# **TOPOLOGICAL VECTOR SPACES**

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#### Abstract

This article deals with the concept of Topological Vector Spaces with an example and the definitions required for this. Also we will study continuous mapping on topological spaces.

# **Keywords**

Cartesian product, Induced, Metric, Norm, Set, Topology etc.

### **Introduction**

To understand the concept of topological vector spaces, we require following concepts....

(Definition-1)**VECTOR SPACE:** A non empty set A is called a Vector space or Linear space over a Field  $(F,+,\cdot)$  if A is an Abelian group under an operation which we denote '+'and if for every  $a \in F$ ,  $\alpha \in A$  there is defined an element  $a\alpha \epsilon A$  subjected to

- 1.  $a(\alpha + \beta) = a\alpha + a\beta$
- 2.  $(a+b)\alpha = a\alpha + b\alpha$

3.  $a(b\alpha) = (ab)\alpha$ 

4.  $1\alpha = \alpha$  For all a, bcF and  $\alpha$ ,  $\beta$ cA, where 1 represents the unit element of F under multiplication.

(Definition-2)<u>TOPOLOGY</u>: A Topology τ defined over a non empty set X is the collection of subsets of set X satisfies the following axioms...

- [A1] X and  $\Phi$  belong to  $\tau$ .
- [A2] The union of any family of sets in  $\tau$  belongs to  $\tau$ .
- [A3] The intersection of any two sets in  $\tau$  belongs to  $\tau$ .

The set X together with the Topology  $\tau$  is called Topological Spaces and written as the pair (X, $\tau$ ) or simply by X.

(Definition-3)**Metric space:** Let X be a non-empty set. A metric on X, denoted by d is defined as the mapping from the Cartesian product X×X into the set of real numbers R satisfying the following conditions......

- (M1)  $d(x,y) \ge 0$  for every  $x,y \in X$ . This is called non-negative restriction.
- (M2) d(x,y)=0 if and only if x=y for  $x,y\in X$ .
- (M3) d(x,y) = d(y,x) for every  $x,y \in X$ . This is called symmetric property of d. and
- (M4)  $d(x,y) + d(y,z) \ge d(x,z)$  for every  $x,y,z \in X$ . This is called triangle inequality of d.

The set X together with the metric d is called metric space and denoted by the pair (X,d) or simply X. There can always be defined a topology on X induced by the metric d called natural topology or usual topology on X hence a metric space is always a topological space.

(Definition-4)**NORM**: For a given linear space E, over a field F, a norm on E is defined as a map  $x \rightarrow ||x||$  from X into the set R<sup>+</sup> of non negative real numbers which satisfies the following axioms ....

(N1) ||x||=0 iff x=0 (N2)  $||\Lambda x||=|\Lambda|\cdot||x|| \forall \Lambda \in F, x \in X.$  (N3)  $||x+y|| \le ||x|| + ||y|| \forall x,y \in X.$ 

A linear space on which a norm is defined is called normed linear space or simply normed space. There can always be defined a metric d induced by norm  $\| \|$  given as  $d(x, y) = \|x - y\|$  for every  $x, y \in X$ . And definition-3 implies that a topology can be induced by a metric, therefore, every norm space is a topological space.

**Property-1**  $||x|| - ||y|| \le ||x - y||$  for very *x*, *y*  $\in$  X.

Since  $||x|| = ||(x-y) + y|| \le ||x-y|| + ||y||$  (by axiom N3), implies that  $||x|| - ||y|| \le ||x-y||$ .

(Definition-5)<u>CONTINUOUS MAPPING ON TOPOLOGICAL SPACES</u>: Let us consider X and Y are two Topological spaces and  $f : X \rightarrow Y$ . The mapping f is said to be continuous at a point  $x \in X$  if for each neighborhood V of y = f(x) in Y,

 $f^{-1}$  (V) is a neighborhood of x in X. f is said to be continuous on X into Y if f is continuous at each x $\in$ X.

Sequentially (in view of metric spaces), f is continuous if for  $x \in X$  every sequence  $(x_n)$  in X converging to x, the sequence  $(f(x_n))$  in Y converging to f(x) i.e.  $x_n \to x \Rightarrow f(x_n) \to f(x)$ . i.e. if  $d_1 \& d_2$  are metrices in X and Y respectively then for  $\epsilon$ >0 there exists  $\delta$ >0 such that  $d_1(x_n, x) < \delta \Rightarrow d_2(f(x_n), f(x)) < \varepsilon$ .

