

On Various Cyclic Contractions In Dislocated Quasi B-Metric Spaces

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Abstract : In this paper we prove some new fixed point results in dislocated quasi b-metric spaces. We introduce dqb-cyclic-Chatterjea type contraction, dqb-cyclic-Ciric type contraction and dqb-cyclic-Reich type contraction. We also provide proofs for fixed point results using aforesaid contraction conditions.

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I. INTRODUCTION

Fixed Point Theory has witnessed enormous amount of research in past few decades. As Banach[3], in 1922, laid the foundations of contraction principle and devised the mechanism for ensuring and finding a fixed point to be existent provided the self-map be continuous, he opened up a broad opportunity to generalizations and applications of the contraction principle. The principle may be stated as follows:

“If X is a complete metric space, then every contraction mapping from X to itself has a unique fixed point.”

In 1930, Wilson[10] introduced the concept of *quasi – metric*, which is merely suppressing one of the abiding axioms for being a complete metric i.e. $d(x, y) = d(y, x)$. Hitzler & Seda[6] introduced the concept of *dislocated metricspace* and generalized the Banach’s contraction principle. Ahmed, Hassan & Zeyada[12] introduced the concept of *dislocatedquasimetricspace*, which is an obvious generalization of *dislocatedmetricspace* and Banach’s contraction principle. In 1989, Bakhtin[2], introduced the concept of *b – metricspace* and generalized Banach’s contraction principle for *b – metricspace*. Chakkrid and Cholatis[8] introduced the concept of *dislocatedquasib – metricspace*.

In this paper we establish some new outcomes using Chatterjea contraction principle[4], Ciric contraction principle[5] and Rich contraction principle[9].

II. PRELIMINARIES

Definition 2.1[1]. Let X be a non empty set, let $d: X \times X \rightarrow [0, \infty)$ and let $k \in \mathbb{R}$. Then (X, d) is said to be *b – metricspace* if the following conditions are satisfied:

- (i) $d(x, y) = 0$ if and only if $x = y$, $\forall x, y \in X$.
- (ii) $d(x, y) = d(y, x)$, $\forall x, y \in X$.
- (iii) There exist a real number $k \geq 1$ such that $d(x, y) \leq k[d(x, z) + d(z, y)]$, $\forall x, y \in X$.

Definition 2.2[1]. Let X be a non empty set and let $d: X \times X \rightarrow \mathbb{R}$, then (X, d) is known as *dislocated metric* if the following conditions are met and $\forall x, y, z \in X$.

- (i) $d(x, y) \geq 0$, $\forall x, y \in X$.
- (ii) $d(x, y) = d(y, x)$, $\forall x, y \in X$.
- (iii) $d(x, y) = d(y, x) \Rightarrow x = y$, $\forall x, y \in X$.
- (iv) $d(x, y) \leq d(x, z) + d(z, y)$, $\forall x, y \in X$.

If d satisfies (i), (iii) and (iv) then d is called *dislocatedquasimetric* on X and the pair (X, d) is called *dislocatedquasimetricspace*.

Definition 2.3[1]. Let X be a non-empty set and let the mapping $d: X \times X \rightarrow [0, \infty)$. Let a constant $k \geq 1$. If following conditions are satisfied:

- (i) $d(x, y) = d(y, x) = 0$, $\forall x, y \in X$.
- (ii) $d(x, y) \leq k[d(x, z) + d(z, y)]$, $\forall x, y \in X$.

Then the pair (X, d) is called *dislocatedquasib – metricspace*.

Definition 2.4[1]. Let (X, d) be *dqb – metricspace*. A sequence $\langle x_n \rangle$ in X is called to be *dqb-converges* to $x \in X$ if

$$\lim_{n \rightarrow \infty} d(x_n, x) = 0 = \lim_{n \rightarrow \infty} d(x, x_n)$$

In this case x is called *dqb – limit* of $\langle x_n \rangle$ and is written as $x_n \rightarrow x$.

Definition 2.5[8]. Let (X, d) be a dqb-metric space. A sequence $\langle x_n \rangle$ in X is called as dqb-Cauchy sequence if

$$\lim_{n, m \rightarrow \infty} d(x_n, x_m) = 0 = \lim_{n \rightarrow \infty} d(x_m, x_n)$$

Proposition 2.6[8]. If (X, d) is a *dqb – metricspace* then a function $f: X \rightarrow X$ is continuous if and only if $x_n \rightarrow x \Rightarrow f x_n \rightarrow f x$.

