

$\tau_i\tau_j - M^* - \sigma_k$ -continuous Maps

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Abstract

The aim of this paper is to introduce and investigate the concept of $\tau_i\tau_j - M^* - \sigma_k$ -continuous maps in a bitopological space. Moreover we investigate the relationship between $\tau_i\tau_j - \delta - \sigma_k$ -continuous, $\tau_i\tau_j - \delta s - \sigma_k$ -continuous, $\tau_i\tau_j - a - \sigma_k$ -continuous, $\tau_i\tau_j - e^* - \sigma_k$ -continuous and respective some other closed mappings..

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Introduction and Preliminaries

Levine in 1963 initiated a new types of open set called semiopen set [10]. A subset A of a space (X, τ) is called regular open (resp., regular closed) [15] if $A = \text{int}(cl(A))$ (resp., $A = cl(\text{int}(A))$). The delta interior [4] of a subset A of (X, τ) is the union of all regular open sets of X contained in A and is denoted by $\delta\text{int}(A)$. A subset A of a space (X, τ) is called δ -open [12] if $A = \delta\text{int}(A)$. The complement of δ -open set is called δ -closed. Alternatively, a set A of (X, τ) is called δ -closed [4] if $A = \delta cl(A)$, where $\delta cl(A) = \{x \in X : A \cap \text{int}(cl(U)) \neq \emptyset, U \in \tau \text{ and } x \in U\}$. A subset A of a space X is called θ -open [1] if $A = \theta\text{int}(A)$, where $\theta\text{int}(A) = \bigcup \{\text{int}(U) : U \subseteq A, U \in \tau^c\}$, and a subset A is called θ -semiopen [2] (resp., δ -preopen [12], e -open[5], M -open [6], M^* -open[3], δ -semiopen [11], δ -open[15], e^* -open [5] and a -open[5]) if $A \subseteq cl(\theta\text{int}(A))$ (resp., $A \subseteq \text{int}(\delta cl(A))$, $A \subseteq cl(\delta\text{int}(A)) \cup \text{int}(\delta cl(A))$ and $A \subseteq cl(\theta\text{int}(A)) \cup \text{int}(\delta cl(A))$, $A \subseteq \text{int}(cl(\theta\text{int}(A)))$, $A \subseteq cl(\delta\text{int}(A))$, $A = \delta\text{int}(A)$, $A \subseteq cl(\text{int}(\delta cl(A)))$ and $A \subseteq \text{int}(cl(A)(\delta\text{int}(A)))$, where $\text{int}()$, $cl()$, $\theta\text{int}()$, $\delta\text{int}()$ and $\delta cl()$ are the interior, closure, θ -interior, δ -interior and δ -closure operations, respectively. The notion of bitopological spaces (in short, Bts's) was first introduced by Kelly[8].

Through out this paper, let (X, τ_1, τ_2) or simply X be a Bts and $i, j \in \{1, 2\}$. A subset S of a Bts X is said to be $\tau_{1,2}$ -open [9] if $S = A \cup B$ where $A \in \tau_1$ and $B \in \tau_2$. A subset S of X is said to be $\tau_{1,2}$ -closed if the complement of S is $\tau_{1,2}$ -open. and $\tau_{1,2}$ -clopen if S is both $\tau_{1,2}$ -open and $\tau_{1,2}$ -closed. For a subset A of X , the interior (resp., closure) of A with respect to τ_i will be denoted by $\text{int}_i(A)$ (resp., $cl_i(A)$) for $i = 1, 2$. In this paper, we introduce and investigate the concept of $\tau_i\tau_j - M^* - \sigma_k$ -continuous maps in a bitopological spaces. In addition, several properties of these notions and connections to several other known ones are provided.

