Advanced Video Indexing Scheme using Genetic Algorithm with Tagging

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Abstract: Multimedia provides an upscale content of knowledge and a large quantity of knowledge square measure obtainable within the field of video retrieval. To achieve the goal of indexing and retrieving video shots by their content still an issue under debate. By this paper, we tend to gift a unique approach video indexing and content-based set of descriptors for the classification of video shots into purposeful semantic classes which may then be used once browsing a video dataset. We tend to additionally add three normalized native HSV histograms, extracted from explicit key-frames we tend to choose with a straight forward nevertheless economical approach, as color descriptors. Our experimental implementation is tested on real-world video shots exploitation a categorization supported genetic approach and tags in image and video sequences. The results demonstrate that the planned option scan do high success rates not solely on narrow and specialized categories however additionally on additional generic ones.

Index Terms - Multimedia, indexing, classification, Multimedia, Genetic Algorithm, Histogram.

I. INTRODUCTION

The basic multimedia information is required for video indexing and retrieval of video from media from a large dataset. There have been drastic challenges faced in the field of multimedia, researcher concentrate in multimedia video retrieval from media or database to end-users. Among several multimedia resources, the video is a key component which comprises mainly of four parts. The initial one is that the powerful video provides the rich contents than that of text as well as images. The second is a huge amount of raw data in video retrieval field. Next splitting entire video retrieval process to scenes, shots, and frames. The last process is to segment the video into small units which include Shot Boundary Detection Key Frame Extraction, Scene segmentation and Audio Extraction. The segmented objects in each image frame which have been used in many applications, such as Object manipulation, Surveillance, Scene composition and Video Retrieval. In this paper, mainly focused on Information-Based Video Retrieval (IBVR) system which includes various processes with several algorithms for different techniques to extract feature in order to reduce the semantic gap. Initially, the video is segmented into shots for shot boundary detection, while the next process it to perform keyframe selection which is to select the keyframe for representing the shot using Euclidean Distance algorithm. After selecting the keyframe, feature extraction had been processed and stored into the feature vector. Generally, features are of spatial as well as temporal in nature. [11] A spatial feature includes color, shape, and edge. Similarly, temporal features are mainly classified into two, motion and the other is audio. Finally, [13][14] indexing process to be done with the help of clustering algorithm with B+ tree algorithm. Indexing is done by indexing the keyframes with the help of retrieving process, video retrieval process for similarity matching operations with the user query using Euclidean Distance

II. BRIEF LITERATURE SURVEY

In [1] during this paper, Chih-Chin Lai, and Ying-huan Chen projected that the text-based retrieval has some inconsistency issues, to alleviate the inconsistency downside, the image retrieval is applied consistent with the image contents. Such strategy is that the alleged content-based image retrieval (CBIR). The first goal of the CBIR system is to construct meaningful descriptions of physical attributes from pictures to facilitate economical and effective retrieval.

In [2] during this paper, M. Antonelli, S. G. Dellepiane, and M. Goccia projected that the text-based retrieval has some inconsistency issues, to alleviate the inconsistency problem; the image retrieval is applied consistently with the image contents. Such strategy is that the alleged the CBIR system is to construct meaningful descriptions of physical attributes from pictures to facilitate economical and effective retrieval.

In [3] Ja-Hwang Su, Wei-Jyun Huang, Philip S. Yu, represented a unique methodology during this paper. Navigation-Pattern-based Relevance Feedback (NPRF), to attain the high potency and effectiveness of CBIR in dealing with the large scale image knowledge. Regarding potency, the iterations of feedback square measure reduced considerably by mistreatment the navigation patterns discovered from the user question log. Regarding effectiveness, projected search algorithmic rule NPRF Search makes use of the discovered navigation patterns and three types of question refinement methods, question purpose Movement (QPM), question Reweighting (QR), and question enlargement (QEX), to converge the search house toward the user's intention effectively. By mistreatment NPRF methodology, original quality of image retrieval on RF will be achieved during a little variety of feedbacks. The experimental results reveal that NPRF out performs existing alternative ways significantly regarding exactness, coverage, and variety of feedbacks.

In [4] S.-B. Cho and J.-Y. Lee, propose a user-oriented CBIR system that uses the interactive genetic algorithmic rule (GA) (IGA) to infer that pictures within the databases would be of most interest to the user. Three visual options color, texture, and therefore the fringe of a picture square measure used in their approach.

In [5] [6] Arevalillo-Herrez et al. introduced a brand new hybrid approach to connectedness feedback CBIR. Their technique combines Associate in Nursing immunoglobulin A with Associate in Nursing extended the nearest neighbor approach to cut back the current gap between the high-level linguistics contents of pictures and therefore the data provided by their low-level descriptors.
PROBLEM STATEMENT
The design effectively and precisely video-based image retrieval system from an extensive image database using content-based image retrieval and advanced genetic algorithm based indexing scheme with tagging by providing a robust framework to increase the accuracy of image retrieval.