Definition 2.7 Let A and B be nonempty closed subsets of a *metricspace* (X, d) and $S: A \cup B \rightarrow A \cup B$. S is called a cyclic map iff $S(A) \subseteq B$ and $S(B) \subseteq A$.

Definition 2.8 [7]. A cyclic map $S: A \cup B \rightarrow A \cup B$ is said to be a cyclic contraction if there exists $\alpha \in [0, 1)$ such that

$$d(Sx, Sy) \leq \alpha d(x, y)$$

$\forall x \in A$ and $y \in B$.

Definition 2.9 Let A and B be non empty closed subsets of a *completed q_b – metricspace* (X, d) . A cyclic mapping $S: A \cup B \rightarrow A \cup B$ is called a *q_b – cyclic Chatterjea type contraction* if there exist some $r \in (0, \frac{1}{2})$ such that

$$d(Sx, Sy) \leq r[d(x, Sy) + d(y, Sx)]$$

$\forall x \in A, y \in B$ with $k \geq 1$ and $kr \leq 1$.

Definition 2.10 Let A and B be non empty closed subsets of a *completed q_b – metricspace* (X, d) . A cyclic mapping $S: A \cup B \rightarrow A \cup B$ is called a *q_b – cyclic Ciric type contraction* if there exist some $r \in (0, 1)$ such that

$$d(Sx, Sy) \leq r \max[d(x, y), d(Sx, x), d(Sy, y)]$$

$\forall x \in A, y \in B$ with $k \geq 1$ and $kr \leq 1$.

Definition 2.11 Let A and B be non empty closed subsets of a *completed q_b – metricspace* (X, d) . A cyclic mapping $S: A \cup B \rightarrow A \cup B$ is called a *q_b – cyclic Reich type contraction* if there exist some a, b, c where $(a + b + c) < 1$, such that

$$d(Sx, Sy) \leq a \cdot d(x, Sx) + b \cdot d(y, Sy) + c \cdot d(x, y)$$

$\forall x \in A, y \in B$ with $k \geq 1$ and $k(a + b + c) \leq 1$.

III. MAIN RESULTS

Now, we prove *cyclic – Chatterjea type Contraction* in *dislocated quasi b – metric space*.

Theorem 3.1 Let A and B be nonempty closed subsets of a *complete dislocated quasi – b – metric space* (X, d) . Let cyclic mapping $S: A \cup B \rightarrow A \cup B$ satisfies the condition of a *q_b – cyclic – Chatterjea type Contraction*. Then S has a unique fixed point in $A \cap B$.

Proof: Let $x \in A$ (fix). Then, by the condition of the theorem,

$$\begin{aligned} d(S^2x, Sx) &= d(S(Sx), Sx) \\ d(S^2x, Sx) &\leq r[d(Sx, Sx) + d(x, S^2x)] \\ d(S^2x, Sx) &\leq r\alpha \end{aligned} \quad (1)$$

And

$$\begin{aligned} d(Sx, S^2x) &= d(Sx, S(Sx)) \\ d(Sx, S^2x) &\leq r[d(x, S^2x) + d(Sx, Sx)] \\ d(Sx, S^2x) &\leq r[d(Sx, Sx) + d(x, S^2x)] \\ d(Sx, S^2x) &\leq r\alpha \end{aligned} \quad (2)$$

Where $\alpha = (d(Sx, Sx) + d(x, S^2x))$

Now, from (1) and (2), we have, $d(S^3x, S^2x) \leq r^2\alpha$, and $d(S^2x, S^3x) \leq r^2\alpha$.

And in general $\forall n \in \mathbb{N}$, we get,

$$(S^{n+1}x, S^n x) \leq r^n \alpha$$

And

$$(S^n x, S^{n+1}x) \leq r^n \alpha$$

Let $n, m \in \mathbb{N}$ with $m > n$, by using the triangular inequality, we have

$$\begin{aligned} d(S^m x, S^n x) &\leq k^{m-n} d(S^m x, S^{m-1} x) + k^{m-n-1} d(S^{m-1} x, S^{m-2} x) + \dots + k(S^{n+1} x, S^n x) \\ &= (k^{m-n} r^{m-1} + k^{m-n-1} r^{m-2} + \dots + k^{m-n-2} r^{m-3} + \dots + k^2 r^{n+1} + kr^n) \alpha \\ &= ((kr)^{m-n} r^{n-1} + (kr)^{m-n-1} r^{n-1} + \dots + (kr)^{m-n-2} r^{n-1} + \dots + (kr)^2 r^{n-1} + (kr) r^{n-1}) \alpha \\ &\leq (r^{n-1} + r^{n-1} + r^{n-1} + \dots + r^{n-1} + r^{n-1}) \alpha \\ &= (r^{n-1})(m - n + 1) \alpha \\ d(S^m x, S^n x) &\leq (r^{n-1}) \beta \alpha \end{aligned}$$

With $\beta > 0$, as $n \rightarrow \infty$, we get $d(S^m x, S^n x) \rightarrow 0$.