Let (X, τ_1, τ_2) be a Bts. A subset A of X is called $\tau_i \tau_j$ - M -open [13] (briefly, $\tau_i \tau_j$ - M -o) if $A \subseteq cl_j(\theta int_i(A)) \cup int_i(\delta cl_j(A))$ and A is $\tau_i \tau_j$ - M closed (in short, $\tau_i \tau_j$ - M -c) if $X \setminus A$ is $\tau_i \tau_j$ - M -o. A is pairwise M -open if it is both $\tau_i \tau_j$ - M -o and $\tau_j \tau_i$ - M -o. A subset A of X is called $\tau_i \tau_j$ - M^* -open [13] (briefly, $\tau_i \tau_j$ - M^* -o) if $A \subseteq int_i(cl_j(\theta int_i(A)))$ and A is $\tau_i \tau_j$ - M^* -closed (briefly, $\tau_i \tau_j$ - M^* -c) if $X \setminus A$ is $\tau_i \tau_j$ - M^* -o. A is pairwise M^* -o if it is both $\tau_1 \tau_2$ - M^* -o and $\tau_2 \tau_1$ - M^* -o.

Clearly A is $\tau_i \tau_j$ - M^* -c iff $A \supseteq cl_j(int_i(\theta cl_j(A)))$. We denote the family of all $\tau_i \tau_j$ - M^* -c sets in a Bts (X, τ_1, τ_2) by $D_{M^*C}(\tau_i, \tau_j)$. A subset A of X is called $\tau_i \tau_j$ - θ -semiopen [13] (briefly, $\tau_i \tau_j$ - θ -so) if $A \subseteq cl_j(\theta int_i(A))$, $\tau_i \tau_j$ - δ -preopen [13] (briefly, $\tau_i \tau_j$ - δ -po) if $A \subseteq int_i(\delta cl_j(A))$, $\tau_i \tau_j$ - e -open if $A \subseteq cl_j(\delta int_i(A)) \cup int_i(\delta cl_j(A))$, $\tau_i \tau_j$ - δ -semi open [13] (briefly, $\tau_i \tau_j$ - δ -so) if $A \subseteq cl_j(\delta int_i(A))$, $\tau_i \tau_j$ - δ -open [13] (briefly, $\tau_i \tau_j$ - δ -o) if $A = \delta int_i(A)$, $\tau_i \tau_j$ - e^* -open [13] (briefly, $\tau_i \tau_j$ - e^* -o) if $A \subseteq cl_j(int_i(\delta cl_j(A)))$, $\tau_i \tau_j$ - a -open [13] (briefly, $\tau_i \tau_j$ - a -o) if $A \subseteq int_i(cl_j(A)(\delta int_i(A)))$.

Definition 1.1 A map $f: (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called [14] $\tau_i \tau_j$ - θ - σ_k -continuous (briefly, $\tau_i \tau_j$ - θ - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - θ -c set in (X, τ_1, τ_2) ; $\tau_i \tau_j$ - θs - σ_k -continuous (briefly, $\tau_i \tau_j$ - θs - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - θs -c set in (X, τ_1, τ_2) ; $\tau_i \tau_j$ - M - σ_k -continuous (briefly, $\tau_i \tau_j$ - M - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - M -c set in (X, τ_1, τ_2) ; $\tau_i \tau_j$ - e - σ_k -continuous (briefly, $\tau_i \tau_j$ - e - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - e -c set in (X, τ_1, τ_2) ; $\tau_i \tau_j$ - δp - σ_k -continuous (briefly, $\tau_i \tau_j$ - δp - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - δp -c set in (X, τ_1, τ_2) and τ_i - σ_k -continuous **Error! Reference source not found.** (briefly, τ_i - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - τ_i -c set in (X, τ_1, τ_2) .

2. $\tau_i \tau_j$ - M^* - σ_k -continuous Maps

Definition 2.1 A map $f: (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is called

- (1) $\tau_i \tau_j$ - M^* - σ_k -continuous (briefly, $\tau_i \tau_j$ - M^* - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - M^* -c set in (X, τ_1, τ_2) .
- (2) $\tau_i \tau_j$ - δ - σ_k -continuous (briefly, $\tau_i \tau_j$ - δ - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - δ -c set in (X, τ_1, τ_2) .
- (3) $\tau_i \tau_j$ - δs - σ_k -continuous (briefly, $\tau_i \tau_j$ - δs - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - δs -c set in (X, τ_1, τ_2) .
- (4) $\tau_i \tau_j$ - a - σ_k -continuous (briefly, $\tau_i \tau_j$ - a - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - a -c set in (X, τ_1, τ_2) .
- (5) $\tau_i \tau_j$ - e^* - σ_k -continuous (briefly, $\tau_i \tau_j$ - e^* - σ_k -cts) if the inverse image of every σ_k -c set is an $\tau_i \tau_j$ - e^* -c set in (X, τ_1, τ_2) .