#### Theorem-1 Norm function is a continuous function.

<u>Solution</u>: Let X is a normed space with the norm  $\| \|$  from X into R. Let the metric induced by norm in X is  $d_1 = \|x - y\|$ and  $d_2 = \| \|x\| - \|y\| \|$  be the usual metric in R. Now let  $(x_n)$  be a sequence in the normed space X such that  $x_n \to x$  in X. Then for the mapping  $\| \|$ , we find that

 $||x_n|| - ||x|| \le ||x_n - x||$  (by property-1), which implies that  $|||x_n|| - ||x||| \le d_1(x_n, x) \to 0$  as  $x_n \to x$  in X. Therefore, we get  $d_2(||x_n||, ||x||) = |||x_n|| - ||x||| \to 0$  then definition-5 implies that norm || || is a continuous mapping. (Definition-6)<u>TOPOLOGICAL VECTOR SPACES</u>: Let E is a vector space over a field K(real or complex) and a topology  $\tau$  is

defined on it. The set E is called a **topological vector space** if the maps (I)  $(x, y) \rightarrow x + y$  from  $E \times E \rightarrow E$  and (II)  $(\lambda, x) \rightarrow \lambda . x$  from  $K \times E \rightarrow E$  are continuous and then it

is abbreviated by TVS. The topology defined on  $E \times E$  is the product topology  $\tau \times \tau$  and the topology defined on  $K \times E$  is the product topology  $\mu \times \tau$  where  $\mu$  is the usual topology defined on the field K.

**Theorem-2** Let E is a normed vector space over a field K then the maps (i)  $(x, y) \rightarrow x + y$  from E×E into E. and (ii)  $(\lambda, x) \rightarrow \lambda x$  from K×E into E. are continuous mapping.

<u>Solution</u>: Let <(x,y)> be a sequence in the space  $E \times E$  converging to a point (a,b) in  $E \times E$  which implies that  $x \to a$  and  $y \to b$  in E for which taking  $||x - a|| < \frac{\varepsilon}{2}$  and  $||y - b|| < \frac{\varepsilon}{2}$ , then we have

 $||(x+y)-(a+b)|| = ||(x-a)+(x-b)|| \le ||x-a|| + ||y-b|| < \varepsilon$  (by property N3 of definition-4)

Which implies that  $(x + y) \rightarrow (a + b)$ . So the mapping  $(x, y) \rightarrow x + y$  from E×E into E is continuous.

Now let  $(\lambda, x) \rightarrow (\alpha, a)$  in the space K×E which implies that  $\lambda \rightarrow \alpha \& x \rightarrow a$  in their respective spaces. Such that

 $\|x-a\| < \frac{\varepsilon}{2|\lambda|} \& |\lambda-\alpha| < \frac{\varepsilon}{2\|a\|}$  , then we have

 $\|\lambda x - \alpha a\| = \|\lambda x - \lambda a + \lambda a - \alpha a\| \le \|\lambda (x - a)\| + \|a(\lambda - \alpha)\| \le |\lambda| \|x - a\| + \|a\| |\lambda - \alpha| < \varepsilon \text{ i.e. } \lambda x \to \alpha a \text{ so the mapping } (\lambda, x) \to \lambda . x \text{ from } K \times E \to E \text{ is continuous.}$ 

# Example-1 A normed vector space equipped with the topology defined by its norm is a topological vector space.

**Solution:** Let E is a normed vector space over a field K and d is the metric induced by the norm  $\|\|\|$  on E given as  $d(x, y) = \|x - y\|$  and then a topology  $\tau$  is induced by d on E. Now from theorem-2, we find that the maps

(i)  $(x, y) \rightarrow x + y$  from E×E into E. and (ii)  $(\lambda, x) \rightarrow \lambda x$  from K×E into E. are continuous mapping.

Therefore by definition-6, E is a topological vector space.

#### <u>result</u>

For defining the concept of a TVS, we need the concept of vector space, topology and continuous mapping in topological spaces. Example-3 is an example of a TVS for which we need the concept of norm.

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