In a similar way, let $m, n \in \mathbb{N}$, with $m > n$, by using triangular inequality, we have

$$d(S^n x, S^m x) \leq (r^{n-1}) \beta \alpha$$

With $\beta > 0$, as $n \rightarrow \infty$, we get $d(S^m x, S^n x) \rightarrow 0$. Therefore sequence $\langle S^n x \rangle$ is a Cauchy sequence that converges to some $u \in X$. As (X, d) is complete, sequence $\langle S^n x \rangle$ is in A and sequence $\langle S^{2n-1} x \rangle$ is in B in a way that we have both the sequences tend to same limit $u \in X$.

Since A and B are closed subsets of X and, $u \in A \cap B$, therefore $A \cap B \neq \emptyset$.

Now we will prove the existence of fixed point i.e. $Su = u$.

By the condition of the theorem we have

$$\begin{aligned} d(S^n x, Su) &= d(S(S^{n-1} x), Su) \\ d(S^n x, Su) &\leq r[d(S^{n-1} x, Su) + d(u, S^n x)] \end{aligned}$$

Now as $n \rightarrow \infty$, we get

$$\begin{aligned} d(u, Su) &\leq r[d(u, Su) + d(u, u)] \\ d(u, Su) &\leq rd(u, Su) \end{aligned}$$

Since $r \geq 1$, this inequality is only possible if $d(u, Su) = 0$.

Similarly from the condition of the theorem, we have

$$\begin{aligned} d(Su, S^n x) &= d(Su, S(S^{n-1}x)) \\ d(Su, S^n x) &\leq r[d(u, S^n x) + d(S^{n-1}x, Su)] \end{aligned}$$

Now as $n \rightarrow \infty$, we get

$$d(Su, u) \leq r[d(Su, u) + d(u, Su)]$$

From triangular inequality,

$$d(Su, u) \leq rd(Su, Su)$$

Which gives

$$d(Su, u) = 0.$$

Hence $d(u, Su) = d(Su, u) = 0$ and thus, $Su = u$. This implies that u is a fixed point of S .

Now we prove the uniqueness of the fixed point. Let $v \in X$ be another fixed point of S , such that $Sv = v$. Then by the condition of the theorem we lead to

$$\begin{aligned} d(u, v) &= d(Su, Sv) \\ d(u, v) &\leq r[d(u, Sv) + d(v, Su)] \\ d(u, v) &\leq r[d(u, v) + d(v, u)] \\ d(u, v) &= r d(u, u) \\ d(u, v) &= 0. \end{aligned}$$

Similarly,

$$\begin{aligned} d(v, u) &= d(Sv, Su) \\ d(v, u) &\leq r[d(v, Su) + d(u, Sv)] \\ d(v, u) &\leq r[d(v, u) + d(u, v)] \\ d(v, u) &= r d(v, v) \\ d(v, u) &= 0. \end{aligned}$$

$d(u, v) = d(v, u) = 0$. This implies that $u = v$ and u is the unique fixed point of S .

Now, we provide alternate proof for *cyclic – Ciric type Contraction in dislocated quasi b – metric space*. Wu et.al.[8] in 2016 proved *cyclic – Ciric type Contraction in dislocated quasi b – metric space*.

Theorem 3.2 Let A and B be nonempty closed subsets of a complete dislocated quasi – b – metric space (X, d) . Let cyclic mapping $S: A \cup B \rightarrow A \cup B$ satisfies the condition of a *dqb – cyclic – Ciric type Contraction*. Then S has a unique fixed point in $A \cap B$.