Theorem 2.1 If a map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a

- (1) $\tau_i - \sigma_k$ -cts then it is a $\tau_i \tau_j - M^* - \sigma_k$ -cts
- (2) $\tau_i \tau_j - \theta - \sigma_k$ -cts then it is a $\tau_i \tau_j - M^* - \sigma_k$ -cts
- (3) $\tau_i \tau_j - \theta s - \sigma_k$ -cts then it is a $\tau_i \tau_j - M^* - \sigma_k$ -cts
- (4) $\tau_i \tau_j - \theta - \sigma_k$ -cts then it is a $\tau_i \tau_j - \theta s - \sigma_k$ -cts
- (5) $\tau_i \tau_j - M^* - \sigma_k$ -cts then it is a $\tau_i \tau_j - M - \sigma_k$ -cts
- (6) $\tau_i \tau_j - M - \sigma_k$ -cts then it is a $\tau_i \tau_j - e - \sigma_k$ -cts
- (7) $\tau_i \tau_j - \delta p - \sigma_k$ -cts then it is a $\tau_i \tau_j - e - \sigma_k$ -cts
- (8) $\tau_i \tau_j - \theta - \sigma_k$ -cts then it is a $\tau_i \tau_j - \delta - \sigma_k$ -cts
- (9) $\tau_i \tau_j - \theta s - \sigma_k$ -cts then it is a $\tau_i \tau_j - \delta s - \sigma_k$ -cts
- (10) $\tau_i - \sigma_k$ -cts then it is a $\tau_i \tau_j - M^* - \sigma_k$ -cts
- (11) $\tau_i \tau_j - \delta - \sigma_k$ -cts then it is a $\tau_i \tau_j - a - \sigma_k$ -cts
- (12) $\tau_i \tau_j - M^* - \sigma_k$ -cts then it is a $\tau_i \tau_j - \theta s - \sigma_k$ -cts
- (13) $\tau_i \tau_j - \delta s - \sigma_k$ -cts then it is a $\tau_i \tau_j - e - \sigma_k$ -cts
- (14) $\tau_i \tau_j - \delta p - \sigma_k$ -cts then it is a $\tau_i \tau_j - M - \sigma_k$ -cts
- (15) $\tau_i \tau_j - a - \sigma_k$ -cts then it is a $\tau_i \tau_j - \delta p - \sigma_k$ -cts
- (16) $\tau_i \tau_j - e - \sigma_k$ -cts then it is a $\tau_i \tau_j - e^* - \sigma_k$ -cts
- (17) $\tau_i \tau_j - a - \sigma_k$ -cts then it is a $\tau_i \tau_j - \delta s - \sigma_k$ -cts

Proof. (1) Let V be an σ_k -c set. Since f is $\tau_i - \sigma_k$ -cts. $f^{-1}(v)$ is $\tau_i \tau_j - \sigma_i$ -c. By Lemma 2.1 in [13], $f^{-1}(v)$ is $\tau_i \tau_j - M^*$ -c in (X, τ_1, τ_2) . Therefore f is $\tau_i \tau_j - M^* - \sigma_k$ -cts. The proof of (2) to (17) are similar as in (1).

