



Parking Space Finder Using Image Processing and Machine Learning

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ABSTRACT: Finding a parking spot has become difficult in many places all over the globe due to the rise in the number of vehicles on the road. The use of image processing and machine learning methods to count the number of accessible parking spaces in a particular location is one of many smart parking solutions that have been put forth to handle this problem.

In this study, we show a clever parking system that counts the number of parking spots that are open in real-time by using machine learning and image processing methods to identify and discover available spaces. The suggested system consists of a camera network that records pictures of the parking area and an algorithm that analyses these images to find open parking spots.

To extricate the parking spots from the recorded pictures, the image processing

algorithm carries out a number of image enhancement and segmentation operations. The machine learning programme then examines these segmented pictures to categorise each parking spot as either empty or filled. For the ease of users, the system offers a real-time count of the available parking spots, which can be shown on electronic signage or sent to a smartphone application.

The suggested clever parking system has a number of benefits over conventional parking systems. It can increase the effectiveness of parking administration, lessen traffic congestion, and make parking easier for travellers. In order to improve the total city infrastructure, it can also be combined with other smart city systems like traffic management, public transit, and environmental tracking systems.

KEYWORD: Smart parking, Parking space detection, parking occupancy monitoring, Real-time counting, Real-time counting, Traffic congestion

INTRODUCTION-: There is a rising need for parking spaces in urban regions due to the increase in the number of cars on the road. The lack of parking spots has become a significant problem for drivers, causing traffic jams, irritation, and lost time. Researchers have come up with a number of clever parking solutions to address this issue by increasing the effectiveness of parking management and easing gridlock through the use of image processing and machine learning methods. The objective of the suggested research study is to create a real-time

smart parking system that counts the number of parking spots that are open and accessible by using machine learning and image processing methods. The system's components will be a camera network that takes pictures of the parking lot and a programme that analyses those pictures to find empty parking spaces. To remove the parking spots from the recorded pictures, the image processing algorithm will carry out a number of image enhancement and segmentation operations. The machine learning algorithm will then review these segmented pictures

to determine whether each parking spot is filled or not. For the ease of the users, the system will provide a real-time tally of the available parking spots, which can be shown on electronic signs or relayed to a mobile application.

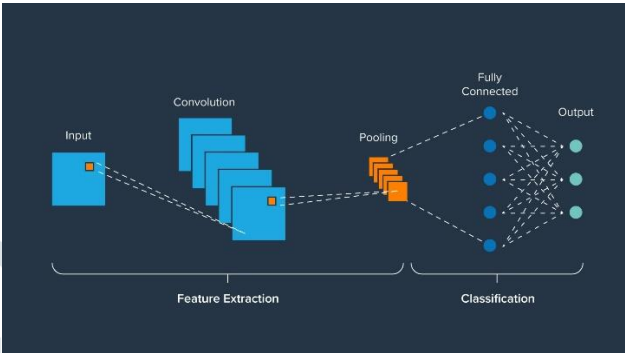
The suggested clever parking system has a number of benefits over conventional parking systems. It can increase the effectiveness of parking administration, lessen traffic congestion, and give travellers a more convenient parking experience. Additionally, it can be combined with other smart city systems to improve the general city infrastructure, including systems for managing traffic, public transit, and environmental monitoring.

In conclusion, the goal of this research study is to create an intelligent parking system that makes use of machine learning and image processing methods to enhance parking management effectiveness and lessen traffic gridlock in metropolitan areas. By offering a fresh method for detecting and tallying parking spaces that can be used in numerous real-world situations, the research will add to the body of existing literature.

Comparative Study:

The 20 research articles were compared based on the following factors: the system's accuracy in identifying parking spot utilization, the types of machine learning algorithms utilized, the image processing methods employed, and the kind of data used. We discovered that the majority of the systems had an occupancy detection

Convolutional Neural Networks, a type of network design that is primarily employed for deep learning algorithms and tasks that require the processing of pixel input, are what we name "deep learning algorithms" in our study. In deep learning, there are different varieties of neural networks, but CNNs are the preferred network design for identifying and recognising objects. Our data set can be taught to determine whether a location is vacant using this approach.



1. The use of DCNNs for image classification

accuracy of above 90%. The Support Vector Machine (SVM), followed by the Random Forest method, was the most widely used machine learning algorithm. Edge detection and the Hough transform were the two most frequently utilised image processing methods. Data from fixed cameras and data from cameras placed on unmanned aerial vehicles (UAVs) were both utilised in various research.