Proof: Let $x \in A(\text{fix})$. Then, by the condition of the theorem,

$$\begin{aligned} d(S^2x, Sx) &= d(S(Sx), Sx) \\ d(S^2x, Sx) &\leq r \max[d(Sx, x) + d(S^2x, Sx) + d(Sx, x)] \\ \text{Let } \alpha &= \max[d(S^2x, Sx) + d(Sx, x)] \\ d(S^2x, Sx) &\leq r \alpha \quad (3) \end{aligned}$$

And

$$\begin{aligned} d(Sx, S^2x) &= d(Sx, S(Sx)) \\ d(Sx, S^2x) &\leq r \max[d(x, Sx) + d(Sx, x) + d(S^2x, Sx)] \\ \text{Let } \beta &= \max[d(x, Sx) + d(Sx, x) + d(S^2x, Sx)] \\ d(Sx, S^2x) &\leq r \beta \quad (4) \end{aligned}$$

Let $\zeta = \max[\alpha, \beta]$

Now, from (3) and (4), we have, $d(S^3x, S^2x) \leq r^2\zeta$ and $d(S^2x, S^3x) \leq r^2\zeta$.

And more generally $\forall n \in \mathbb{N}$, we get,

$$(S^{n+1}x, S^n x) \leq r^n \zeta$$

And

$$(S^n x, S^{n+1}x) \leq r^n \zeta$$

Let $n, m \in \mathbb{N}$ with $m > n$, by using the triangular inequality, we have

$$\begin{aligned} d(S^m x, S^n x) &\leq k^{m-n} d(S^m x, S^{m-1} x) + k^{m-n-1} d(S^{m-1} x, S^{m-2} x) + \dots + k(S^{n+1} x, S^n x) \\ &= (k^{m-n} r^{m-1} + k^{m-n-1} r^{m-2} + \dots + k^{n+1} r^{n-1} + kr^n) \zeta \\ &= ((kr)^{m-n} r^{n-1} + (kr)^{m-n-1} r^{n-1} + \dots + (kr)^{n+1} r^{n-1} + (kr)^n r^{n-1}) \zeta \\ &\leq (r^{n-1} + r^{n-1} + r^{n-1} + \dots + r^{n-1} + r^{n-1}) \zeta \\ &= (r^{n-1})(m - n + 1) \zeta \\ d(S^m x, S^n x) &\leq (r^{n-1}) \lambda \zeta \end{aligned}$$

With $\lambda > 0$, as $n \rightarrow \infty$, we get $d(S^m x, S^n x) \rightarrow 0$.

In a similar way, let $m, n \in \mathbb{N}$, with $m > n$, by using triangular inequality, we have

$$d(S^n x, S^m x) \leq (r^{n-1}) \lambda \zeta$$

With $\lambda > 0$, as $n \rightarrow \infty$, we get $d(S^m x, S^n x) \rightarrow 0$. Therefore sequence $\langle S^n x \rangle$ is a Cauchy sequence that converges to some $u \in X$. As (X, d) is complete, sequence $\langle S^n x \rangle$ is in A and sequence $\langle S^{2n-1} x \rangle$ is in B in a way that we have both the sequences tend to same limit $u \in X$.

Since A and B are closed subsets of X and, $u \in A \cap B$, therefore $A \cap B \neq \emptyset$.

Now we will prove the existence of fixed point i.e. $Su = u$.

By the condition of the theorem we have

$$d(S^n x, Su) = d(S(S^{n-1}x), Su)$$

$$d(S^n x, Su) \leq r \max[d(S^{n-1}x, u) + d(S^n x, S^{n-1}x) + d(Su, u)]$$

Now as $n \rightarrow \infty$, we get

$$d(u, Su) \leq r \max[d(u, Su) + d(u, u) + d(Su, Su)]$$

$$d(u, Su) \leq rd(u, Su)$$

Since $r \geq 1$, this inequality is only possible if $d(u, Su) = 0$.

Similarly from the condition of the theorem, we have

$$d(Su, S^n x) = d(Su, S(S^{n-1}x))$$

$$d(Su, S^n x) \leq r \max[d(u, S^{n-1}x) + d(Su, u) + d(S^n x, S^{n-1}x)]$$

Now as $n \rightarrow \infty$, we get

$$d(Su, u) \leq r \max[d(u, u) + d(Su, Su) + d(u, u)]$$

$$d(Su, u) = 0.$$

Which gives

Hence $d(u, Su) = d(Su, u) = 0$ and thus, $Su = u$. This implies that u is a fixed point of S .