Example 2.1 Let $X = Y = \{a, b, c, d\}$, $\tau_1 = \{\phi, X, \{a\}, \{b\}, \{a, b\}, \{d, c\}, \{a, d, c\}, \{b, c, d\}\}$, $\tau_2 = \{\phi, X, \{a\}, \{b, d\}, \{a, c\}, \{a, b, d\}\}$, $\sigma_1 = \{Y, \phi, \{b, c\}, \{b, d\}\}$ and $\sigma_2 = \{Y, \phi, \{b\}, \{b, d\}, \{a, b, c\}\}$. Then the identity map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a

- (1) $\tau_1 \tau_2 - M^* - \sigma_1$ -cts but it is not $\tau_1 - \sigma_1$ -cts, since for the σ_1 -c set $\{a, d\}$, $f^{-1}(\{a, d\}) = \{a, d\}$ which is not τ_1 -c set.
- (2) $\tau_1 \tau_2 - M^* - \sigma_1$ -cts but it is not $\tau_1 \tau_2 - \theta - \sigma_1$ -cts, since for the σ_1 -c set $\{a, c\}$, $f^{-1}(\{a, c\}) = \{a, c\}$ which is not $\tau_1 \tau_2 - \theta$ -c set.

Example 2.2 Let $X = Y = \{a, b, c, d\}$, τ_1 and τ_2 are defined as in Example 2.1, $\sigma_1 = \{Y, \phi, \{d\}, \{a, d\}\}$ and $\sigma_2 = \{Y, \phi, \{d\}, \{a, b, c\}, \{a, b, d\}\}$. Then the identity map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1 \tau_2 - M^* - \sigma_1$ -cts but it is not $\tau_1 \tau_2 - \theta s - \sigma_1$ -cts. Since for the σ_1 -c set $\{b, c\}$, $f^{-1}(\{b, c\}) = \{b, c\}$ which is not $\tau_1 \tau_2 - \theta$ -sc set.

Example 2.3 Let $X = Y = \{a, b, c, d\}$, τ_1 and τ_2 are defined in Example 2.1, $\sigma_1 = \{Y, \phi, \{b, c\}, \{a, b, c\}\}$ and $\sigma_2 = \{Y, \phi, \{b\}, \{a, b, c\}, \{a, b, d\}\}$. Then the identity map $f : (X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1 \tau_2 - \theta s - \sigma_1$ -cts but it is not $\tau_1 \tau_2 - \theta - \sigma_1$ -cts. Since for the σ_1 -c set $\{d\}$, $f^{-1}(\{d\}) = \{d\}$ which is not $\tau_1 \tau_2 - \theta$ -c set.

Example 2.4 Let $X=Y=\{a,b,c,d\}, \tau_1$ and τ_2 are defined in Example 2.1, $\sigma_2 = \{Y, \phi, \{d\}, \{a,d\}, \{a,b,c\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ - M - σ_1 -cts but it is not $\tau_1\tau_2$ - M^* - σ_1 -cts. Since for the σ_1 -c set $\{a,b,c\}, f^{-1}(\{a,b,c\}) = \{a,b,c\}$ which is not $\tau_1\tau_2$ - M^* -c set.

Example 2.5 Let $X=Y=\{a,b,c,d\}, \tau_1$ and τ_2 are defined in Example 2.1, $\sigma_1 = \{Y, \phi, \{c\}, \{a,c\}\}$ and $\sigma_2 = \{Y, \phi, \{c\}, \{a,c\}, \{a,c,d\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ -e- σ_1 -cts but it is not $\tau_1\tau_2$ - M - σ_1 -cts. Since for the σ_1 -c set $\{b,d\}, f^{-1}(\{b,d\}) = \{b,d\}$ which is not $\tau_1\tau_2$ - M -c set.

Example 2.6 Let $X=Y=\{a,b,c,d\}, \tau_1$ and τ_2 are defined in Example 2.1, $\sigma_1 = \{Y, \phi, \{a,c\}\}$ and $\sigma_2 = \{Y, \phi, \{a\}, \{a,c\}, \{a,c,d\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ -e- σ_1 -cts but it is not $\tau_1\tau_2$ - δp - σ_1 -cts. Since for the σ_1 -c set $\{b,d\}, f^{-1}(\{b,d\}) = \{b,d\}$ which is not $\tau_1\tau_2$ - δ -pc set.

