substituting (13) and (14) in (10), the resultant equation is,

$$\frac{\partial E(C)}{\partial S_1} = 0 \Longrightarrow$$

$$h_1 - \frac{d_1}{\mu_1 r_1 (b-a)} \left[ \left\{ b - \frac{s_1}{r_1} - \frac{1}{\theta} \right\} e^{-\frac{s_1}{r_1}\theta} + \frac{\theta^*}{(\theta^* - \theta)\theta} \left\{ e^{-\frac{s_1}{r_1}\theta} - e^{a(\theta^* - \theta) - \frac{s_1}{r_1}\theta^*} \right\} \right]$$

$$-\frac{d_2}{\mu_2 r_1 (b-a)} \left[ \left\{ b - \left(\frac{s_1}{r_1} + \frac{s_2}{r_2}\right) - \frac{1}{\theta} \right\} e^{-\left(\frac{s_1}{r_1} + \frac{s_2}{r_2}\right)\theta} + \frac{\theta^*}{(\theta^* - \theta)\theta} \left\{ e^{-\left(\frac{s_1}{r_1} + \frac{s_2}{r_2}\right)\theta} - e^{a(\theta^* - \theta) - \left(\frac{s_1}{r_1} + \frac{s_2}{r_2}\right)\theta} \right\} \right] = 0 \ (15)$$
  
In a similar way it can be shown that  
$$\frac{\partial E(C)}{\partial s_2} = 0 \Longrightarrow$$
$$h_2 - \frac{d_2}{\mu_2 r_2 (b-a)} \left[ \left\{ b - \left(\frac{s_1}{r_1} + \frac{s_2}{r_2}\right) - \frac{1}{\theta} \right\} e^{-\left(\frac{s_1}{r_1} + \frac{s_2}{r_2}\right)\theta} \right]$$

$$+ \frac{\theta^{*}}{(\theta^{*} - \theta)\theta} \left\{ e^{-\left(\frac{S_{1}}{r_{1}} + \frac{S_{2}}{r_{2}}\right)\theta} - e^{a(\theta^{*} - \theta)} e^{-\left(\frac{S_{1}}{r_{1}} + \frac{S_{2}}{r_{2}}\right)\theta^{*}} \right\} = 0$$
(16)

Solving the equations (15) and (16), we get

$$h_1 r_1 - h_2 r_2 \frac{d_1}{\mu_1 (b-a)} \left[ \left\{ b - \frac{s_1}{r_1} - \frac{1}{\theta} \right\} e^{-\frac{s_1}{r_1}\theta} + \frac{\theta^*}{(\theta^* - \theta)\theta} \left\{ e^{-\frac{s_1}{r_1}\theta} - e^{a(\theta^* - \theta)} e^{-\frac{s_1}{r_1}\theta^*} \right\} \right] = 0 \quad (17)$$

Using the equations (16) and (17) the optimal value of  $\hat{S}_1$  and  $\hat{S}_2$  can be obtained for fixed values of  $h_1$ ,  $h_2$ ,  $d_1$ ,  $d_2$ ,  $\mu_1$ ,  $\mu_2$ ,  $r_1$ ,  $r_2$ ,  $\theta$ ,  $\theta^*$ , a and b.

#### 6. Numerical illustrations

The variations in  $\hat{S}_1$  and  $\hat{S}_2$  in  $h_1$ ,  $h_2$ ,  $d_1$ ,  $d_2$ ,  $\mu_1$  and  $\mu_2$  have been studied by assuming other parameters has

h1	15	16	17	18
Ŝı	0.9274	0 <mark>.7528</mark>	0.6036	0.4731

**Table 1** The optimal reserve inventory for varying  $h_1$ 



Fig 1 The optimal reserve inventory for varying h<sub>1</sub>

h <sub>2</sub>	9	10	11	12
Ŝı	0.7528	0.9274	1.1383	1.4065
Ŝ2	0.5262	0.3856	0.2591	0.1441

**Table 2** The optimal reserve inventory for varying  $h_2$ 



**Fig. 2** The optimal reserve inventory for varying h<sub>2</sub> **Table 3** The optimal reserve inventory for varying d<sub>1</sub>





Table 4 The optimal reserve inventory for varying  $d_2$ 

d <sub>2</sub>	60	70	80	90
Ŝ2	0.3856	0.5916	0.7717	0.9320



Fig. 4 The optimal reserve inventory for varying  $d_2$ 

Table 5 The optimal reserve inventory for varying
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$\mu_1$	0.8	0.9	1.0	1.1
Ŝı	0.9272	0.8148	0.7143	0.6211



Fig. 5 The optimal reserve inventory for varying  $\mu_1$ 

μ2	1.0	1.1	1.2	1.3
$\hat{S}_2$	0.3856	0.2591	0.1441	0.0387

**Table 6** The optimal reserve inventory for varying  $\mu_2$ 



Fig. 6 The optimal reserve inventory for varying  $\mu_2$ 

### 7 Conclusion

It is seen from the above numerical illustration that the determination of optimal  $\hat{S}_1$  and  $\hat{S}_2$  depends upon various parameters  $\mu_1$ ,  $\mu_2$  and also on the values of the costs  $d_1, d_2$ ,  $h_1$  and  $h_2$ . Also two rates of consumption  $M_2$  and  $M_3$  namely  $r_1$  and  $r_2$  play a role in the optimal size of  $S_1$  and  $S_2$ . The changes in the values of  $\hat{S}_1$  and  $\hat{S}_2$  due to changes of  $\mu_1$ ,  $\mu_2$   $h_1$ ,  $h_2$ ,  $d_1$  and  $d_2$  have been studied. The optimal reserve inventory level increases in the first inventory when increasing both inventory costs, but the second inventory level does not altered due to the changes of its corresponding inventory cost. On the other hand, second inventory level decreases for increasing its inventory cost. Due to the changes of down time costs, the corresponding inventory level changes in the same direction, but others remain the same. Similarly, the levels of both inventories changes in opposite direction due to the changes of average inter-arrival times, but others do not changes.

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