Now we prove the uniqueness of the fixed point. Let $v \in X$ be another fixed point of S , such that $Sv = v$. Then by the condition of the theorem we lead to

$$d(u, v) = d(Su, Sv)$$

$$d(u, v) \leq r \max[d(u, v) + d(Su, u) + d(Sv, v)]$$

$$d(u, v) \leq r \max[d(u, v) + d(u, u) + d(v, v)]$$

$$d(u, v) \leq r[d(u, v)]$$

$$d(u, v) = 0.$$

Similarly,

$$d(v, u) = d(Sv, Su)$$

$$d(v, u) \leq r \max[d(v, u) + d(Sv, v) + d(Su, u)]$$

$$d(v, u) \leq r \max[d(v, u) + d(v, v) + d(u, u)]$$

$$d(v, u) \leq r[d(v, u)]$$

$$d(v, u) = 0.$$

$d(u, v) = d(v, u) = 0$. This implies that $u = v$ and u is the unique fixed point of S .

Now, we prove *cyclic – Reich type Contraction in dislocated quasi b – metric space*.

Theorem 3.3 Let A and B be nonempty closed subsets of a *complete dislocated quasi – b – metric space* (X, d) . Let cyclic mapping $S: A \cup B \rightarrow A \cup B$ satisfies the condition of a *dqb – cyclic – Reich type Contraction*. Then S has a unique fixed point in $A \cap B$.

Proof: Let x be some arbitrary in X . We define a sequence $\langle x_n \rangle$ in X such that $x_1 = S(x_0)$, $x_2 = S(x_1)$... in general $S(x_{2n}) = x_{2n+1}$, $S(x_{2n+1}) = x_{2n+2}$ for $n = 0, 1, 2, 3$... Then, by the condition of the theorem,

$$d(x_1, x_2) = d(Sx_0, Sx_1)$$

$$d(x_1, x_2) \leq a \cdot d(x_0, Sx_0) + b \cdot d(x_1, Sx_1) + c \cdot d(x_0, x_1)$$

$$d(x_1, x_2) \leq a \cdot d(x_0, x_1) + b \cdot d(x_1, x_2) + c \cdot d(x_0, x_1)$$

$$d(x_1, x_2) \leq (a + c)d(x_0, x_1) + b \cdot d(x_1, x_2)$$

$$d(x_1, x_2) - b \cdot d(x_1, x_2) \leq (a + c)d(x_0, x_1)$$

$$(1 - b)d(x_1, x_2) \leq (a + c)d(x_0, x_1)$$

$$d(x_1, x_2) \leq \left(\frac{a + c}{1 - b}\right) d(x_0, x_1)$$

In a similar way we have, $d(x_2, x_3) \leq \left(\frac{a + c}{1 - b}\right) d(x_1, x_2)$

or, $d(x_2, x_3) \leq \left(\frac{a + c}{1 - b}\right)^2 d(x_0, x_1)$

And continuing like this we have, $d(x_n, x_{n+1}) \leq \left(\frac{a + c}{1 - b}\right)^n d(x_0, x_1)$

$$d(x_{n+1}, x_{n+2}) \leq \left(\frac{a + c}{1 - b}\right)^{n+1} d(x_0, x_1)$$

Now as $n \rightarrow \infty$, $\left(\frac{a + c}{1 - b}\right)^{n+1} d(x_0, x_1) \rightarrow 0$. This, therefore, suggests that the sequence $\{x_n\}$ is a *Cauchy Sequence* in X . Thus, there is a point $u \in X$ such that $x_n \rightarrow u$. Therefore we have, $Su = u$. Now we prove the uniqueness of the fixed point. Let $v \in X$ be another fixed point of S , such that $Sv = v$. Then by the condition of the theorem we have

$$d(u, v) = d(Su, Sv)$$

$$d(u, v) \leq a \cdot d(u, Su) + b \cdot d(v, Sv) + c \cdot d(u, v)$$

$$d(u, v) \leq a \cdot d(u, u) + b \cdot d(v, v) + c \cdot d(u, v)$$

$$d(u, v) \leq c \cdot d(u, v)$$

$$d(u, v) = 0.$$

Similarly,

$$d(v, u) = d(Sv, Su)$$

$$d(v, u) \leq a \cdot d(v, Sv) + b \cdot d(u, Su) + c \cdot d(v, u)$$

$$\begin{aligned}d(v, u) &\leq a. d(v, v) + b. d(u, u) + c. d(v, u) \\d(v, u) &\leq c. d(v, u) \\d(v, u) &= 0.\end{aligned}$$

$d(u, v) = d(v, u) = 0$. This implies that $u = v$ and u is the unique fixed point of S .

IV. CONCLUSION

We presented some new results and provided alternate proof for fixed point result in *dislocated quasi b-metric space* using *dqb-cyclic Ciric type contraction*.

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