Example 2.7 Let $X=Y=\{a,b,c,d\}, \tau_1$ and τ_2 are defined in Example 2.1, $\sigma_1 = \{Y, \phi, \{c\}, \{b,d\}\}$ and $\sigma_2 = \{Y, \phi, \{b\}, \{b,d\}, \{a,b,c\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ - δ - σ_1 -cts but it is not $\tau_1\tau_2$ - θ - σ_1 -cts. Since for the σ_1 -c set $\{a,b,d\}, f^{-1}(\{a,b,d\}) = \{a,b,d\}$ which is not $\tau_1\tau_2$ - θ -c set.

Example 2.8 Let $X=Y=\{a,b,c,d\}, \tau_1$ and τ_2 are defined in Example 2.1, $\sigma_1 = \{Y, \phi, \{c\}, \{a,c\}\}$ and $\sigma_2 = \{Y, \phi, \{b\}, \{a,c\}, \{a,b,c\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ - δs - σ_1 -cts but it is not $\tau_1\tau_2$ - θs - σ_1 -cts. Since for the σ_1 -c set $\{b,d\}, f^{-1}(\{b,d\}) = \{b,d\}$ which is not $\tau_1\tau_2$ - θ -sc set.

Example 2.9 Let $X=Y=\{a,b,c,d\}, \tau_1 = \{\phi, X, \{a,b\}\}, \tau_2 = \{\phi, X, \{c\}\}, \sigma_1 = \{Y, \phi, \{a,b\}\}$ and $\sigma_2 = \{Y, \phi, \{a\}, \{a,b\}, \{a,b,c\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ - M^* - σ_1 -cts but it is not τ_1 - σ_1 - σ_1 -cts. Since for the σ_1 -c set $\{c,d\}, f^{-1}(\{c,d\}) = \{c,d\}$ which is not τ_1 -c set.

Example 2.10 Let $X=Y=\{a,b,c,d\}, \tau_1 = \{\phi, X, \{a\}, \{b,c\}, \{a,b,c\}\}, \tau_2 = \{\phi, X, \{a\}, \{b\}, \{a,c\}, \{a,b,d\}\}, \sigma_1 = \{Y, \phi, \{b\}, \{a,b\}\}$ and $\sigma_2 = \{Y, \phi, \{a\}, \{a,b\}, \{a,b,d\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ -a- σ_1 -cts but it is not $\tau_1\tau_2$ - δ - σ_1 -cts. Since for the σ_1 -c set $\{a,c,d\}, f^{-1}(\{a,c,d\}) = \{a,c,d\}$ which is not $\tau_1\tau_2$ - δ -c set.

Example 2.11 Let $X=Y=\{a,b,c,d\}, \tau_1$ and τ_2 are defined in Example 2.10, $\sigma_1 = \{Y, \phi, \{a,c\}\}$ and $\sigma_2 = \{Y, \phi, \{a\}, \{a,c\}, \{a,b,c\}\}$. Then the identity map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is a $\tau_1\tau_2$ - θs - σ_1 -cts but it is not $\tau_1\tau_2$ - M^* - σ_1 -cts. Since for the σ_1 -c set $\{b,d\}, f^{-1}(\{b,d\}) = \{b,d\}$ which is not $\tau_1\tau_2$ - M^* -c set.

Example 2.12 Let $X=Y=\{a,b,c,d\}$, τ_1 and τ_2 are defined in Example 2.10, $\sigma_1=\{Y,\phi,\{a,b\},\{a,c\}\}$ and $\sigma_2=\{Y,\phi,\{a\},\{a,b\},\{a,c\}\}$. Then the identity map $f:(X,\tau_1,\tau_2)\rightarrow(Y,\sigma_1,\sigma_2)$ is a $\tau_1\tau_2$ -e- σ_1 -cts but it is not $\tau_1\tau_2$ - δs - σ_1 -cts. Since for the σ_1 -c set $\{c,d\}$, $f^{-1}(\{c,d\})=\{c,d\}$ which is not $\tau_1\tau_2$ - δ -sc set.