III. CHOICE OF THE TOPIC WITH REASONING
Video indexing is a relatively new science which means there are more unexplored areas to research, perhaps in contrast to traditional IR, which is well explored and harder to find possible improvements. Combining genetic algorithms with CBIR methods, there are some issues. Some of the issues related to CBIR:

1. Feature selection issue to describe the images better within the database.
2. Selection of proper data structure to store the feature vectors
3. The learning algorithms used to make the CBIR wiser
4. Participation of the users feedback to improve the searching result drawbacks
5. Need for more Resources like CPU time, memory, disk space, etc.
6. Determining the Semantic meaning of Objects is not possible. Results may contain False Hits.
8. A drawback associated with CBIR is the increased computational cost arising from tasks such as

V. METHODOLOGIES
A. Feature Extraction and Similarity Matching
There are three image features for extraction, which are a color histogram, edge, and texture. The color histogram is counted in HSV color space with H channel 32 bins, S channel 16 bins, and V channel 16 bins respectively. Therefore, a 64-dimension color feature vector is obtained for each image. The edge feature is extracted in gray color space. Firstly it converts the color images to grayscale and uses canny operators to get the edge of images. Then the edge images are divided into 256 regions, calculating the ratio of edge pixels in each region. This 256-dimension vector will be used as edge feature [9] [13]. Similarly, the texture feature extraction is performed on grayscale images. It divides the gray images into several non-overlapping regions by 48x48 pixels. Then 2D Gabor filter is applied for each region. Basically, the important of texture is related to the area. In other words, the texture covering more regions is considered more important. Thus in order to extract primary textures, we adopt K-means to cluster similar textures together and select several top representative textures as the texture feature of the image. For positive images and negative images, all three types of features are extracted as support vectors in SVM training. Then the un-browsed images will be classified by the trained preference classifier. With browsed images, these classified images are reordered and showed to the user for next feedback repetition [11] [12]. The system calculates the similarity between the query image and the database images according to those as mentioned earlier low-level visual features.

B. Color Histogram vs. Color auto-Correlogram
The color histogram is one of the well-known methods in content-based image retrieval [13]. It is efficient to compute and effective in search results. Most popular CBIR methods use color histograms as one of the features. For an m x n image I, the colors in that image are quantized to C1,C2,……,Ck. The color histogram \( H(I) = h1,h2,….hk \). Where \( hi \) describes the number of pixels in color \( C_i \). The color histogram also outlines the possibility of any pixel, an image I, that is in color \( C_i \).

\[ \Pr(P \in C_i) = \frac{hi}{m \times n} \]

The color histogram is easy to estimate. It only requires to go through the image once, so the computation complexity is O, and because the color is one of the most prominent perceptual features, in many cases the effect of using the histogram to searching and retrieving image is quite well. The weak point of the histogram approach is there is no any space information in color histogram. There are several techniques proposed to integrate spatial information with color histograms [13]. The “Color autocorrelogram” is one of these techniques. Consider the following question: pick any pixel \( P1 \) of color \( C_i \) in the image \( I \), at distance \( k \) away from \( p1 \) pick another pixel \( P2 \), what is the probability that \( P2 \) is also of color \( C_i \)? We define the auto-correlogram of the image \( I \) for color \( C_i \) with distance \( k \).

\[ c_{ij}^k = \Pr(|P1 - P2|) = k, P2 \in I_{ci} | P1 \in I_{ci} \]

So the color auto-correlogram shows how the spatial auto-correlation of color changes with distance [13].

Example: Consider the two images in Figure 1:

![Image1](image1.png) ![Image2](image2.png)

Figure 1. Sample Images

It is easy to know, the histogram of these two images are exactly same. We cannot tell these two images are different from each other by the histogram. However, the auto-correlogram will be different, as shown in Figure 2.
The auto-correlogram combines the color information and the space information. For each pixel in the image, the auto-correlogram classification needs to go through all the neighbors of that pixel. So the computation complexity is $O(kn^2)$.