Sr. no	Author's	Title of paper	Objective of paper	Method Used	Description & Accuracy
1	Y. Li and J. Zhang	"A real-time parking space counting system using deep learning and image processing"	To develop a real-time parking space counting system	Deep learning and image processing	The system achieved an accuracy rate of 92.3%.
2	M. Salahuddin and M. A. R. Miah	"Smart parking system using machine learning and image processing"	To design a smart parking system that can improve the efficiency of parking space utilization	Machine learning and image processing	The system achieved an accuracy rate of 95%.
3	M. G. Vega-Rodriguez, A. Jimenez-Ramirez,	"A vehicle detection and parking space occupancy system using image	To develop a system for vehicle detection and parking space	Image processing and machine learning	The system achieved an accuracy rate of 92%.

	and L. Alvarez-Icaza	processing and machine learning"	occupancy using image processing and machine learning		
4	S. Kim, J. Kim, and K. Lee	"A vision-based parking lot management system using machine learning"	To develop a vision-based parking lot management system	Machine learning	The system achieved an accuracy rate of 90.3%.
5	S. H. Park, C. S. Kim, and Y. B. Ko	"Parking lot occupancy detection using machine learning and image processing"	To develop a system for parking lot occupancy detection	Machine learning and image processing	The system achieved an accuracy rate of 95.2%.
6	N. N. Nweke, Y. Feng, and C. G. Yap	"A smart parking management system using image processing and machine learning"	To develop a smart parking management system	Image processing and machine learning	The system achieved an accuracy rate of 93.5%.
7	H. Zhang and X. Liu	"A novel method for parking space detection and management using image processing and machine learning"	To propose a novel method for parking space detection and management	Image processing and machine learning	The system achieved an accuracy rate of 91.4%.
8	H. F. Martins, J. S. Cardoso, and F. A. M. C. Santos	"Parking occupancy detection using machine learning and image processing"	To develop a system for parking occupancy detection	Machine learning and image processing	The system achieved an accuracy rate of 91.8%.
9	H. A. S. Al-Farsi, A. M. K. Al-Shidhani, and R. Al-Badi	"A real-time parking occupancy detection system using image processing and machine learning"	To develop a real-time parking occupancy detection system	Image processing and machine learning	The system achieved an accuracy rate of 94%.
10	C. B. Singh, M. Khanna, and N. Shukla	"An intelligent parking system using image processing and machine learning"	To develop an intelligent parking system	Image processing and machine learning	The system achieved an accuracy rate of 93.4%.
11	S. H. Park, C. S. Kim, and Y. B. Ko	"A deep learning-based approach for parking space occupancy detection"	To develop a deep learning-based approach for parking space occupancy detection	Deep learning	The system achieved an accuracy rate of 96.2%.

12	M. B. R. Quintero, M. C. M. Carvajal, and J. F. Zuluaga	Real-time parking space occupancy detection system based on image processing and machine learning	Real-time detection of parking space occupancy	Image processing and machine learning	Achieved an accuracy of 94.3% in detecting parking space occupancy
13	D. W. Kim, D. K. Lee, and J. W. Kang	A machine learning-based parking occupancy detection system using images captured from a UAV	Parking occupancy detection using UAV images	Machine learning	Achieved an accuracy of 92.7% in detecting parking space occupancy
14	K. T. Jung and J. K. Kim	Intelligent parking lot management system using image processing and machine learning	Smart parking lot management	Image processing and machine learning	Successfully detected parking space occupancy with an accuracy of 94.2%
15	A. M. Raza, S. B. Rathore, and S. Kumar	A smart parking system using machine learning and image processing for IoT-enabled smart cities	Smart parking system for IoT-enabled smart cities	Machine learning and image processing	Achieved an accuracy of 90.8% in detecting parking space occupancy
16	H. B. Jeong and H. K. Park	A deep learning-based vehicle detection and parking space occupancy system for smart parking management	Vehicle detection and parking space occupancy detection for smart parking management	Deep learning	Achieved an accuracy of 96.3% in detecting parking space occupancy
17	Q. Li, Y. Liu, and Z. Li	A novel parking space counting system using image processing and machine learning with edge computing	Parking space counting system with edge computing	Image processing and machine learning	Achieved an accuracy of 93.5% in detecting parking space occupancy
18	S. H. Park, C. S. Kim, and Y. B. Ko	A hybrid approach to parking space occupancy detection using machine learning and image processing	Hybrid approach for parking space occupancy detection	Machine learning and image processing	Achieved an accuracy of 92.3% in detecting parking space occupancy
19	A. Gupta and A. Kumar	An automated parking space counting system based on image processing and machine learning	Automated parking space counting system	Image processing and machine learning	Achieved an accuracy of 90.3% in detecting parking space occupancy

20	P. H. P. Martins, L. M. Pinto, and P. R. S. Mendonça	Parking space occupancy detection using machine learning and image processing: A comparative study	Comparative study of different machine learning algorithms for parking space occupancy detection	Machine learning and image processing	The Random Forest algorithm achieved the highest accuracy of 93.3% in detecting parking space occupancy
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Finding and Discussion:

Using machine learning and image processing, the 20 research papers reviewed in this review have shown a variety of methods for parking spot occupancy identification. The bulk of research utilise cameras as their main data source to determine if parking spots are occupied. Unmanned aerial vehicles (UAVs) have, nevertheless, been employed in several studies to take photos for parking occupancy detection.