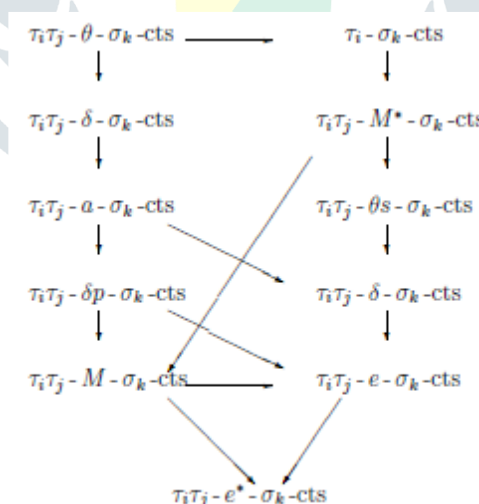
Example 2.13 Let $X=Y=\{a,b,c,d\}$, τ_1 and τ_2 are defined in Example 2.10, $\sigma_1=\{Y,\phi,\{b\},\{a,c\}\}$ and $\sigma_2=\{Y,\phi,\{a\},\{a,b\},\{a,c\}\}$. Then the identity map $f:(X,\tau_1,\tau_2)\rightarrow(Y,\sigma_1,\sigma_2)$ is a $\tau_1\tau_2$ -M- σ_1 -cts but it is not $\tau_1\tau_2$ - δp - σ_1 -cts. Since for the σ_1 -c set $\{a,c,d\}$, $f^{-1}(\{a,c,d\})=\{a,c,d\}$ which is not $\tau_1\tau_2$ - δ -pc set.

Example 2.14 Let $X=Y=\{a,b,c\}$, $\tau_1=\{\phi,X,\{a\},\{b\},\{a,b\}\}$, $\tau_2=\{\phi,X,\{a\},\{a,b\}\}$, $\sigma_1=\{Y,\phi,\{a,c\}\}$ and $\sigma_2=\{Y,\phi,\{a\},\{a,c\}\}$. Then the identity map $f:(X,\tau_1,\tau_2)\rightarrow(Y,\sigma_1,\sigma_2)$ is a $\tau_1\tau_2$ - δp - σ_1 -cts but it is not $\tau_1\tau_2$ -a- σ_1 -cts. Since for the σ_1 -c set $\{b,d\}$, $f^{-1}(\{b,d\})=\{b,d\}$ which is not $\tau_1\tau_2$ -a-c set.

Example 2.15 Let $X=Y=\{a,b,c\}$, τ_1 and τ_2 are defined in Example 2.14, $\sigma_1=\{Y,\phi,\{b,c\}\}$ and $\sigma_2=\{Y,\phi,\{b\},\{b,c\}\}$. Then the identity map $f:(X,\tau_1,\tau_2)\rightarrow(Y,\sigma_1,\sigma_2)$ is a

(1) $\tau_1\tau_2$ -e*- σ_1 -cts but it is not $\tau_1\tau_2$ -e- σ_1 -cts, since for the σ_1 -c set $\{a\}$, $f^{-1}(\{a\})=\{a\}$ which is not $\tau_1\tau_2$ -e-c set.

(2) $\tau_1\tau_2$ - δp - σ_1 -cts but it is not $\tau_1\tau_2$ -a- σ_1 -cts, since for the σ_1 -c set $\{a\}$, $f^{-1}(\{a\})=\{a\}$ which is not $\tau_1\tau_2$ -a-c set.



Note: $A \rightarrow B$ denotes A implies B , but not conversely.

Theorem 2.2 A map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\tau_i \tau_j - M^* - \sigma_k$ -cts. iff the inverse image of every σ_k -o set in Y is $\tau_i \tau_j - M^*$ -o in X .

Proof. Let G be a σ_k -o set in Y . Then G^c is σ_k -c set in Y . Since f is $\tau_i \tau_j - M^* - \sigma_k$ -cts, $f^{-1}(G^c)$ is $\tau_i \tau_j - M^*$ -c in X . That is $f^{-1}(G^c) = (f^{-1}(G))^c$ and so $f^{-1}(G)$ is $\tau_i \tau_j - M^*$ -o in (X, τ_1, τ_2) .