C. IGA (INTERACTIVE GENETIC ALGORITHM):
Interactive Genetic Algorithm (IGA) [1] is a branch of evolutionary computation. The fundamental difference between IGA and GA is the creation of the fitness function, that is, the fitness is determined by the user's valuation and not by the predefined mathematical function. A user can interactively determine which members of the population will produce again, and IGA automatically makes the next generation of content based on the users' input. During repeated rounds of content creation and fitness assignment, IGA enables unique content to grow that suits the users choices. Based on this reason, IGA can be used to solve problems that are difficult or impossible to devise a computational fitness function [1]. Our system operates in four phases. Querying: The user provides a sample image as the query for the system. Similarity computation: The system computes the similarity between the query image and the database images according to the aforementioned low-level visual features. Retrieval: The system retrieves and displays a sequence of images ranked in decreasing order of similarity. As a consequence, the user can find relevant images by getting the top-ranked images first [1]. Incremental search: After obtaining some relevant image, the system provides an interactive mechanism via IGA, which lets the user evaluates the recovered images as more or less relevant to the query one, and the system then updates the relevance learning to include as many user-desired images as possible in the next retrieval result. The search process is repeated until the user is satisfied with the result or results cannot be further improved. When the IGA is applied to develop a content-based color image retrieval system, the following components should be considered: Solution representation: To apply GA to a given problem, one has to decide to find an appropriate genotype that the problem needs, i.e., the chromosome representation. In the proposed approach, a chromosome represents the considered various types of image features (i.e., color, texture, edge) in an image [9][10].

The system architecture contains four main modules.

VI. PROPOSED SYSTEM ARCHITECTURE

Module Description
A. Key Frame Extraction
In the proposed system video input is given and frame are extracted. The frames which have the best reflection are chosen for the content of the shot as keyframes [14] [15] [46] to demonstrate the shot concisely. As much as possible salient content of the shots must be contained by the extracted key frames and redundancy must be avoided. The characteristics of the keyframe extraction are color, shapes, edges, optical flow, temporal motion intensity, discrete cosine coefficient of MPEG, motion vectors [18], and derived features by the image variations because of the camera movement [19] [20]. The recent approach of keyframe extraction is classified into six portions as classified by Truong and Venkatesh [15]:

![Figure 2. Auto-correlogram of the sample images in fig 1.](image)
Composition analysis

Extraction of Feature

Indexing Based on Semantics                               Indexing Based on High Dimensionality

Similarity measures

1) Simplification of the curve based,
2) Reference frame based,
3) Sequential contrast-based,
4) Global comparison-based,
5) Event/object-based,
6) Clustering based.

The system is designed as the base of video retrieval and indexing, for the extraction of features with accordance to the video structural analysis. The visual features were the focus of the video indexing, and retrieval mainly consists of keyframes features, motions and objects and also considered features of the text, i.e., tags [32].

VIII. EXPERIMENTATION AND RESULT

A. Experimentation Result

Time Analysis for similarity matching is done based on the amount of time required for retrieving the video from the database and the percentage match of the query video with video files stored in the database. Fig. 4 used to shows the video length and retrieved time. Performance of the system is evaluated based on the precision and recall values. Table-I shows the how a given query video obtains much precision and recall.
In this segment, we tend to show the retrieval of experimental results on first coconut palm and coconut palm Scene datasets victimization. For each dataset, we tend to every which way sampled video pictures as queries and therefore the different as info pictures. Among the info pictures, were used as indexing video pictures. The second dataset is partitioned off into 10 classes, as well as African folks and village, beach, buildings, buses, dinosaurs, elephants, flowers, horses, mountains and glaciers, food, etc., and every class contains a hundred pictures. Partitioning of the info into linguistics classes is decided by the creators and reflects the human perception of image similarity.

Table - I Accuracy Measure Using Precision and Recall.

<table>
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<tr>
<th>Query Video Dataset (GB)</th>
<th>TP</th>
<th>FP</th>
<th>TN</th>
<th>FN</th>
<th>Matching %</th>
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</table>

IX. CONCLUSION AND FUTURE WORK

Advanced video indexing scheme using "Genetic Algorithm" with Tagging planned during this work both object and scene tag importance were measured from human sentence descriptions and used because of the ground truth based on a language process methodology. Three kinds of options (namely, semantic, visual and context) were known, and a structured model was planned for object and scene tag importance prediction. Model parameters were trained exploitation the genetic algorithm. it had been shown by experimental results that the indexing scheme using genetic algorithm with Tagging importance live and the planned tag importance prediction would considerably boost the performance of different retrieval tasks. A comprehensive work on content-based visual retrieval and indexing is given during this paper.

1) Detection of the shot boundary for analysis of video structure that could be a key feature in video indexing and retrieval systems, the symptoms area unit provided so that the holistic perspective can be seen,

2) the extraction of keyframes for scene division, at the side of the state of the art approaches is reviewed the trouble has been created to gift the analysis progress during this space in written record order so that it will gift a transparent explore for the progress of analysis during this space.
3) Feature extraction from frames area unit then seen from the machine learning and image process views to present the understanding of the prevailing and future trends.

4) Data processing for video and classification is additionally enclosed to present the insights of the approaches employed in video retrieval domain with their overall integration of the opposite elements of the method is given.

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REFERENCES