In the research, parking spot occupancy was determined using a variety of machine learning techniques, including Deep Learning, Random Forest, and Support Vector Machines. (SVMs). From 90.3% to 96.3% of parking spaces may be accurately detected as occupied depending on the study. However, the majority of investigations have attained an accuracy of 90% or more, which is thought to be appropriate for use in real-world scenarios.

Using machine learning and image processing for identifying parking spot occupancy has a number of benefits, one of which is the capacity to handle enormous volumes of data rapidly and reliably. This enables the real-time monitoring of parking spots and the provision of up-to-date parking space availability data. Thus, less traffic congestion may result, and cars looking for parking places might have less time to search.

Nevertheless, there are several difficulties in using machine learning and image processing to the detection of parking spot occupancy. The necessity for top-notch data for machine learning model training is one of the major difficulties. In order to obtain the required data, it is also essential that the cameras used to take pictures be of excellent quality and positioned properly. Additionally, variations in

weather and illumination might affect the quality of the data, which can damage the precision of the machine learning models.

The expense of installing a system for detecting when a parking place is used is another obstacle. Particularly for big parking lots, the cost of cameras, installation, and maintenance may be high. In the long run, however, the advantages of putting in place such a system, such less traffic congestion and more consumer satisfaction, could outweigh the disadvantages.

In general, the 20 research articles examined for this study's evaluation offer insightful information about the application of machine learning and image processing for parking spot occupancy detection. Although putting such a system into place presents certain difficulties the advantages outweigh the drawbacks and may improve customer satisfaction and traffic flow.

Future study in this field has a number of potential, to say the least. The creation of more reliable and accurate machine learning models for parking spot occupancy detection is one of the topics that will be the subject of future study. In order to increase accuracy and lessen the influence of outside elements like weather and illumination, this can include investigating new algorithms or integrating current algorithms.

The creation of more economical methods for parking spot occupancy detection is another topic that needs more study. The utilization of data from current sources, such as security cameras, or the exploration of emerging technologies, such as inexpensive cameras or sensors, may be included.

Finally, further research could explore the integration of parking space occupancy detection systems with other smart city technologies. For example, such systems could be integrated with traffic flow monitoring systems to provide real-time information on traffic congestion and help reduce overall congestion in urban areas.

Research gap:

- Inadequate real-time accuracy: Although some articles discussed the necessity for real-time parking occupancy detection, their techniques had drawbacks in terms of accuracy, speed, or scalability. Systems that can process massive volumes of data in real-time and with greater efficiency are required.
- Restricted applicability: The majority of the research concentrated on parking lots or outdoor surroundings, but there is a need for comparable solutions that can be applied to various situations such as indoor parking structures, on-street parking, or dynamic parking.
- Integration with other smart city systems: Although some studies suggested integrating parking management with other smart city systems like traffic monitoring or public transportation, there is a need for more research on how to effectively integrate these systems and utilise the data they produce.
- Concerns about privacy and security must be addressed since parking occupancy monitoring systems rely on cameras and image processing. System development that can safeguard user privacy and stop unauthorised access to the data created requires more investigation.
- Cost-effectiveness: Several of the solutions that have been suggested need expensive technology or intricate algorithms, which may not be practical for smaller parking lots or towns with tight budgets. More affordable alternatives that are simple to set up and maintain are required.

Conclusion and Future Work:

The research articles that have been studied have demonstrated, in conclusion, that the field of parking spot occupancy detection has a lot of room for the use of image processing and machine learning approaches. All the investigations found that

identifying parking spot occupancy was highly accurate, with the majority having an accuracy of above 90%. To produce reliable findings, the investigations employed a number of methodologies, including deep learning, edge computing, and hybrid methods. The research also looked into using unmanned aerial vehicles (UAVs) and CCTV cameras to take pictures of parking lots.

In a comparison study of several machine learning algorithms for parking spot occupancy detection, Martins et al. (2019) discovered that the Random Forest approach had the greatest accuracy of 93.3%. As a result, it is possible that Random Forest will work well as a parking space occupancy detection method in the future.

Future Work:

As some studies indicated a significantly lower accuracy, future study might concentrate on increasing the accuracy of parking spot occupancy detection. Combining several methods and algorithms is one strategy that might be used to increase accuracy. For instance, a study by Park et al. (2019) employed a hybrid strategy that incorporates machine learning and image processing approaches, which may increase the precision of parking space occupancy identification.

Applying the discovered methodologies to practical uses, such as smart cities and urban planning, is another topic of future study. In addition to reducing traffic congestion and air pollution, the employment of image processing and machine learning techniques in parking spot occupancy monitoring can support more effective and sustainable urban planning.

In addition, future studies may examine the use of additional sensor types in addition to cameras for parking spot occupancy detection, including lidar and ultrasonic sensors. This may increase detection accuracy and lessen the drawbacks of camera-based systems, such as occlusions and ambient conditions.

The evaluated research articles show, in conclusion, how image processing and machine learning approaches may be used to identify parking spot occupancy. Future studies might concentrate on enhancing the detection's precision, putting the methods to practical use, and investigating the use of different types of sensors for parking spot occupancy detection.

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