Conversely, let F be a σ_k -c set in Y . Then F^c is σ_k -p set in Y . By hypothesis, $f^{-1}(F^c)$ is $\tau_i \tau_j - M^*$ -o in X . That is $f^{-1}(F^c) = (f^{-1}(F))^c$ and so $f^{-1}(F)$ is $\tau_i \tau_j - M^*$ -c in (X, τ_1, τ_2) . Therefore f is $\tau_i \tau_j - M^* - \sigma_k$ -cts.

Theorem 2.3 If a map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\tau_i \tau_j - M^* - \sigma_k$ -cts, then $f(\tau_i \tau_j - M^* cl(A)) \subseteq \sigma_k cl(f(A))$ holds for every subset A of X .

Proof. Let A be any subset of X . Then $f(A) \subseteq \sigma_k cl(f(A))$ and $\sigma_k cl(f(A))$ is σ_k -c set in Y . Also $f^{-1}(f(A)) \subseteq f^{-1}(\sigma_k cl(f(A)))$. That is $A \subseteq f^{-1}(\sigma_k cl(f(A)))$. Since f is $\tau_i \tau_j - M^* - \sigma_k$ -cts, $f^{-1}(\sigma_k cl(f(A)))$ is $\tau_i \tau_j - M^*$ -c in (X, τ_1, τ_2) . By Theorem 2.7 in [13] $\tau_i \tau_j - M^* cl(A) \subseteq f^{-1}(\sigma_k cl(f(A)))$. Therefore $f(\tau_i \tau_j - M^* cl(A)) \subseteq f(f^{-1}(\sigma_k cl(f(A)))) \subseteq \sigma_k cl(f(A))$. Hence $f(\tau_i \tau_j - M^* cl(A)) \subseteq \sigma_k cl(f(A))$ for every subset A of (X, τ_1, τ_2) .

Converse of the above Theorem **Error! Reference source not found.** is not true as seen from the following Example.

Example 2.16 Let $X = \{a, b, c, d\}$, $\tau_1 = \{\phi, X, \{a\}, \{b\}, \{a, b\}\}$ and $\tau_2 = \{\phi, X, \{a\}, \{b, c\}, \{a, b, c\}\}$ and $Y = \{p, q\}$, $\sigma_1 = \{\phi, Y, \{p\}\}$ and $\sigma_2 = \{Y, \phi\}$. Then $\tau_2 \tau_1 - M^* = \{X, \phi, \{c\}, \{d\}, \{a, b\}, \{c, d\}, \{a, c\}, \{b, d\}, \{a, b, c\}, \{b, c, d\}, \{a, c, d\}, \{a, b, d\}\}$. Define a map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ by $f(a) = f(c) = f(d) = p$ and $f(b) = q$. Then $f((2,1) - M^* cl(A)) \subseteq \sigma_1 cl(f(A))$ for every subset A of X . But f is not $\tau_2 \tau_1 - M^* - \sigma_1$ -cts, since for the σ_1 -c set $\{q\}$, $f^{-1}(\{q\}) = \{b\}$ which is not $(2,1) - M^*$ -c set in (X, τ_1, τ_2) .

Theorem 2.4 If a map $f:(X, \tau_1, \tau_2) \rightarrow (Y, \sigma_1, \sigma_2)$ is $\tau_i \tau_j - M^* - \sigma_k$ -cts and $g:(Y, \sigma_1, \sigma_2) \rightarrow (Z, \eta_1, \eta_2)$ is $\eta_n - \sigma_k$ -cts, then $g \circ f$ is $\tau_i \tau_j - M^* - \eta_n$ -cts.

Proof. Let F be η_n -c set in (Z, η_1, η_2) . Since g is $\eta_n - \sigma_k$ -cts, $g^{-1}(F)$ is σ_k -c set in (Y, σ_1, σ_2) . Since f is $\tau_i \tau_j - M^* - \sigma_k$ -cts, $f^{-1}(g^{-1}(F)) = (g \circ f)^{-1}(F)$ is $\tau_i \tau_j - M^*$ -c set in (X, τ_1, τ_2) and hence $g \circ f$ is $\tau_i \tau_j - M^* - \eta_n$ -cts.

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